

SED1633

LOW-POWER 100-BIT LCD COMMON DRIVER

■ DESCRIPTION

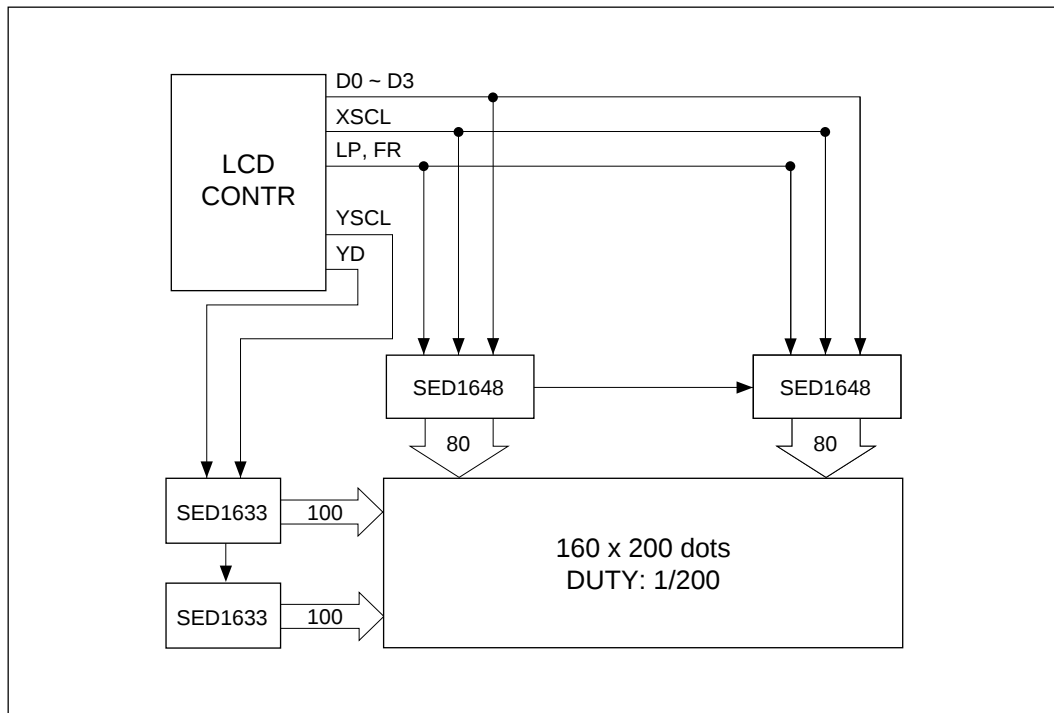
The SED1633 is a 100-output dot matrix LCD common (row) driver for driving high-capacity LCD panels at duty cycles higher than 1/64 (up to 1/300). The LSI has a wide range of LCD driving voltages, and has its maximum drive voltage, VO, isolated from VDD for flexibility of bias voltage generation.

The SED1633 is used in conjunction with the SED1648 (80-output segment driver) or the SED1600 (80-bit segment driver) to drive a large-capacity dot matrix LCD panel).

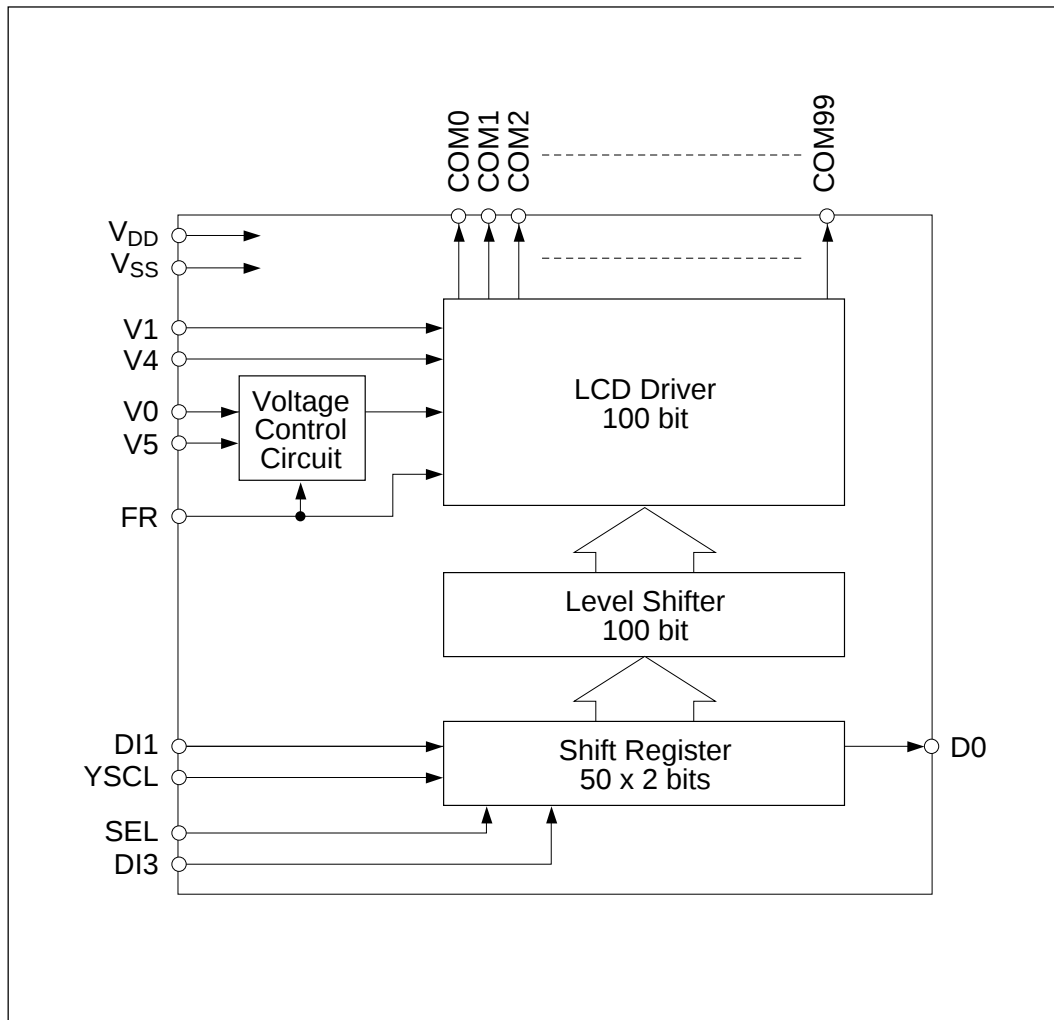
■ FEATURES

- Low-power CMOS technology
- 100-bit (50 × 2 structure) common (row) driver
- Duty cycle 1/64 to 1/300
- Low output impedance 500Ω typ (V1, V4 level)
700Ω typ (VO, V5 level)
- Duty cycle 1/100 to 1/300
- Ability to adjust offset bias of the LCD relative to VDD
- Non-biased display off function
- Pin selection of the output shift direction
- LCD voltage -8 to -28V
- Supply voltage 2.7 to 5.5V
- Package Al pad (D1A)
Au bump (D1B)

■ SYSTEM BLOCK DIAGRAM



■ BLOCK DIAGRAM



■ BLOCK DESCRIPTION

● Shift Register

This is a bidirectional shift register for common data transmission.

● Shift Direction

SED1633	COM 0 → COM 99	
SED1634	COM 99 → COM 0	Reference

● Level Shifter

This is a level interface circuit for shifting the signal voltage from the logic system level to the LCD driver system level.

● LCD Drivers and Voltage Controller Circuit

Outputs the LCD driver voltage.

The relationships between the content of the shift register, the alternating signal FR, and the common output voltage are as shown in the table below:

Contents of Shift Register	FR	COM Output Voltage	
H	H	V5	Select level
	L	V0	
L	H	V1	Non-select level
	L	V4	

■ PIN DESCRIPTION

Pin Name	I/O	Function	No. of Pins
COM0-COM99	O	LCD driver common (row) output Changes on the falling edge of the YSCL signal.	100
DI1, DI3	I	Serial data input for the 100 bit shift register. DI3 is the intermediate shift input. (When DI3 is unused, tie it to V _{DD} or V _{SS} .)	2
YSCL	I	Serial data shift clock input. Scanning data is shifted at the falling edge.	1
FR	I	LCD driver output AC signal input	1
V _{DD} , V _{SS}	Power	Power source for logic. V _{DD} : 0V (GND). V _{SS} : -5.0V	2
V0, V1, V4, V5	Power	Power source for LCD driver. V5: -12 to -28 V V _{DD} ≥ V0 ≥ V1 > V4 ≥ V5	4
SEL	I	Shift Register Operating Configuration Selection:	
		SEL	Shift Register Configuration
		H	50 × 2
		L	100 × 1
DO	O	Shift Register Operating Configuration Selection:	1
		DI3	
		Input	
		H/L	
DO	O	Shift register data output.	1
		The output changes with the falling edge of the YSCL signal.	

Total: 112

■ ELECTRICAL CHARACTERISTICS

● Absolute Maximum Ratings

Parameter	Symbol	Condition	Unit
Power voltage (1)	V _{SS}	−7.0 to +0.3	V
Power voltage (2)	V ₅	−30.0 to +0.3	V
Power voltage (3)	V ₀ , V ₁ , V ₄	V ₅ − 0.3 to + 0.3	V
Input voltage	V _I	V _{SS} − 0.3 to + 0.3	V
Output voltage	V _O	V _{SS} − 0.3 to + 0.3	V
Output current (1)	I _O	20	mA
Output current (2)	I _{OCOM}	20	mA
Operating temperature	T _{opr}	−40 to +85	°C
Storage temperature	T _{stg}	−65 to +150	°C

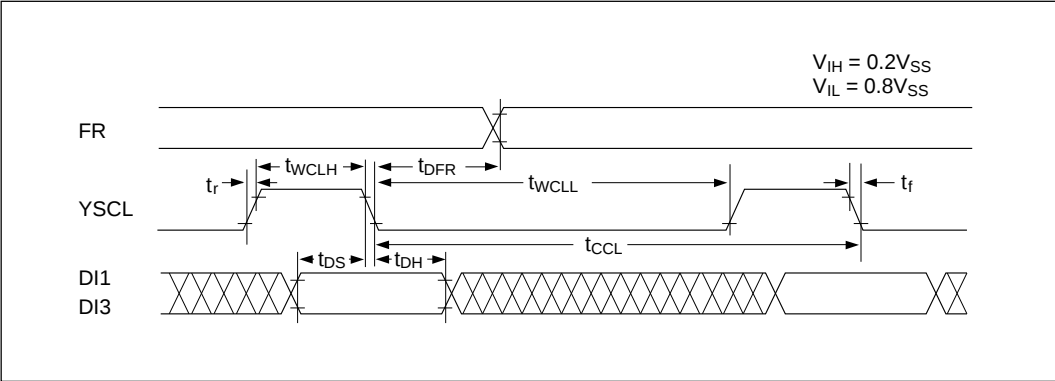
- Notes:**
- *1. The voltages are all relative to V_{DD} = 0V.
 - *2. Ensure that the relationship between V₀, V₁, and V₄ is always as follows: V_{DD} ≥ V₀ ≥ V₁ ≥ V₄ ≥ V₅.
 - *3. The LSI may be permanently damaged if the logic system power is floating or V_{SS} is less than or equal to −2.6V when power is applied to the LC drive circuit system. Special caution must be paid to the power sequences when turning the power on and off.

● DC Electrical Characteristics

Unless otherwise specified, $V_{DD} = V_0 = 0V$,
 $V_{SS} = -5.0V \pm 10\%$, $T_a = -40$ to $85^\circ C$

Parameter	Symbol	Conditions	Applicable Pins	Min	Typ	Max	Unit
Power voltage (1)	V_{SS}		V_{SS}	-5.5	-5.0	-2.7	V
Recommended operating voltage	V_5		V_5	-28.0	—	-12.0	V
Possible operating voltage	V_5	Function	V_5	—	—	-8.0	V
Power voltage (2)	V_0	Recommended value	V_0	-2.5	—	0	V
Power voltage (3)	V_1	Recommended value	V_1	$2/9 \times V_5$	—	V_{DD}	V
Power voltage (4)	V_4		V_4	V_5	—	$7/9 \times V_5$	V
High-level input voltage	V_{IH}	$V_{SS} = -2.7$ to $-5.5V$	DI1, YSCL, SEL, DI3, FR	$0.2 \times V_{SS}$	—	—	V
Low-level input voltage	V_{IL}			—	—	$0.8 \times V_{SS}$	V
High-level output voltage	V_{OH}	$I_{OH} = -0.3mA$ $I_{OH} = -0.2mA$ ($V_{SS} = -2.7$ to $-4.5V$)	DO	-0.4	—	—	V
Low-level output voltage	V_{OL}	$I_{OL} = 0.3mA$ $I_{OL} = 0.2mA$ ($V_{SS} = -2.7$ to $-4.5V$)		—	—	$V_{SS} + 0.4$	V
Input leakage current	I_{LI}	$V_{SS} \leq V_{IN} \leq 0V$	YSCL, SEL, DI3, FR	—	—	2.0	μA
I/O leakage current	I_{LO}	$V_{SS} \leq V_{IN} \leq 0V$	DI1, DO	—	—	5.0	μA
Static current	I_{DDS}	$V_5 = -12.0$ to $-28.0V$ $V_{IH} = V_{DD}$, $V_{IL} = V_{SS}$	V_{DD}	—	—	25	μA
Output resistance	R_{COM}	$\Delta V_{ON} = 0.5V$ $V_5 = -20.0V$ $V_5 = -14.0V$ *($V_5 = -8.0V$) $V_5 = -20.0V$ $V_5 = -14.0V$ *($V_5 = -8.0V$)	When outputting the V1, V4 levels COM0 - COM99 When outputting the V0, V5 levels *Reference value	—	0.40 0.50 (0.60)	0.80 1.00 (1.20)	$K\Omega$
Average operating current consumption (1)	I_{SS1}	$V_{SS} = -5.0V$, $V_{IH} = V_{DD}$, $V_{IL} = V_{SS}$, $f_{YSCL} = 12KHz$, Frame frequency = 60KHz, Input data: 1/200, "H" is without load on each duty cycle $V_{SS} = -3.0V$; other parameters are identical	V_{SS}	—	7	15	μA
Average operating current consumption (2)	I_{SS2}	$V_{SS} = -5.0V$, $V_1 = -2.0V$, $V_4 = -18.0V$, $V_5 = -20.0V$; other parameters are the same as for I_{SS1}	V_5	—	7	15	μA
Input terminal capacitance	C_i	$T_a = 25^\circ C$	YSCL, SEL, DI3, FR	—	—	8	pF
I/O terminal capacitance	$C_{I/O}$		DI1, DO	—	—	15	pF

- AC Characteristics
 - Input Timing Characteristics



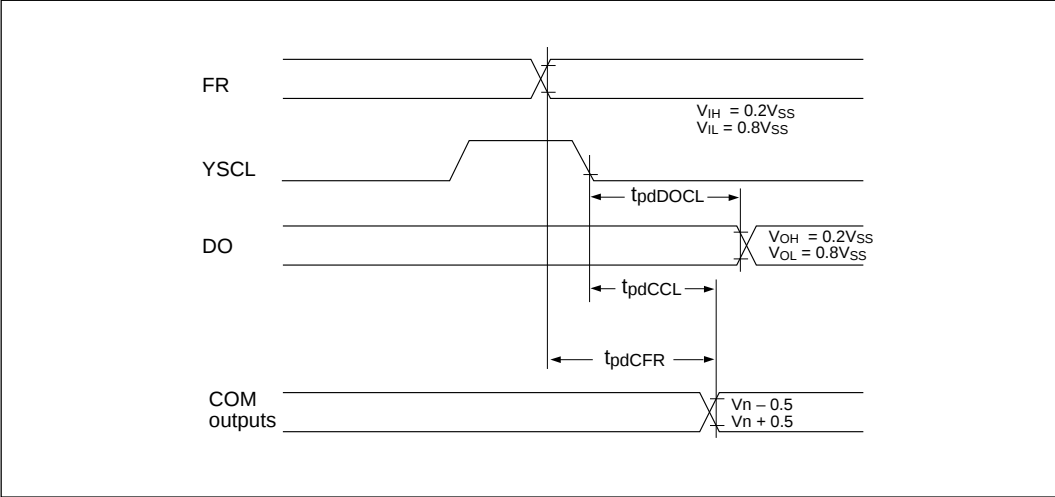
$V_{SS} = -5.0 \pm 10\%$, $T_a = -40$ to 85°C

Parameter	Symbol	Conditions	Min	Max	Unit
Input signal rise time	t_r		—	50	ns
Input signal fall time	t_f		—	50	ns
YSCL frequency	t_{CCL}		500	—	ns
YSCL high-level pulse width	t_{wCLH}		70	—	ns
YSCL low-level pulse width	t_{wCLL}		330	—	ns
Data setup time	t_{DS}		100	—	ns
Data hold time	t_{DH}		10	—	ns
Allowable FR delay	t_{DFR}		−500	500	ns

$V_{SS} = -2.7$ to -4.5V , $T_a = -40$ to 85°C

Parameter	Symbol	Conditions	Min	Max	Unit
Input signal rise time	t_r		—	50	ns
Input signal fall time	t_f		—	50	ns
YSCL frequency	t_{CCL}		1000	—	ns
YSCL high-level pulse width	t_{wCLH}		160	—	ns
YSCL low-level pulse width	t_{wCLL}		330	—	ns
Data setup time	t_{DS}		200	—	ns
Data hold time	t_{DH}		10	—	ns
Allowable FR delay	t_{DFR}		−500	500	ns

◦ Output Timing Characteristics



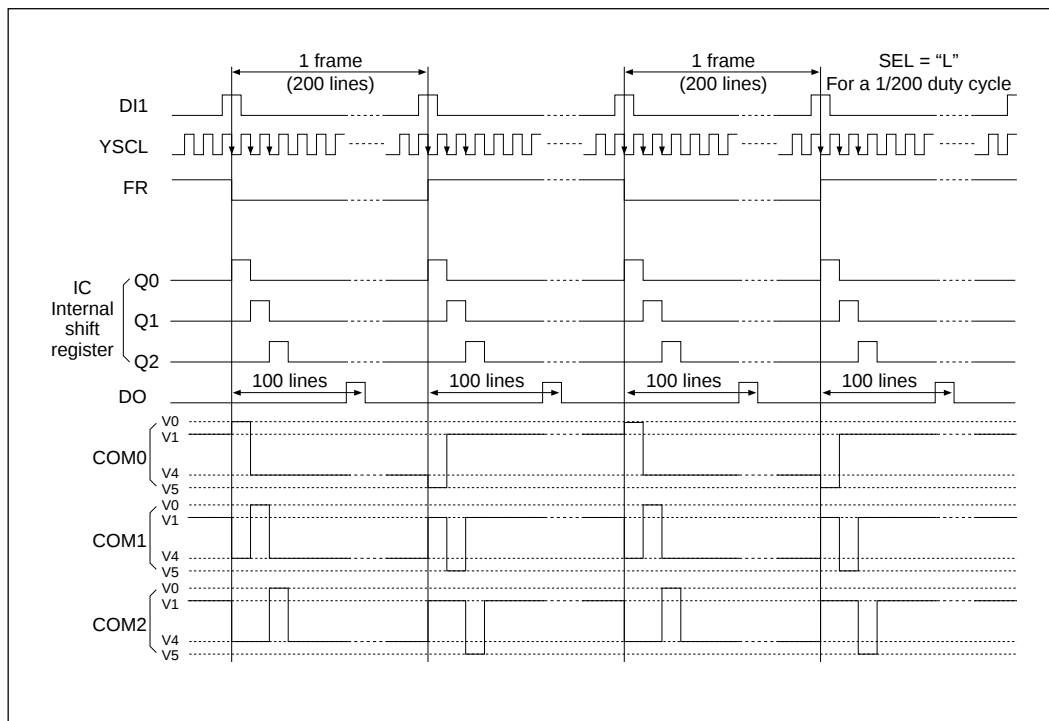
$V_{SS} = -5.0V \pm 10\%$, $T_a = -40$ to $85^\circ C$

Parameter	Symbol	Conditions	Min	Max	Unit
(YSCL fall → D0) delay time	t_{pdDOCL}	$CL = 15pF$	30	300	ns
(YSCL fall → COM output) delay time	t_{pdCCL}	$V_5 = -12.0$ to $-28.0V$	—	3.0	μs
(FR → COM output) delay time	t_{pdCFR}	$CL = 100pF$	—	3.0	μs

$V_{SS} = -2.7$ to $-4.5V$, $T_a = -40$ to $85^\circ C$

Parameter	Symbol	Conditions	Min	Max	Unit
(YSCL fall → D0) delay time	t_{pdDOCL}	$CL = 15pF$	60	600	ns
(YSCL fall → COM output) delay time	t_{pdCCL}	$V_5 = -12.0$ to $-28.0V$	—	3.0	μs
(FR → COM output) delay time	t_{pdCFR}	$CL = 100pF$	—	3.0	μs

- Timing Diagram



■ LCD DRIVING POWER

- Method of Forming Each Voltage Level

The simplest way to obtain the voltage levels for driving the LCs is to use resistive voltage dividers, as shown in the example connection figure. Because a high quality display requires precise and stable voltage levels, the values of the dividing resistances must be set at the low end of the tolerance range of the power capacity.

When there is the need to operate with low power, the values of the voltage dividing resistors must be set high, and the LCs must be driven by an op amp voltage follower. In consideration of the use of op amps, V0 (the highest voltage setting for driving LCs) and VDD are separated and given separate terminals.

However, when the voltage level of V0 is below VDD and the voltage difference between the two is large, the performance of the LC output driver is reduced. Therefore ensure that the voltage gap between V0 and VDD is in the range of 0V to 2.5V.

Connect V0 and VDD when an op amp is not used.

- Cautions During Power Up and Power Down

Because of the high voltage of the LC driving system of this LSI, if the power to the logic system is floating when a high voltage is applied to the LC driving system, then too much current will flow, causing damage to the LSI.

Follow the sequences below during power up and power down:

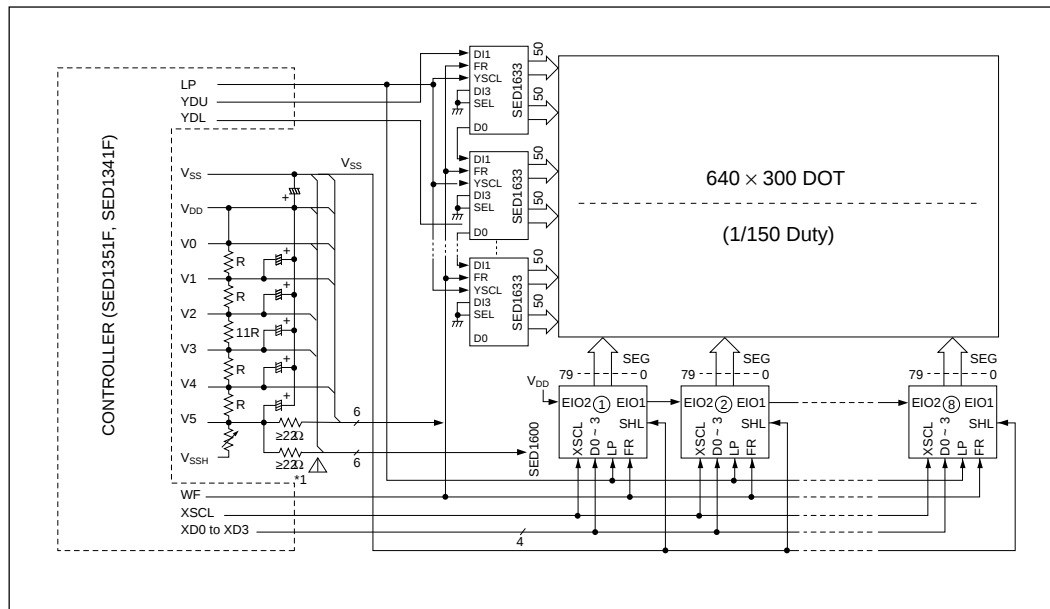
Power up: Logic system on → LC drive system on (or simultaneous)

Power down: LC drive system off → Logic system off (or simultaneous)

In order to prevent excessive current, insert a guard resistance of at least 22 Ω in series with V5.

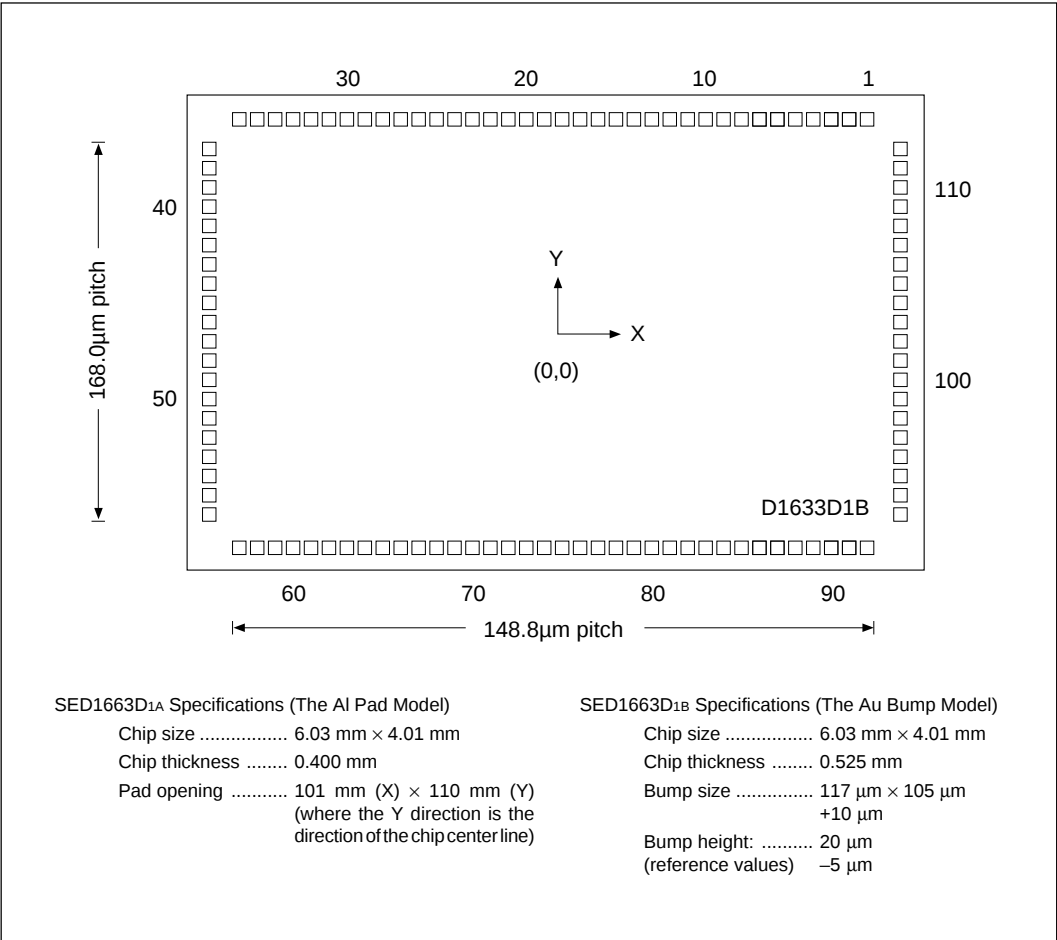
■ EXAMPLE OF CONNECTION

- Connections for a 640 × 300 dot matrix LCD



Note: *1. A guard resistance must be used to prevent excessive current. Moreover, a bypass capacitor (0.01μF) should be used near the Vss and V5 pins of each LSI to prevent noise.

■ PAD LAYOUT



PAD COORDINATES

Applicable to the SED1633D1A and SED1633D1B.

Unit: μm

Pad No.	Pad Name	X Coord.	Y Coord.	Pad No.	Pad Name	X Coord.	Y Coord.	Pad No.	Pad Name	X Coord.	Y Coord.
1	COM5	2604	1834	39	COM43	-2842	1260	76	COM80	223	-1834
2	COM6	2455	1834	40	COM44	-2842	1092	77	COM81	372	-1834
3	COM7	2306	1834	41	COM45	-2842	924	78	COM82	521	-1834
4	COM8	2158	1834	42	COM46	-2842	756	79	COM83	670	-1834
5	COM9	2009	1834	43	COM47	-2842	588	80	COM84	818	-1834
6	COM10	1860	1834	44	COM48	-2842	420	81	COM85	967	-1834
7	COM11	1711	1834	45	COM49	-2842	252	82	COM86	1116	-1834
8	COM12	1562	1834	46	COM50	-2842	84	83	COM87	1265	-1834
9	COM13	1414	1834	47	COM51	-2842	-84	84	COM88	1414	-1834
10	COM14	1265	1834	48	COM52	-2842	-252	85	COM89	1562	-1834
11	COM15	1116	1834	49	COM53	-2842	-420	86	COM90	1711	-1834
12	COM16	967	1834	50	COM54	-2842	-588	87	COM91	1860	-1834
13	COM17	818	1834	51	COM55	-2842	-756	88	COM92	2009	-1834
14	COM18	670	1834	52	COM56	-2842	-924	89	COM93	2158	-1834
15	COM19	521	1834	53	COM57	-2842	-1092	90	COM94	2306	-1834
16	COM20	372	1834	54	COM58	-2842	-1260	91	COM95	2455	-1834
17	COM21	223	1834	55	COM59	-2842	-1428	92	COM96	2604	-1834
18	COM22	74	1834	56	COM60	-2842	-1596	93	COM97	2842	-1596
19	COM23	-74	1834	57	COM61	-2604	-1834	94	COM98	2842	-1428
20	COM24	-223	1834	58	COM62	-2455	-1834	95	COM99	2842	-1260
21	COM25	-372	1834	59	COM63	-2306	-1834	96	D0	2842	-1092
22	COM26	-521	1834	60	COM64	-2158	-1834	97	DI3	2842	-924
23	COM27	-670	1834	61	COM65	-2009	-1834	98	FR	2842	-756
24	COM28	-818	1834	62	COM66	-1860	-1834	99	YSCL	2842	-588
25	COM29	-967	1834	63	COM67	-1711	-1834	100	SEL	2842	-420
26	COM30	-1116	1834	64	COM68	-1562	-1834	101	VDD	2842	-252
27	COM31	-1265	1834	65	COM69	-1414	-1834	102	VSS	2842	-84
28	COM32	-1414	1834	66	COM70	-1265	-1834	103	V0	2842	84
29	COM33	-1562	1834	67	COM71	-1116	-1834	104	V1	2842	252
30	COM34	-1711	1834	68	COM72	-967	-1834	105	V4	2842	420
31	COM35	-1860	1834	69	COM73	-818	-1834	106	V5	2842	588
32	COM36	-2009	1834	70	COM74	-670	-1834	107	DI1	2842	756
33	COM37	-2158	1834	71	COM75	-521	-1834	108	COM0	2842	924
34	COM38	-2306	1834	72	COM76	-372	-1834	109	COM1	2842	1092
35	COM39	-2455	1834	73	COM77	-223	-1834	110	COM2	2842	1260
36	COM40	-2604	1834	74	COM78	-74	-1834	111	COM3	2842	1428
37	COM41	-2842	1596	75	COM79	74	-1834	112	COM4	2842	1596
38	COM42	-2842	1428								

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