

HMCS400 Series

Application Note

HITACHI

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Preface

The HMCS43XX family is a family of 4-bit microcomputers built around the HMCS400 CPU and including standard peripheral functions such as A/D converters with a variety of A/D input channels, serial interfaces, and multifunction timers. The architecture of the powerful HMCS400 CPU core is known for its ease of programming.

The peripheral functions of the HMCS43XX have been developed as standalone modules and a modular architecture employed in which the respective modules are connected via a standardized interface.

The HD404889 Series are also 4-bit microcomputers also built around the powerful HMCS400 CPU core with its excellent ease of programming, and including various peripheral functions such as LCD circuit, A/D converters, and multifunction timers. The microcomputers in this series are ideally suited to display panel control and system control in a wide range of applications, primarily audio-visual equipment such as radiocassette sets with built-in CD players, as well as home appliances such as electronic jars, and telephones and pagers.

The peripheral functions of the HM404889 Series have been developed as standalone modules and a modular architecture employed in which the respective modules are connected via a standardized interface.

The “Applications” volume of the HMCS400 Series Application Notes is a collection of examples of combinations of the built-in peripherals in the HMCS400 Series of microcomputers. This collection is intended as a reference for software and hardware designers.

The operation of the programs and circuits, etc., described in these application notes has been checked. However, please be sure to confirm their operation before actually using them in any application.

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Section 1 HMCS400 Series Application Notes— How to Use the Applications Volume

The Application Notes are, as shown in figure 1, divided into two sections.

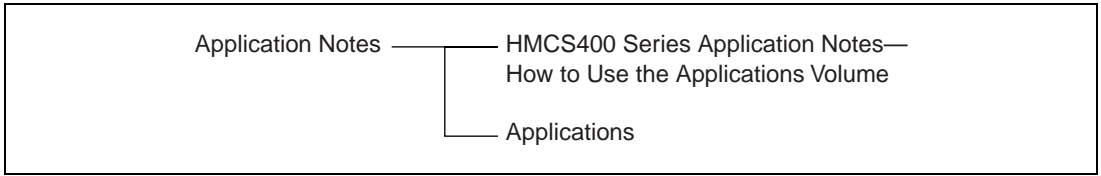


Figure 1 Structure of Application Notes

HMCS400 Series Application Notes—How to Use the Applications Volume

This section describes how to use the HMCS400 Series Application Notes—Applications Volume.

Applications

This section uses simple example tasks to describe how various combinations of the built-in peripherals (timers, serial interface, A/D converters, I/O ports, interrupts, low-power modes, etc.) of the MHCS400 Series of microcomputers are used.

1.1 Structure of Applications Section

As shown in figure 2, the Applications section describes how to use the built-in functions of the HMCS400 Series.

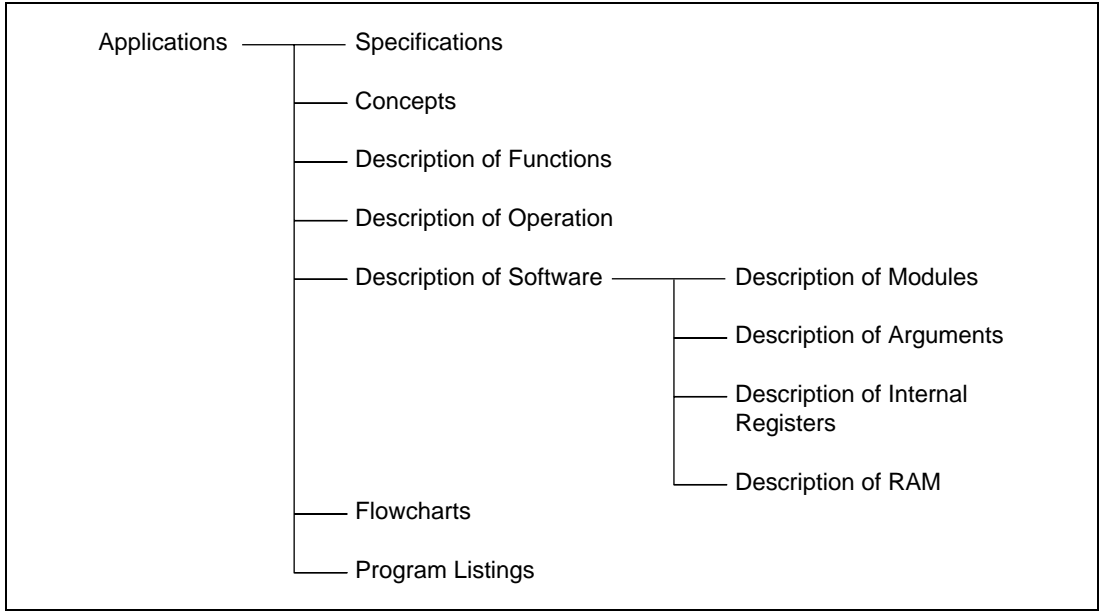


Figure 2 Structure of Applications Section

Specifications

This section describes the system specifications for the example tasks.

Concepts

This section describes the methods employed to realize the systems in the example tasks.

Description of Functions

This section describes the features and distribution of the peripheral functions employed in the example tasks.

Description of Operation

This section uses timing charts to describe the operation of the example tasks.

Description of Software

1. Description of Modules

This section describes the software module operating in the example tasks.

2. Description of Arguments

This section describes the input arguments required for execution of the respective modules, and the arguments output on completion of module execution.

3. Description of Internal Registers

This section describes the internal registers (timer control register and serial mode register, etc.) set by the module.

4. Description of RAM

This section describes the RAM labels used by the modules and their functions.

Flowcharts

This section provides flowcharts of the software run in the example tasks.

Program Listings

This section provides listings of the software run in the example tasks.

Section 2 Applications

2.1 Musical Performance

Musical Performance	MCU: H4344/H4318/H4359/ H4369/H4889	Functions Used: R0/R1 Port, Timer B, and Timer C
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Specifications

1. As shown in figure 1, the Bach minuet is played repeatedly in the H4344/H4318/H4359/H4369 Series by connecting a speaker with an 8-Ω resistance to the R0₃ port. In the H4889, this is achieved by connecting to the R1₂ port.

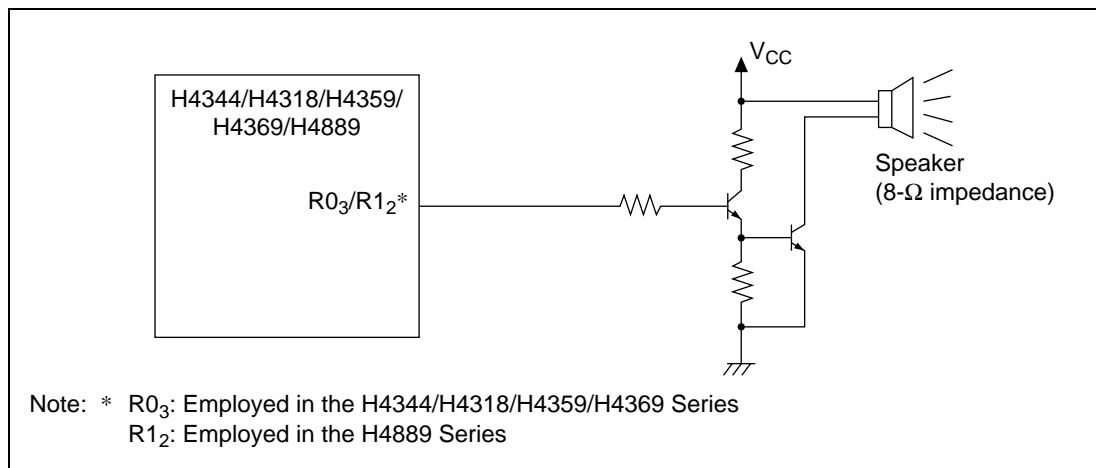


Figure 1 Speaker Connection in Musical Performance

Concepts

1. The “minuet” is played by outputting a pulse with a frequency corresponding to the notes from the $R0_3/R1_2$ port.
2. The frequencies corresponding to the notes are set using the timer B reload timer function. The data table is referenced using the pattern command and the referenced data set in the timer-counter B reload value to achieve the frequency corresponding to the desired note. Moreover, the High/Low output from the $R0_3/R1_2$ port is controlled during timer B interrupt processing.
3. The duration of each note is set using the timer C reload timer function. The data table is referenced using the pattern command and the referenced data set in the timer counter C reload value to set the output duration of each note.
4. Figure 2 shows the settings for the frequencies for the respective notes and the duration of each note.

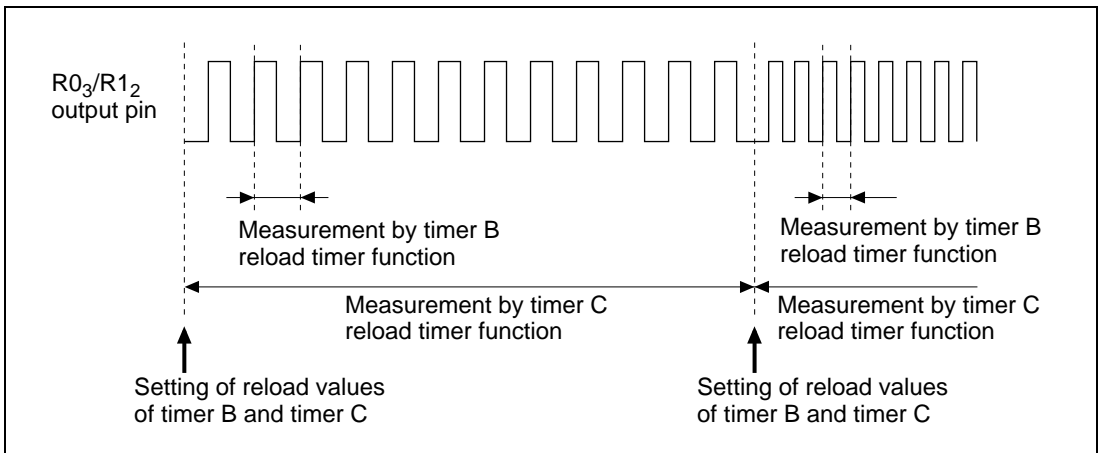


Figure 2 Method of Setting Frequencies for Notes and Output Durations

Description of Functions

1. In this example task, the R0/R1 port, timer B, and timer C functions are used to play a Bach minuet. Figure 3 is a functional block diagram of this task.

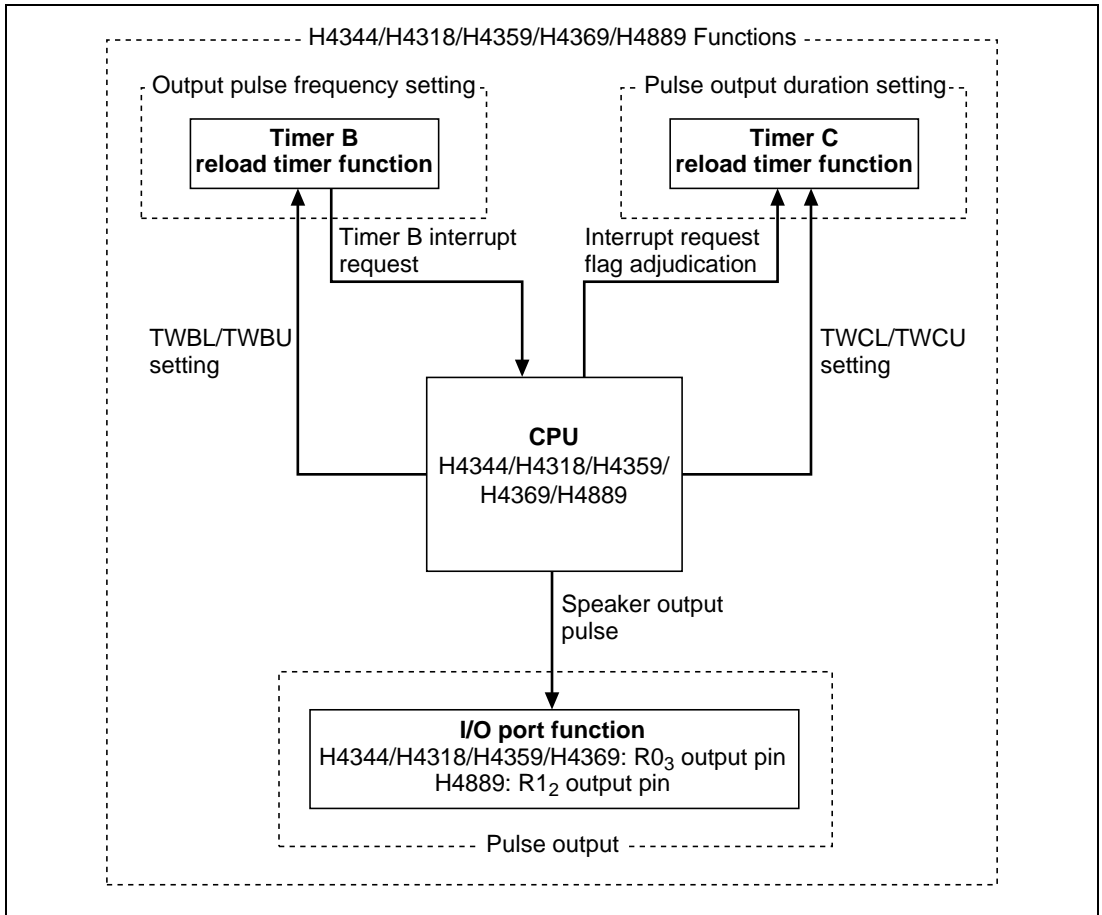


Figure 3 Functional Block Diagram

- Timer B reload timer function

This function sets the output pulse frequency. The frequency of the output pulse is set by the timer counter B reload value. The reload value to be set is referenced from the data table.

- Timer C reload timer function

This function sets the duration for which a frequency pulse is output. The duration of pulse output is set by the timer counter C reload value. The reload value to be set is referenced from the data table.

- I/O port function

This is the output for the pulse to be output to the speaker.

2. The timer B, timer C, and I/O port functions are described below.

a. Figure 4 is a block diagram of the timer B function.

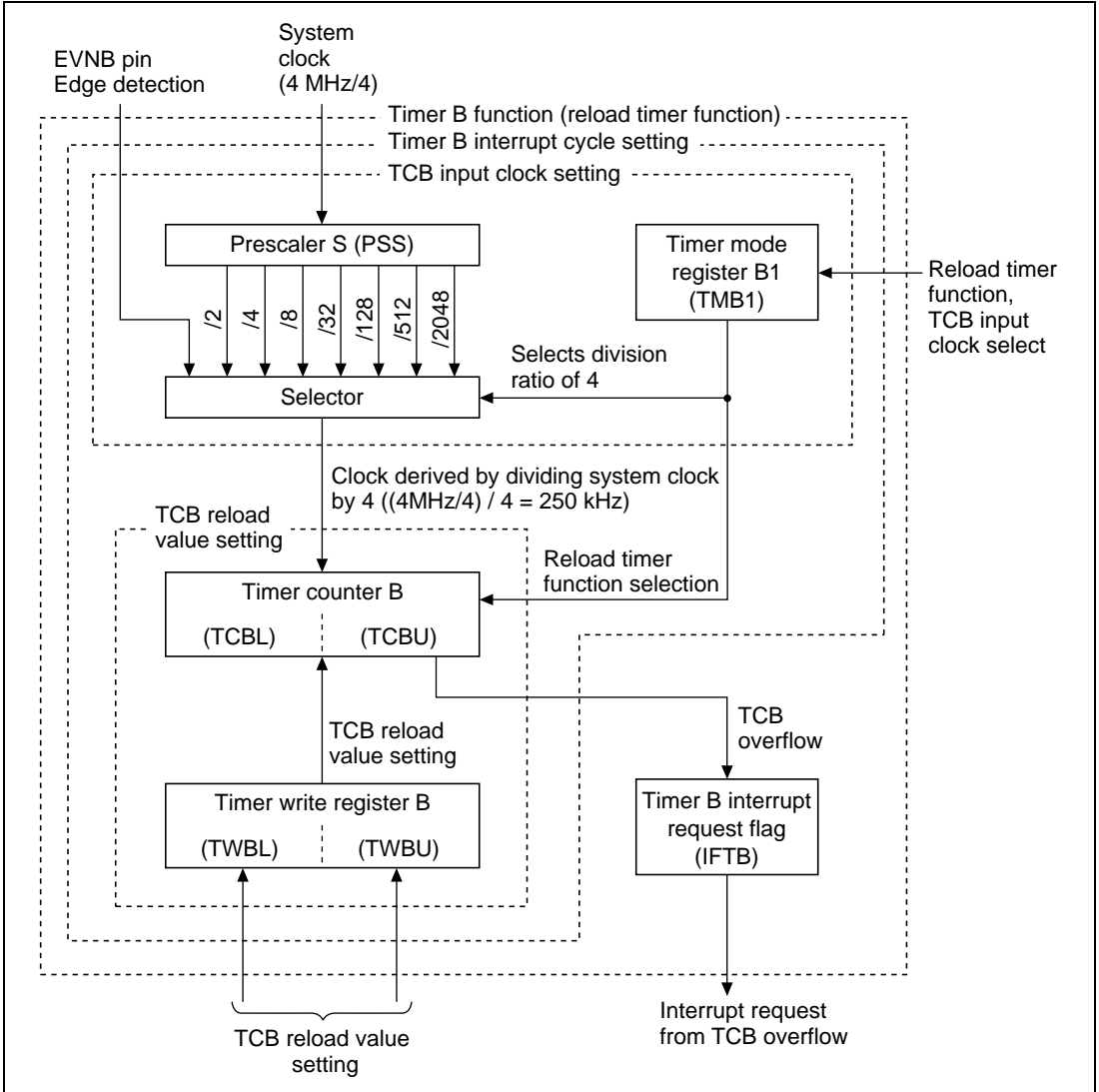


Figure 4 Timer B Function Block Diagram

- b. Timer B is an 8-bit multifunction timer (free running/event counter/reload timer/input capture^{*1}). In this example task, timer B is used as a reload timer. Table 1 describes the timer B functions.

Table 1 Timer B Functions

Timer Mode Register B1 (TMB1)	
Function	TMB1 is a 4-bit write-only register. It selects the timer B function (free-running/reload timer) and operating clock. TMB1 is initialized to \$0 when reset and in stop mode.
Timer Write Register BL, U (TWBL, TWBU)	
Function	TWBL and TWBU form an 8-bit write-only register, which is made up of the lower digit (TWBL) and upper digit (TWBU). TWBL and TWBU are used for the initial TCB setting (the reload setting when operation as a reload timer).
Timer Counter B (TCB)	
Function	TCB is an 8-bit up-counter, which is incremented by the input internal clock. The TCB input clock is selected using bits TMB12 to TMB10 of TMB1. The value written to TWBL and TWBU is also written to TCB. When TCB overflows, the timer B interrupt request flag (IFTB) is set to "1". If, at this point, timer B is set as a reload timer, the value of TWBL and TWBU is written to this counter and the count starts from this value. TCB is initialized to \$00 when reset and in stop mode.
Prescaler S (PSS)	
Function	PSS is an 11-bit counter to which the system clock is input when in active mode and standby mode, and the subsystem clock is input when in subactive mode ^{*2} . PSS is initialized to \$000 at a reset, and division of the system clock starts when the reset is canceled. PSS operation is halted when reset, in stop mode, and in watch mode ^{*2} . However, it runs in other operating modes. The PSS output is shared by the internal peripheral modules, the division ratio being set independently for each of the internal peripheral modules.
Timer B Interrupt Request Flag (IFTB)	
Function	IFTB reflects the existence of the timer B interrupt request. When timer B overflows, IFTB is set to "1". IFTB can only be read/written to (only "0" can be written) using bit operation commands. Note that IFTB is not automatically cleared even when the interrupt is received, and must be cleared by writing "0" using software. IFTB is cleared at a reset and in stop mode.
Timer B Interrupt Mask (IMTB)	
Function	IMTB is the bit that masks IFTB. When IFTB is set to "1" and, additionally, IMTB is "0", a timer B interrupt request is sent to the CPU (when IE = "1"). If IFTB is set to "1" but IMTB is "1", no interrupt request is sent to the CPU and the timer B interrupt is held. IMTB can only be read or written to using bit operation commands. It is set to "1" at a reset and in stop mode.

- Notes: 1. Applies to H4318/H4359/H4369 Series only. In the H4344/H4889 Series, timer B has no input capture function.
 2. Applies only to H4369/H4889 Series.

c. Figure 5 is a block diagram of the timer C function in the H4344/H4318/H4359/H4369 Series.

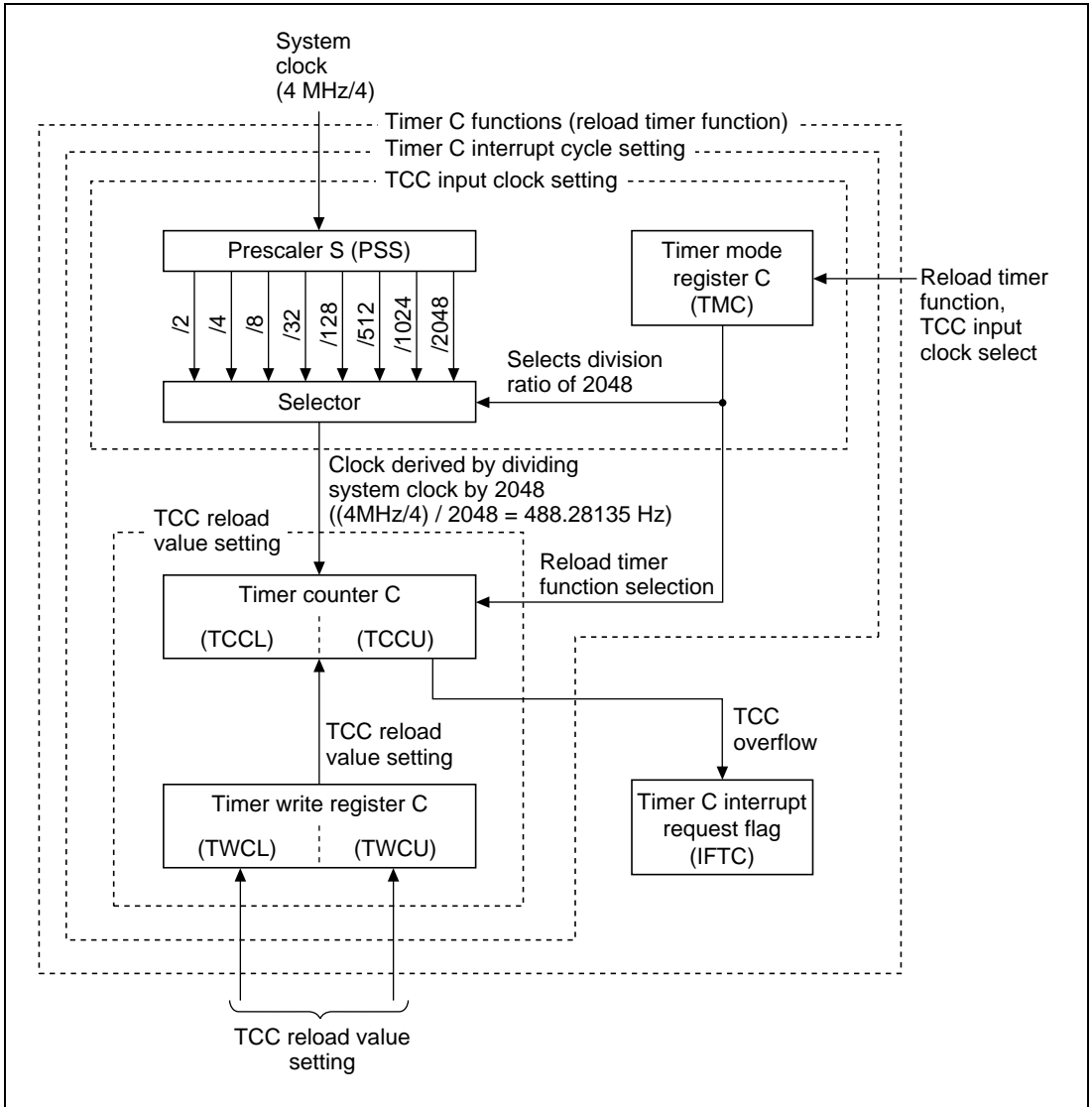


Figure 5 H4344/H4318/H4359/H4369 Series Timer C Function Block Diagram

d. Figure 6 is a block diagram of the timer C function in the H4889 Series.

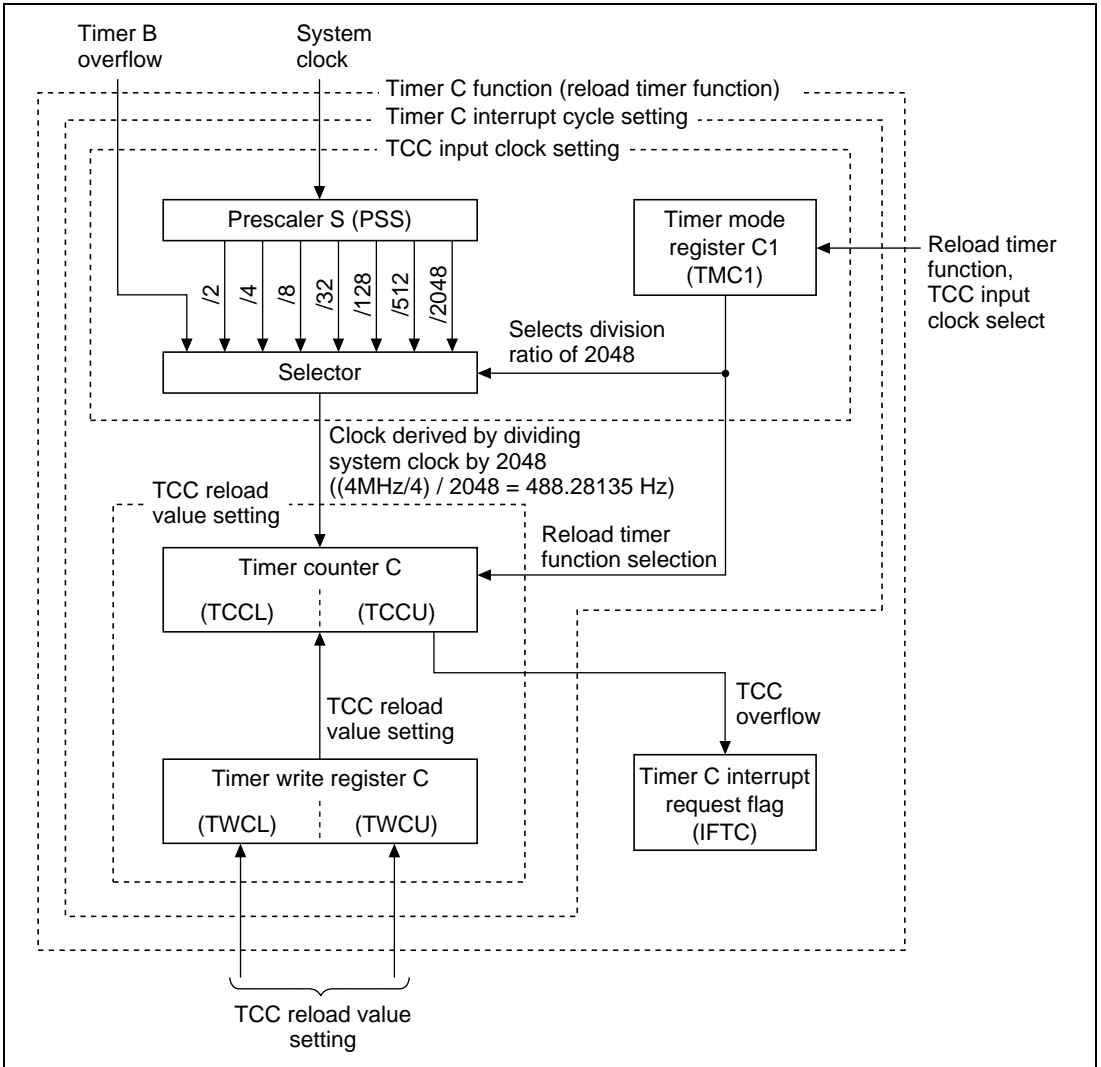


Figure 6 H4889 Series Timer C Function Block Diagram

- e. Timer C is an 8-bit multifunction timer (free running/reload timer). In the H4889 Series, timer B overflow can be selected as the clock source, allowing timer B and timer C to be used as a 16-bit counter. In this example task, timer C is used as a reload timer. Table 2 describes the timer C functions.

Table 2 Timer C Functions

Timer Mode Register C (TMC)		Note: Applies to H4344/H4318/H4359/H4369 Series
Function	TMC is a 4-bit write-only register. It selects the timer C function (free-running/reload timer) and operating clock. TMC is initialized to \$0 when reset and in stop mode.	
Timer Mode Register C1 (TMC1)		Note: Applies to H4889 Series
Function	TMC1 is a 4-bit write-only register. It selects the timer C function (free-running/reload timer) and operating clock. TMC1 is initialized to \$0 when reset and in stop mode.	
Timer Write Register CL, U (TWCL, TWCU)		
Function	TWCL and TWCU form an 8-bit write-only register, which is made up of the lower digit (TWCL) and upper digit (TWCU). TWCL and TWCU are used for the initial TCC setting (the reload setting when operation as a reload timer).	
Timer Counter C (TCC)		
Function	TCC is an 8-bit up-counter, which is incremented by the input internal clock. The TCC input clock is selected using bits TMC12 to TMC10 of TMC1. The value written to TWCL and TWCU is also written to TCC. When TCC overflows, the timer C interrupt request flag (IFTC) is set to "1". If, at this point, timer C is set as a reload timer, the value of TWCL and TWCU is written to this counter and the count starts from this value. TCC is initialized to \$00 when reset and in stop mode.	
Timer C Interrupt Request Flag (IFTC)		
Function	IFTC reflects the existence of the timer C interrupt request. When timer C overflows, IFTC is set to "1". IFTC can only be read/written to (only "0" can be written) using bit operation commands. Note that IFTC is not automatically cleared even when the interrupt is received, and must be cleared by writing "0" using software. IFTC is cleared at a reset and in stop mode.	
Timer C Interrupt Mask (IMTC)		
Function	IMTC is the bit that masks IFTC. When IFTC is set to "1" and, additionally, IMTC is "0", a timer C interrupt request is sent to the CPU (when IE = "1"). If IFTC is set to "1" but IMTC is "1", no interrupt request is sent to the CPU and the timer C interrupt is held. IMTC can only be read or written to using bit operation commands. It is set to "1" at a reset and in stop mode.	

f. Figure 7 is a block diagram of the R0 port functions in the H4344/H4318/H4359/H4369 Series. Figure 8 is a block diagram of the R1 port functions in the H4889 Series.

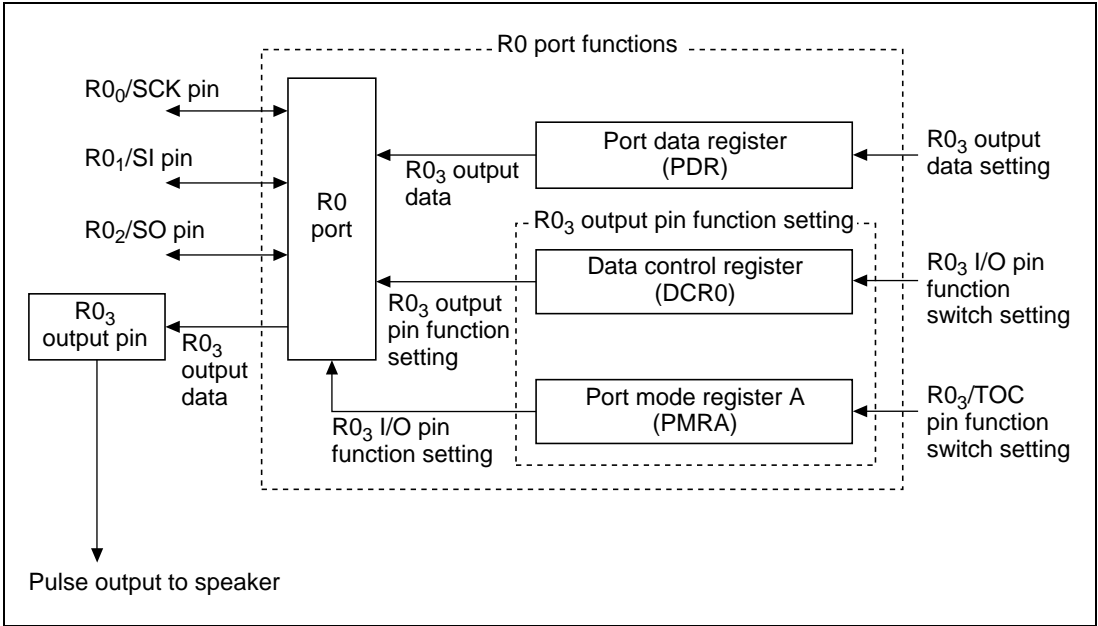


Figure 7 Function Block Diagram of R0 Port in H4344/H4318/H4359/H4369 Series

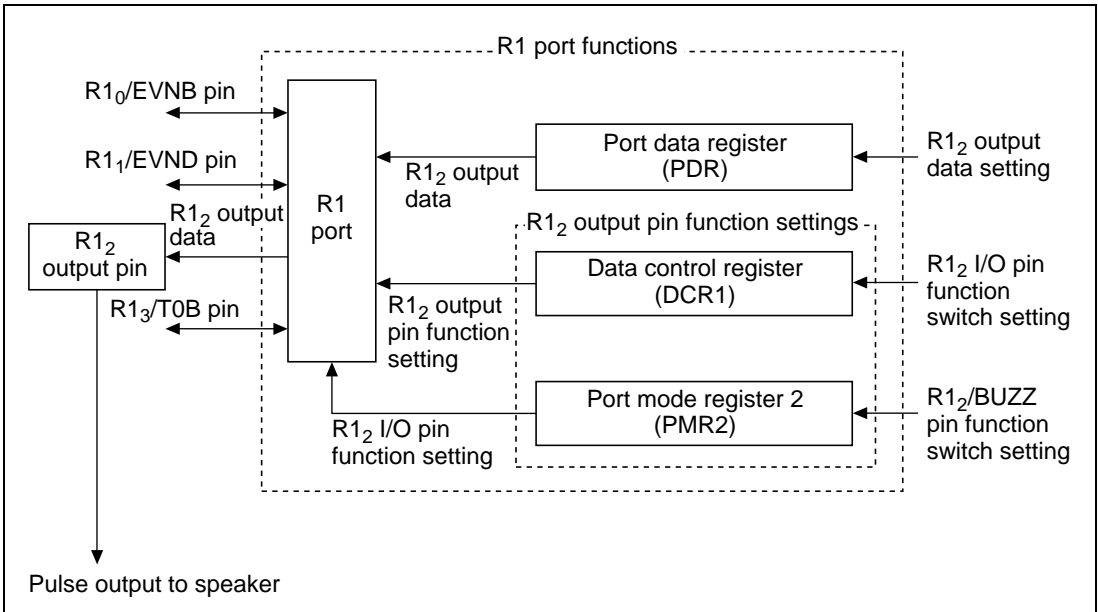


Figure 8 Function Block Diagram of R1 Port in H4889 Series

- g. The R0 port in the H4344/H4318/H4359/H4369 Series, and the R1 port in the H4889 Series are 4-bit I/O ports. The LAR and LBR commands are used for 4-bit input, and the LRA and LRB commands for 4-bit output of both ports. The output data is stored in the PDR of the respective pin. In this example task, the R0₃ pin in the H4344/H4318/H4359/H4369 Series and the R1₂ pin the H4889 Series are set for output, and output a pulse to a speaker. Table 3 describes the functions of the R0 port in the H4344/H4318/H4359/H4369 Series and the R1 port in the H4889 Series.

Table 3 Description of R0 Port Functions in H4344/H4318/H4359/H4369 Series and R1 Port Functions in H4889 Series

Data Control Register R0 (DCR0)		Note: Applies to H4344/H4318/H4359/H4369 Series
Function	DCR0 switches the I/O pin function of the R0 port. When any bit of DCR0 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR0 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.	
Data Control Register R1 (DCR1)		Note: Applies to H4889 Series
Function	DCR1 switches the I/O pin function of the R1 port. When any bit of DCR1 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR1 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.	
Port Mode Register A (PMRA)		Note: Applies to H4344/H4318/H4359/H4369 Series
Function	PMRA is a 4-bit write-only register. Bits PMRA2 to PMRA0 switch the dual-function R0 port pins.	
Port Mode Register 2 (PMR2)		Note: Applies to H4889 Series
Function	PMR2 is a 4-bit write-only register. Bits PMR23 to PMR20 switch the dual-function R1 port pins.	
Port Data Register (PDR)		
Function	The I/O pins of the R ports have built-in PDRs to store the output data. When the LRA and LRB commands are executed, the contents of the accumulator (A) and B register (B) are transferred to the PDR of the specified R port. When the corresponding bit of the DCR of the R port is "1", the output buffer of the appropriate pin is set ON and the value in the PDR is output via that pin. The PDR is initialized to \$F at a reset.	

3. Table 4 shows the allocation of functions in the example task.

Table 4 Function Allocation

Function	Function Allocation
System clock	The system clock is obtained by dividing the clock output from the system clock oscillator by 4. It is used for operating the CPU and internal peripheral modules. In this example task, a 4 MHz system clock oscillator is used, so the clock supplied to the CPU and internal peripheral modules is 1 MHz. The clock used by timer B and timer C is obtained by dividing the 1 MHz clock at PSS.
PSS	The clock input to timer B and timer C is obtained by dividing the system clock. The clock supplied to timer B is obtained by dividing the system clock by 4. The clock supplied to timer C is obtained by dividing the system clock by 2048.
TCB	This is an 8-bit up-counter. The count starts from the value set in TWBL and TWBU. When an overflow occurs, IFTB is set to "1". After an overflow, the reload value set in TWBL and TWBU is set in TCB.
TWBL, TWBU	The TCB reload value is set in TWBL and TWBU. The reload value is determined from the pulse frequency to be output to the speaker. The frequencies corresponding to the various notes are stored in the data table.
TMB1	TMB1 selects the reload timer function for timer B and a clock obtained by dividing the system clock by 4 as the TCB input clock.
IFTB	IFTB reflects the existence of a timer B interrupt request. The pulse output pin output level is set in the timer B interrupt processing.
IMTB	Enables/disables timer B interrupt requests.
TCC	This is an 8-bit up-counter. The count starts from the value set in TWCL and TWCU. When an overflow occurs, IFTC is set to "1". After an overflow, the reload value set in TWCL and TWCU is set in TCC.
TWCL, TWCU	The TCC reload value is set in TWCL and TWCU. The reload value is determined from the duration of pulse output to the speaker. The output duration for each note is stored in the data table.
TMC (H4344/H4318/ H4359/H4369) TMC1 (H4889)	TMC (or TMC1) selects the reload timer function for timer C and a clock obtained by dividing the system clock by 2048 as the TCC input clock.
IFTC	Reflects the existence of a timer C interrupt request.
IMTC	Enables/disables timer C interrupt requests.
DCR0 (H4344/H4318/ H4359/H4369) DCR1 (H4889)	Sets the R ₀ pins (H4344/H4318/H4359/H4369 Series) and R ₁ pins (H4889 Series) as output pins.

Table 4 Function Allocation (cont)

Function	Function Allocation
PMRA (H4344/H4318/ H4359/H4369) PMR2 (H4889)	Sets the R0 ₃ /TOC dual-function pin (H4344/H4318/H4359/H4369 Series) as an R0 ₃ I/O pin and the R1 ₂ /BUZZ dual-function pin (H4889 Series) as an R1 ₂ pin.
PDR	Stores the output data for the R0 ₃ /R1 ₂ pin.
R0 ₃ pin	Output pin for the pulse in the H4344/H4318/H4359/H4369 Series.
R1 ₂ pin	Output pin for the pulse in the H4889 Series.

Description of Operation

1. Figure 9 shows the operating principles of the timer B, timer C, and R₀₃/R₁₂ output pins.

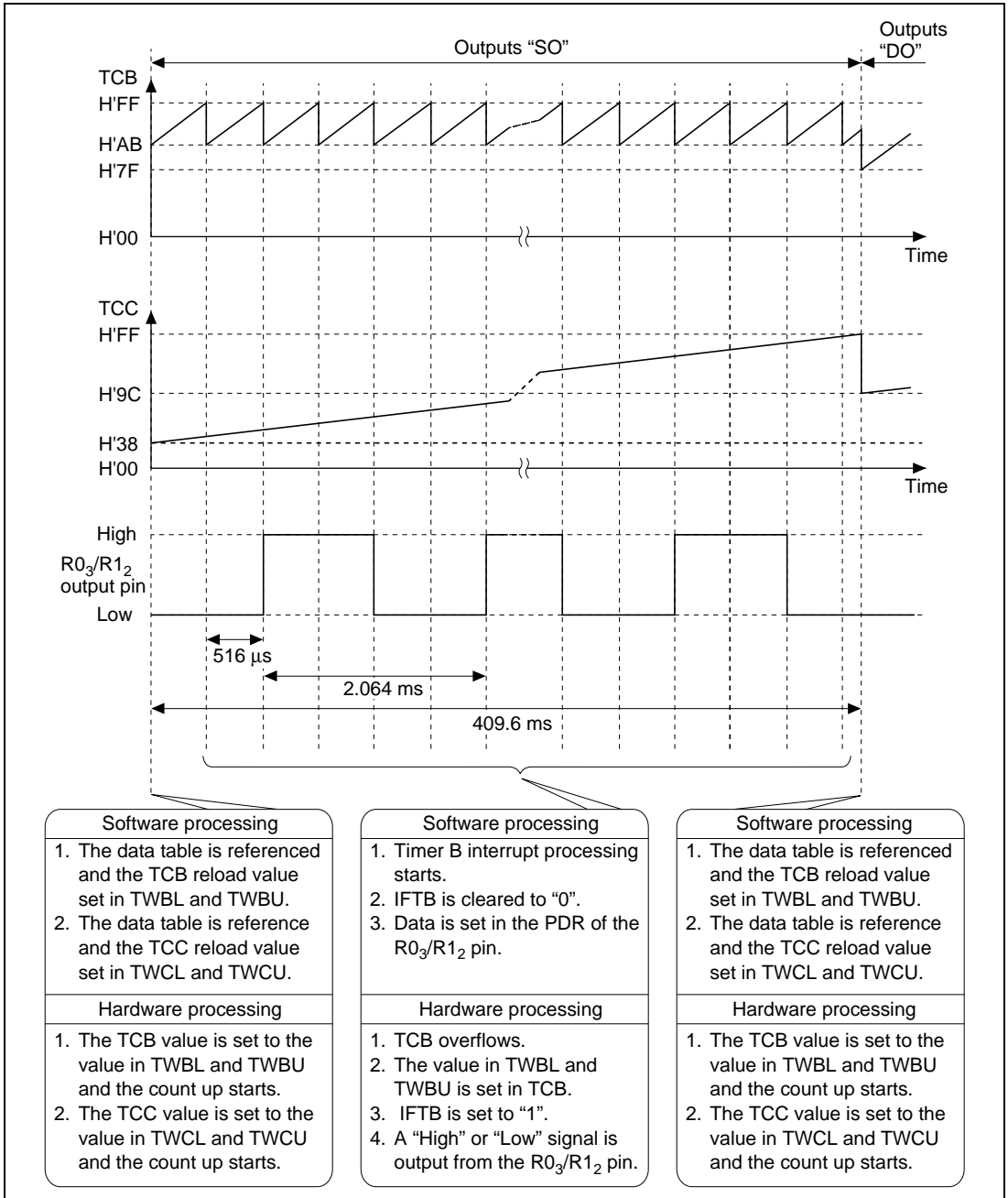


Figure 9 Operating Principles of Timer C, Timer B, and R₀₃/R₁₂ Output Pins

2. Figure 10 shows the operating principles for the pulse output from the $R0_3/R1_2$ pin.

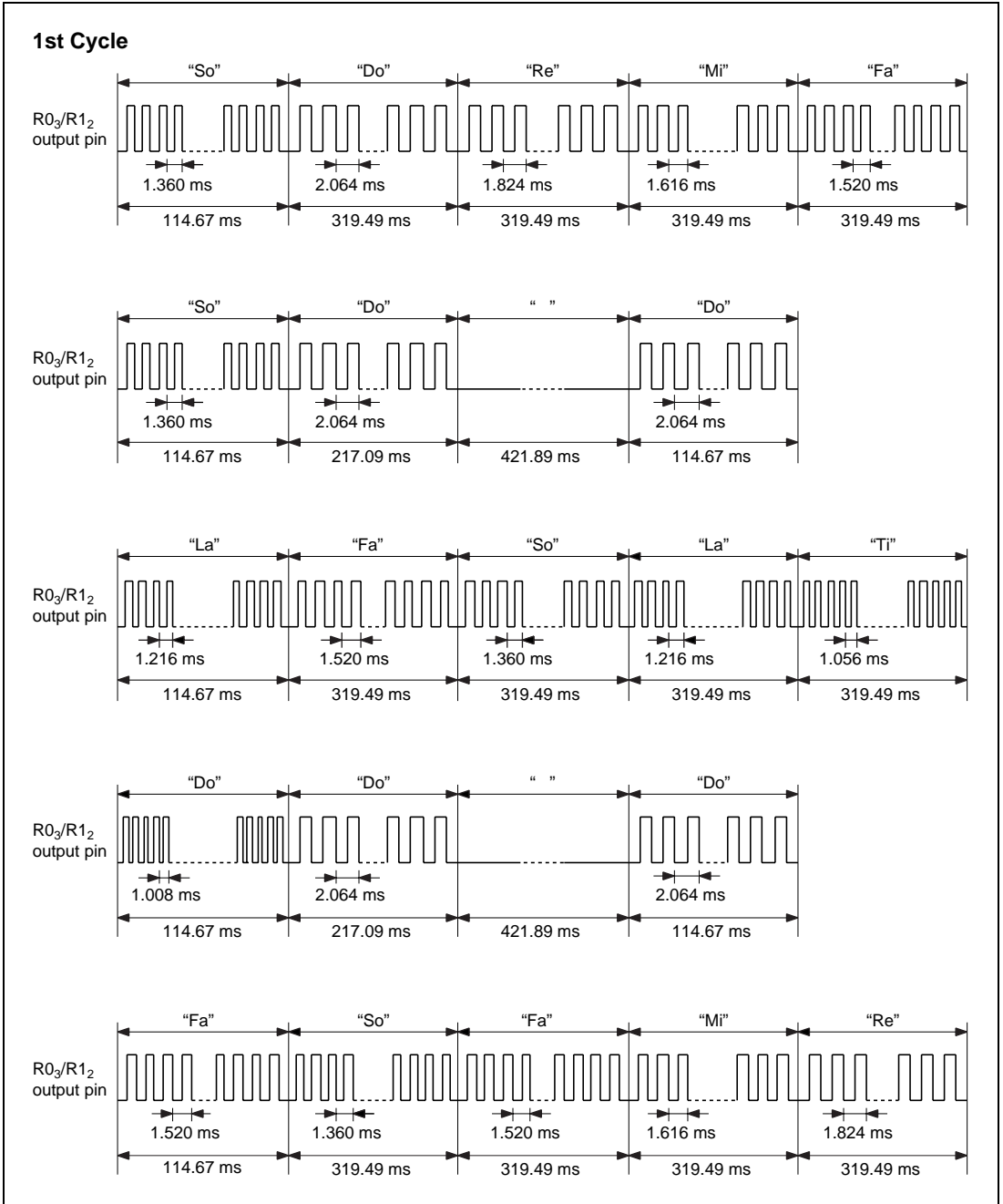
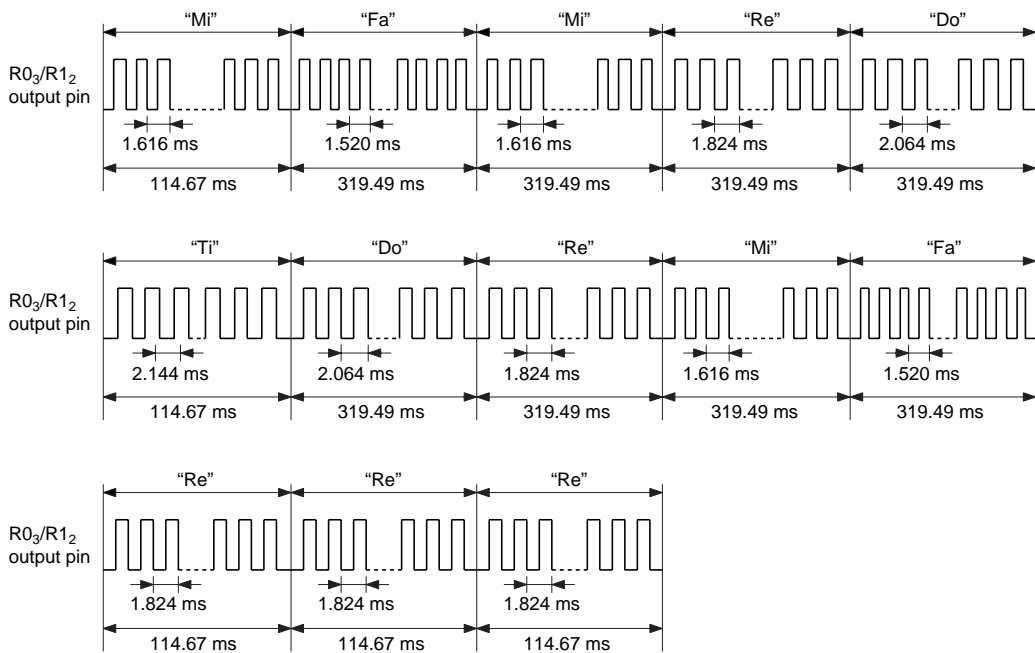


Figure 10 Operating Principles of Output Pulse



2nd Cycle

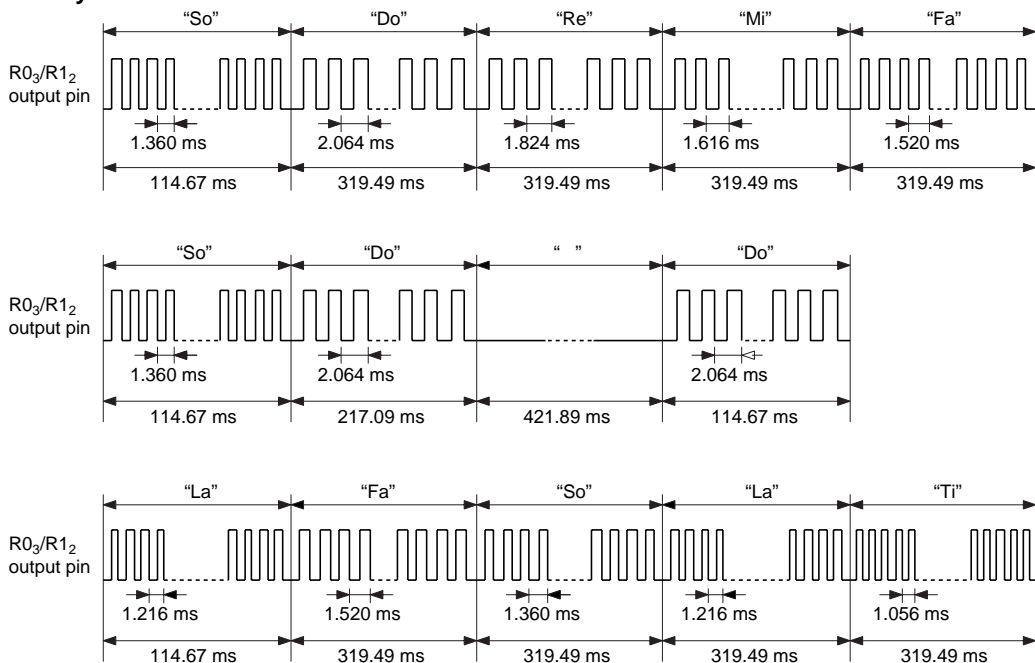


Figure 10 Operating Principles of Output Pulse (cont)

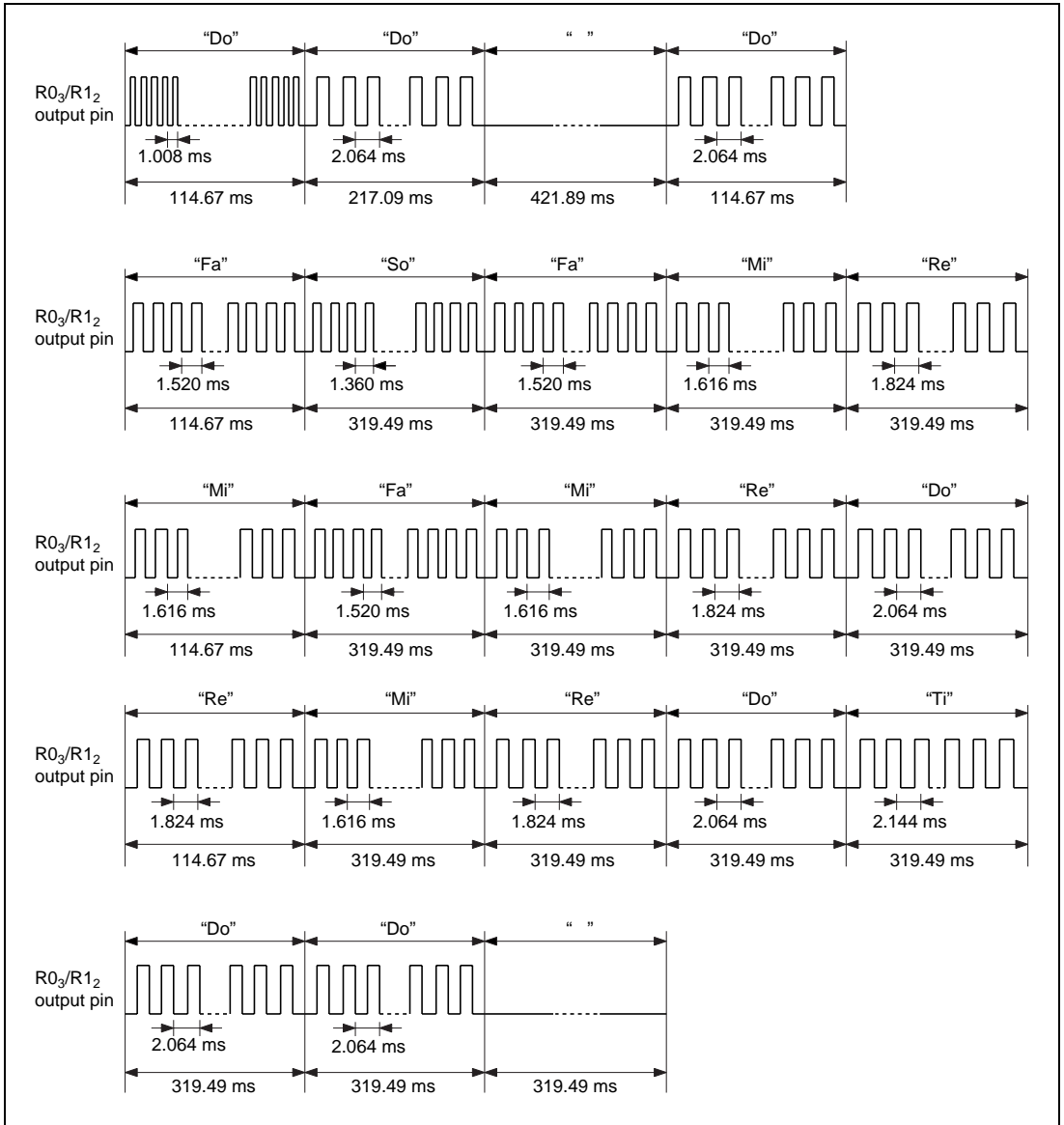
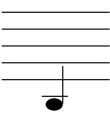

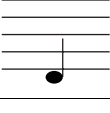
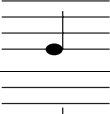
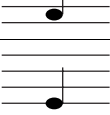
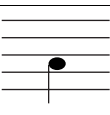
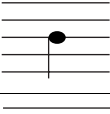
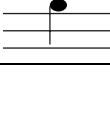



Figure 10 Operating Principles of Output Pulse (cont)

3. Table 5 shows the output pulse frequencies for the respective notes.

Table 5 Output Pulse Frequencies for Respective Notes

Note	Score	TCB Reload Value	TCB Overflow Cycle	Speaker Pulse Output Frequency
Ti		\$7A	536 μ s	$1 / (536 \mu\text{s} \times 4) \approx 466.42 \text{ Hz}$
Do		\$7F	516 μ s	$1 / (516 \mu\text{s} \times 4) \approx 484.50 \text{ Hz}$
Re		\$8E	456 μ s	$1 / (456 \mu\text{s} \times 4) \approx 548.25 \text{ Hz}$
Mi		\$9B	404 μ s	$1 / (404 \mu\text{s} \times 4) \approx 618.81 \text{ Hz}$
Fa		\$A1	380 μ s	$1 / (380 \mu\text{s} \times 4) \approx 657.89 \text{ Hz}$
So		\$AB	340 μ s	$1 / (340 \mu\text{s} \times 4) \approx 735.29 \text{ Hz}$
La		\$B4	304 μ s	$1 / (304 \mu\text{s} \times 4) \approx 822.37 \text{ Hz}$
Ti		\$BD	264 μ s	$1 / (264 \mu\text{s} \times 4) \approx 946.97 \text{ Hz}$
Do		\$C1	252 μ s	$1 / (252 \mu\text{s} \times 4) \approx 992.06 \text{ Hz}$

Description of Functions

1. Description of Modules

Table 6 describes the modules used in the example task.

Table 6 **Description of Modules**

Module	Label	Function
Main routine	SPLMN	This routine makes the initial stack pointer, timer B, timer C, and I/O port settings, enables the interrupts, and initializes the RAM to be used. It also sets the output pulse cycle created by the timer C overflow and the output duration, and initializes and sets those again each time another play starts.
Timer B interrupt processing routine	SPLINT	Controls the "High/Low" setting of the output pulse.

2. Description of Arguments

No arguments are used in this example task.

3. Description of Internal Registers

- a. Table 7 shows the internal registers of the H4344/H4318/H4359/H4369 used in this example.

Table 7 Internal Registers of H4344/H4318/H4359/H4369 Used in Example

Register	Description	RAM Address	Setting
IE	<p>Interrupt Enable Flag</p> <p>This flag controls reception of all interrupts by the CPU.</p> <ul style="list-style-type: none"> When IE = "0", CPU reception of all interrupts is disabled. When IE = "1", CPU reception is enabled. 	0, \$000	1
RSP	<p>Reset Stack Pointer</p> <p>Clearing RSP to "0" initializes the stack pointer.</p>	1, \$000	0
IFTB	<p>Timer B Interrupt Request Flag</p> <p>Reflects the existence of a timer B interrupt request.</p> <ul style="list-style-type: none"> When IFTB = "0", no timer B interrupt is requested. When IFTB = "1", a timer B interrupt is requested. 	0, \$002	0
IMTB	<p>Timer B Interrupt Mask</p> <p>This bit masks IFTB.</p> <ul style="list-style-type: none"> When IMTB = "0", IFTB is enabled. When IMTB = "1", IFTB is masked. 	1, \$002	0
IFTC	<p>Timer C Interrupt Request Flag</p> <p>Reflects the existence of a timer C interrupt request.</p> <ul style="list-style-type: none"> When IFTC = "0", no timer C interrupt is requested. When IFTC = "1", a timer C interrupt is requested. 	2, \$002	0
IMTC	<p>Timer C Interrupt Mask</p> <p>This bit masks IFTC.</p> <ul style="list-style-type: none"> When IMTC = "0", IFTC is enabled. When IMTC = "1", IFTC is masked. 	3, \$002	1
PMRA	<p>Port Mode Register A</p> <p>Bit 0 switches R0₂, SO pin functions, bit 1 switches R0₄/SI pin functions, bit 2 switches R0₃/TOC pin functions, and bit 3 switches D₃/BUZZ pin functions.</p> <ul style="list-style-type: none"> When PMRA = \$0, pins R0₂, R0₁, R0₃ and D₃ are selected. <p>Note: PMRA bit 3 cannot be used in the H4344 Series.</p>	\$004	\$0

Table 7 Internal Registers of H4344/H4318/H4359/H4369 Used in Example (cont)

Register	Description	RAM Address	Setting
TMB1	<p>Timer Mode Register B1</p> <p>TMB13 selects timer B functions, TMB12 to TMB10 select the operating clock</p> <ul style="list-style-type: none"> When TMB13 = "1", TMB12 = "1", TMB11 = "1", and TMB10 = "1", timer B is set for reload timer functions and the operating clock is set for the system clock divided by 4. 	\$009	\$D
TWBL	<p>Timer Write Register BL</p> <p>Sets the lower digit of the TCB reload value.</p>	\$00A	\$0
TWBU	<p>Timer Write Register BU</p> <p>Sets the upper digit of the TCB reload value.</p>	\$00B	\$0
TMC	<p>Timer Mode Register C</p> <p>Selects timer C functions and operating clock.</p> <ul style="list-style-type: none"> When TMC3 = "1", TMC2 = "0", TMC1 = "0", and TMC0 = "0", timer C is set for reload timer functions and the operating clock is set for the system clock divided by 2048. 	\$00D	\$8
TWCL	<p>Timer Write Register CL</p> <p>Sets the lower digit of the TCC reload value.</p>	\$00E	\$0
TWCU	<p>Timer Write Register CU</p> <p>Sets the upper digit of the TCC reload value.</p>	\$00F	\$0
TMB2	<p>Timer Mode Register B2</p> <p>Sets the input capture function and selects the detection edge of the EVNB pin input.</p> <ul style="list-style-type: none"> When TMB22 = "0", free-running/reload timer B functions are selected. When TMB22 = "1", input capture timer B functions are selected. <p>Note: The TMB22 bit cannot be used in the H4344.</p> <ul style="list-style-type: none"> When TMB21 = "0" and TMB20 = "0", there is no edge detection of the EVNB pin input. 	\$026	\$0

Table 7 Internal Registers of H4344/H4318/H4359/H4369 Used in Example (cont)

Register	Description	RAM Address	Setting
SSR1	System Clock Selection Register 1 Selects the system clock oscillation frequency, subsystem clock frequency division, and, in stop mode, the subsystem clock oscillation. <ul style="list-style-type: none">• When SSR11 = "0", the system clock oscillation frequency is set to 0.4 to 1 MHz.• When SSR11 = "1", the system clock oscillation frequency is set to 1.6 to 5 MHz. Note: Applicable only to H4369	\$027	\$2
DCR0	Data Control Register R0 Controls the ON/OFF state of the R0 port output buffer. <ul style="list-style-type: none">• When DCR03 = "0", the R0₃ pin output buffer is set OFF and output set to high impedance.• When DCR03 = "1", the R0₃ pin output buffer is set ON and the value in the corresponding PDR is output.	\$030	\$8

b. Table 8 describes the internal registers used in the H4889.

Table 8 Internal Registers Used in H4889

Register	Function	RAM Address	Setting
IE	Interrupt Enable Flag Controls whether interrupts are received by the CPU. <ul style="list-style-type: none"> When IE = "0", CPU interrupt reception is disabled. When IE = "1", CPU interrupt reception is enabled. 	0, \$000	1
RSP	Reset Stack Pointer Clearing RSP to "0" initializes the stack pointer.	1, \$000	0
IFTB	Timer B Interrupt Request Flag Reflects the existence of a timer B interrupt request. <ul style="list-style-type: none"> When IFTB = "0", no timer B interrupt is requested. When IFTB = "1", a timer B interrupt is requested. 	2, \$002	0
IMTB	Timer B Interrupt Mask This bit masks IFTB. <ul style="list-style-type: none"> When IMTB = "0", IFTB is enabled. When IMTB = "1", IFTB is masked. 	3, \$002	0
IFTC	Timer C Interrupt Request Flag Reflects the existence of a timer C interrupt request. <ul style="list-style-type: none"> When IFTC = "0", no timer C interrupt is requested. When IFTC = "1", a timer C interrupt is requested. 	0, \$003	0
IMTC	Timer C Interrupt Mask This bit masks IFTC. <ul style="list-style-type: none"> When IMTC = "0", IFTC is enabled. When IMTC = "1", IFTC is masked. 	1, \$003	1
SSR	System Clock Selection Register Selects the system clock oscillation frequency, subsystem clock frequency division, the subsystem clock oscillation, and the system clock division ratio for stop mode. <ul style="list-style-type: none"> When SSR1 = "0", the system clock oscillation frequency is set to 0.4 to 1.0 MHz. When SSR1 = "1", the system clock oscillation frequency is set to 1.6 to 4.5 MHz. 	\$004	\$2

Table 8 Internal Registers Used in H4889 (cont)

Register	Function	RAM Address	Setting
PMR2	Port Mode Register 2 Bit 0 switches R1 ₀ /EVNB pin functions, bit 1 switches R1 ₁ /EVND pin functions, bit 2 switches R1 ₂ /BUZZ pin functions, and bit 3 switches R1 ₃ /TOB pin functions. <ul style="list-style-type: none">When PMR2 = \$0, R1₀, R1₁, R1₂ and R1₃ pins are selected.	\$00A	\$0
TMB1	Timer Mode Register B1 TMB13 selects timer B functions, TMB12 to TMB10 select the operating clock. <ul style="list-style-type: none">When TMB13 = "1", TMB12 = "1", TMB11 = "0" and TMB10 = "1", timer B has reload timer functions, and the operating clock is set to the system clock divided by 4.	\$010	\$D
TMB2	Timer Mode Register B2 Selects timer B output mode and EVNB pin input detection edge. <ul style="list-style-type: none">When TMB22 = "0", timer B output is set to a toggle waveform.When TMB22 = "1", timer B output is set for PWM output.When TMB21 = "0" and TMB20 = "0", there is no EVNB pin input edge detection.	\$011	\$0
TWBL	Timer Write Register BL Sets the lower digit of the TCB reload value.	\$012	\$0
TWBU	Timer Write Register BU Sets the upper digit of the TCB reload value.	\$013	\$0
TMC1	Timer Mode Register C1 Selects timer C functions and operating clock. <ul style="list-style-type: none">When TMC13 = "1", TMC12 = "0", TMC11 = "0", and TMC10 = "0", timer C functions as a reload timer, and the operating clock is set to the system clock divided by 2048.	\$014	\$8
TWCL	Timer Write Register CL Sets the lower digit of the TCC reload value.	\$016	\$0
TWCU	Timer Write Register CU Sets the upper digit of the TCC reload value.	\$017	\$0

Table 8 Internal Registers Used in H4889 (cont)

Register	Function	RAM Address	Setting
DCR1	Data Control Register R1 Controls the ON/OFF state of the R1 port output buffer. <ul style="list-style-type: none"> When DCR12 = "0", the R1₂ pin output buffer is set OFF and the output is set to high impedance. When DCR12 = "1", the R1₂ pin output buffer is set ON and the value of the corresponding PDR is output. 	\$035	\$4

4. Description of RAM

Table 9 shows the RAM used in this example task.

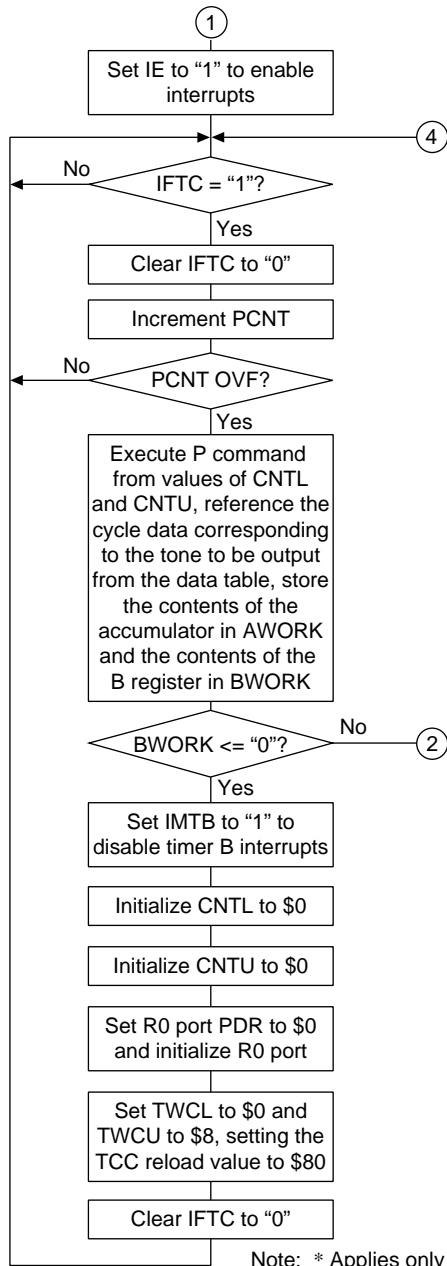
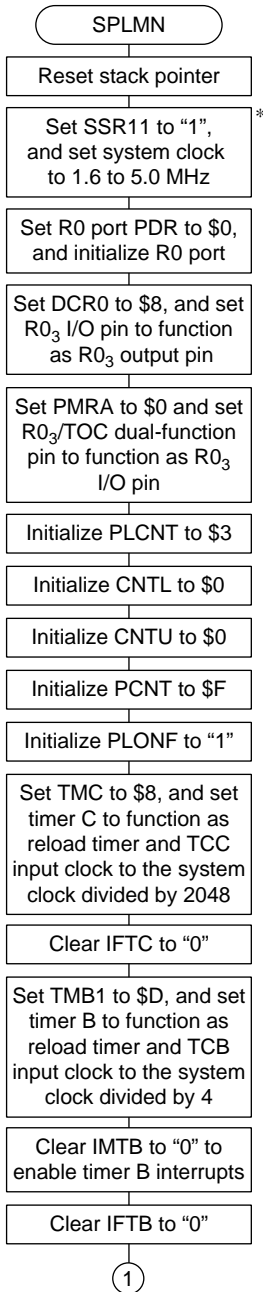
Table 9 Used RAM

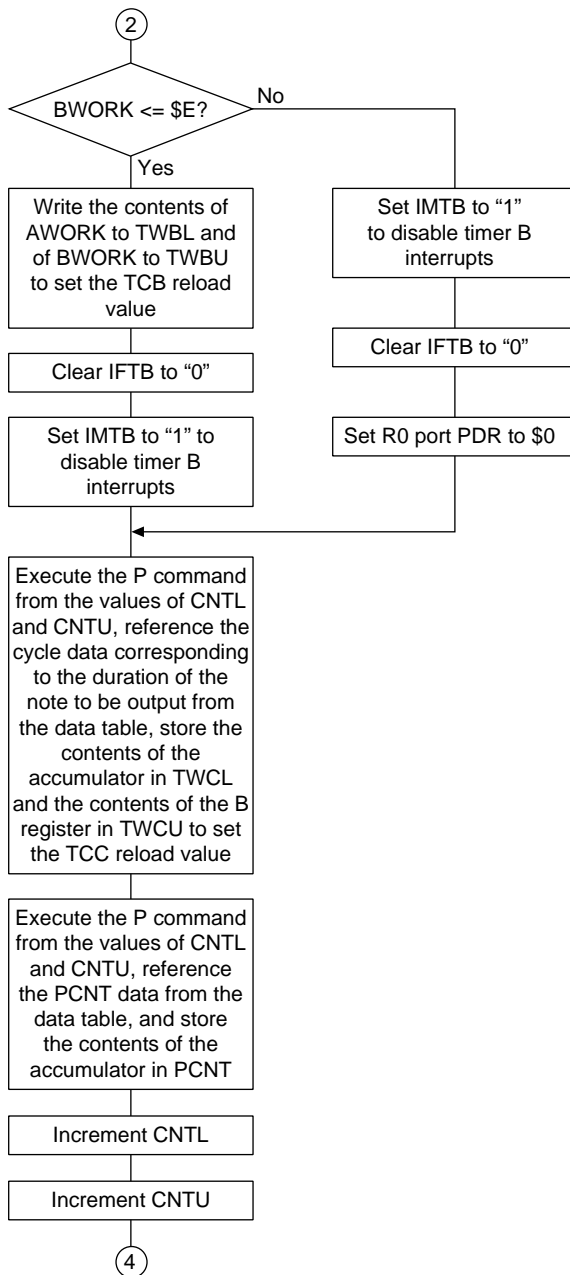
Label	Function	RAM Address	Module
AESC	Stores the contents of the accumulator during timer B interrupt processing.	\$040	SPLINT
BESC	Stores the contents of the B register during timer B interrupt processing.	\$041	SPLINT
PLCNT	This counter controls the High/Low output when outputting a pulse from the R0 ₃ /R1 ₂ pin.	\$090	SPLMN, SPLINT
PLONF	This flag controls the enabling/disabling of pulse output.	0, \$091	SPLMN, SPLINT
CNTL	Stores the contents of the accumulator used for specifying the address when executing a pattern command.	\$093	SPLMN
CNTU	Stores the contents of the B register used for specifying the address when executing a pattern command.	\$094	SPLMN
PCNT	This counter controls the number of times a pulse of a given frequency is output.	\$095	SPLMN
AWORK	Temporarily stores the contents of the accumulator during processing of the main routine.	\$097	SPLMN
BWORK	Temporarily stores the contents of the B register during processing of the main routine.	\$098	SPLMN

Flow charts

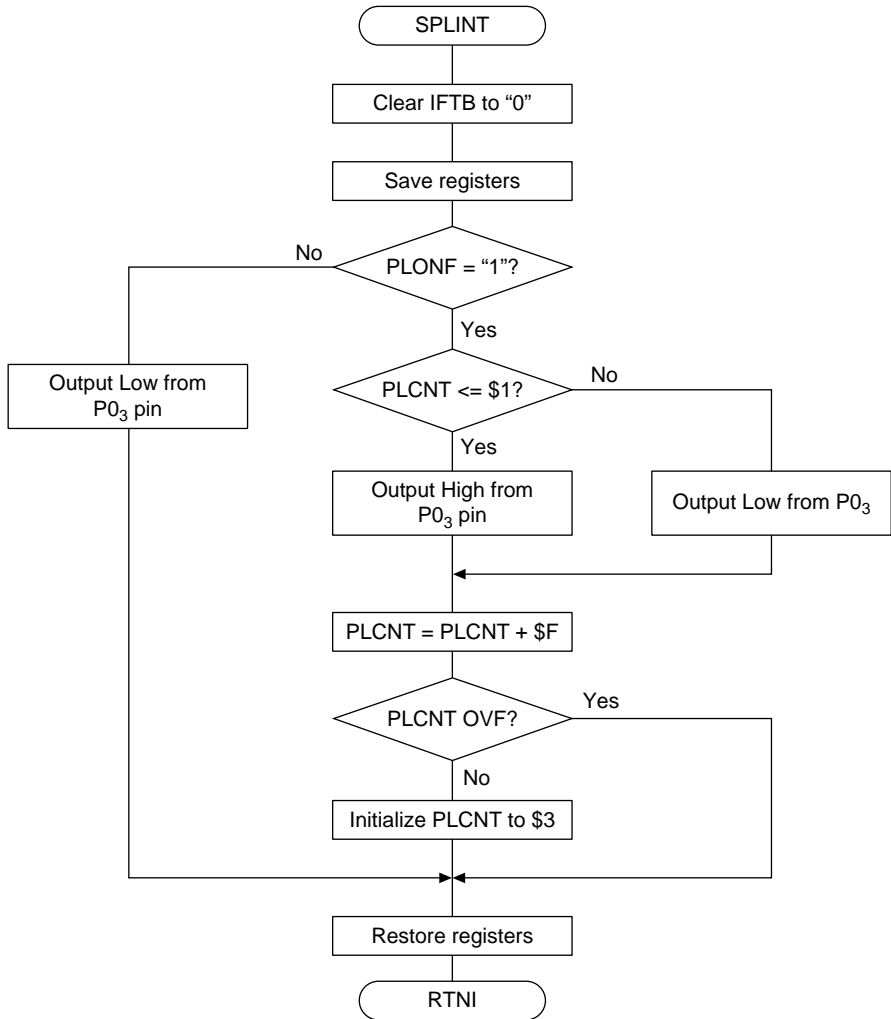
1. H4344/H4318/H4359/H4369

a. Main Routine



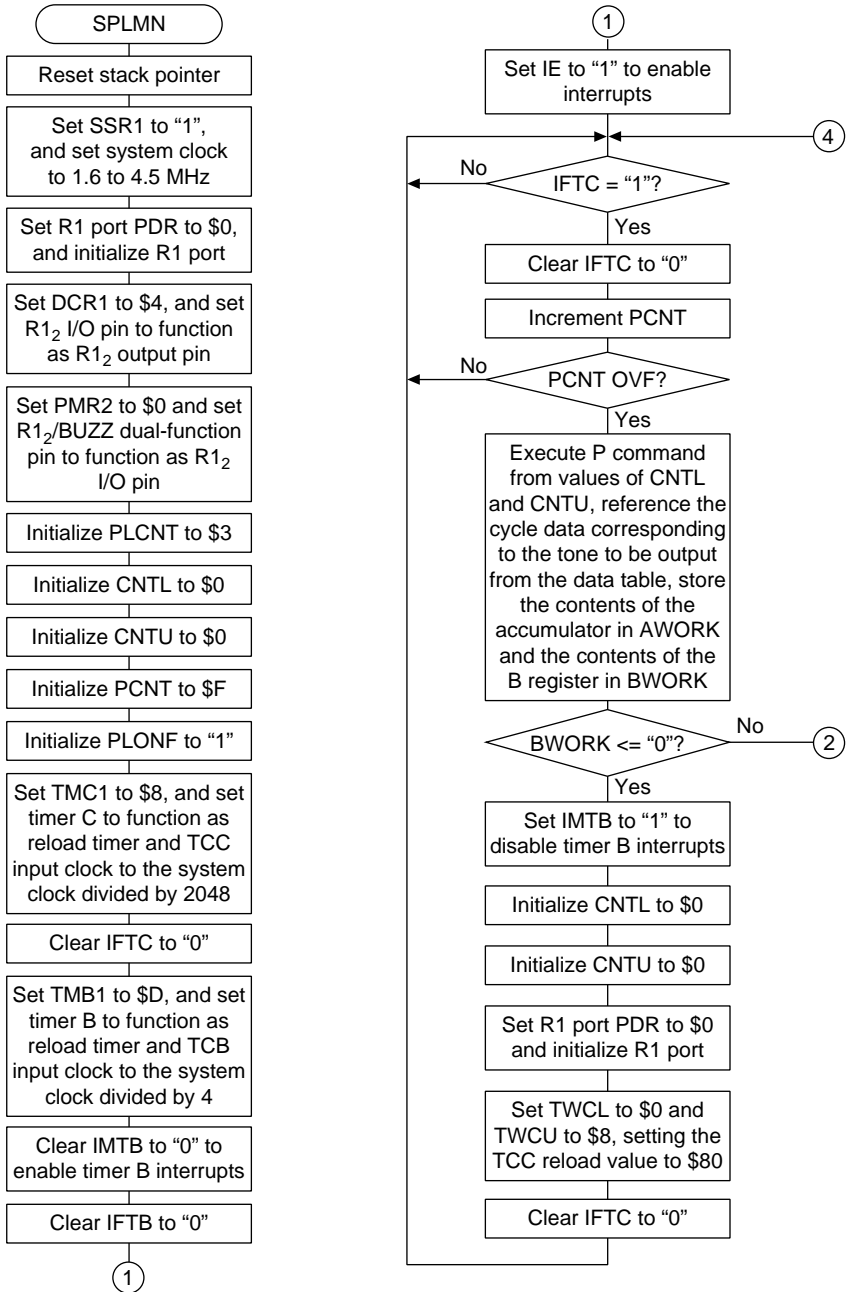


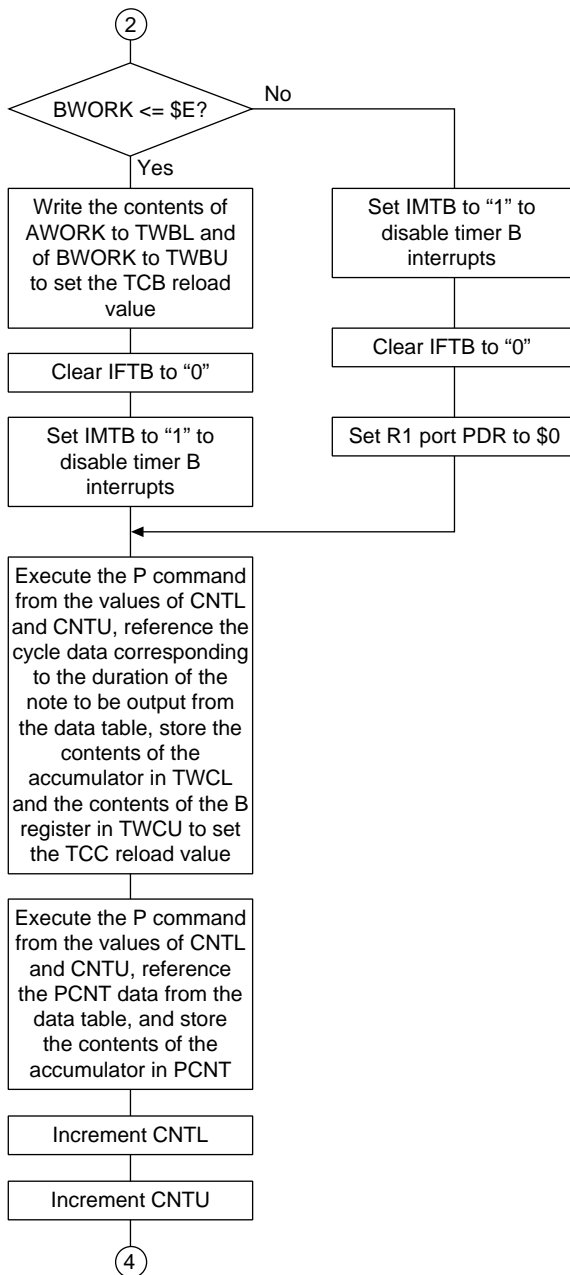
b. Timer B Interrupt Processing Routine



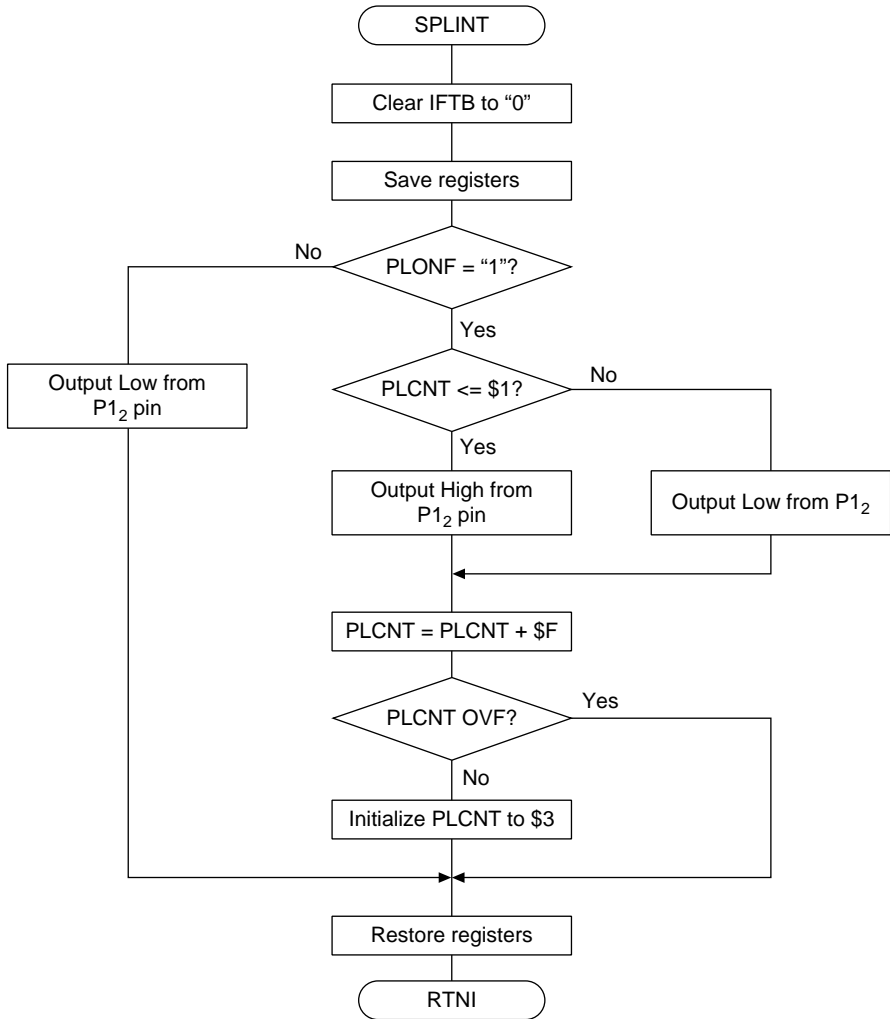
2. H4889

a. Main Routine





b. Timer B Interrupt Processing Routine



Program Listing

1. H4344

```
*****
*
*           HMCS400 Series Application Note
*
*           'Sound Play
*           - Minuet : J.S.Bach'
*
*           MCU : H4344
*
*           External Clock : 4MHz
*           Internal Clock : 1MHz
*           Sub Clock      : 32.768kHz
*
*****
*
*****
*           Symbol Definition
*****
*
IE          equ      0,$000      Interrupt Enable Flag
RSP         equ      1,$000      Reset Stack Pointer
IF0         equ      2,$000      INT0 Interrupt Request Flag
IM0         equ      3,$000      INT0 Interrupt Mask
*
IFTB        equ      0,$002      Timer B Interrupt Request Flag
IMTB        equ      1,$002      Timer B Interrupt Mask
IFTC        equ      2,$002      Timer C Interrupt Request Flag
IMTC        equ      3,$002      Timer C Interrupt Mask
*
IFAD        equ      0,$003      A/D Converter Interrupt Request Flag
IMAD        equ      1,$003      A/D Converter Interrupt Mask
IFS         equ      2,$003      Serial Interrupt Request Flag
IMS         equ      3,$003      Serial Interrupt Mask
*
PMRA        equ      $004        Port Mode Register
SMR         equ      $005        Serial Mode Register
SRL         equ      $006        Serial Data Register L
SRU         equ      $007        Serial Data Register U
*
TMB1        equ      $009        Timer Mode Register B1
TRBL        equ      $00A        Timer Read Register BL
TWBL        equ      $00A        Timer Write Register BL
TRBU        equ      $00B        Timer Read Register BU
TWBU        equ      $00B        Timer Write Register BU
MIS         equ      $00C        Miscellaneous Register
TMC         equ      $00D        Timer Mode Register C
TRCL        equ      $00E        Timer Read Register CL
```

```

TWCL    equ    $00E    Timer Write Register CL
TRCU    equ    $00F    Timer Read Register CU
TWCU    equ    $00F    Timer Write Register CU
ACR     equ    $016    A/D Channel Register
ADRL    equ    $017    A/D Data Register L
ADRU    equ    $018    A/D Data Register U
AMR1    equ    $019    A/D Mode Register 1
AMR2    equ    $01A    A/D Mode Register 2
*
WDON    equ    1,$020  Watchdog on Flag
ADSF    equ    2,$020  A/D Start Flag
*
IAOF    equ    2,$021  IAD off Flag
RAME    equ    3,$021  RAM Enable Flag
*
PMRB    equ    $024    Port Mode Register B
PMRC    equ    $025    Port Mode Register C
TMB2    equ    $026    Timer Mode Register B2
*
DCD0    equ    $02C    D Port Data Control Register 0
DCD1    equ    $02D    D Port Data Control Register 1
*
DCR0    equ    $030    R Port Data Control Register 0
DCR1    equ    $031    R Port Data Control Register 1
DCR2    equ    $032    R Port Data Control Register 2
DCR3    equ    $033    R Port Data Control Register 3
*
*****
*          RAM ALLOCATION
*****
*
AESC    equ    $040    Accumulator Escape
BESC    equ    $041    B Register Escape
*
PLCNT   equ    $090    Pulse Counter
*
PLFLG1  equ    $091    Pulse Flag 1
PLONF   equ    0,PLFLG1 Pulse Output Enable Flag
*
CNTL    equ    $093    Lower Counter
CNTU    equ    $094    Upper Counter
PCNT    equ    $095    Period Counter
AWORK   equ    $096    Accumulator Work RAM Area
BWORK   equ    $097    B Register Work RAM Area
*
*****
*          Vector Address
*****
*
        org    $0000
*

```

```

JMPL   SPLMN   Reset Interrupt
JMPL   SPLMN   INT0 Interrupt
*
*
org    $0008
*
JMPL   SPLINT  Timer B Interrupt
JMPL   SPLMN   Timer C Interrupt
JMPL   SPLMN   A/D Converter Interrupt
JMPL   SPLMN   Serial Interrupt
*
*****
*      Main Program
*****
*
org    $1000
*
SPLMN  REMD    RSP      Reset Stack Pointer
*
LAI    0
LRA    0      Initialize R0 Port PDR
LMID   8,DCR0  Initialize R03 Output Terminal Function
LMID   0,PMRA  Initialize R03 Input/Output Terminal Function
*
LMID   3,PLCNT Initialize Pulse Counter
LMID   0,CNTL  Initialize Lower Counter
LMID   0,CNTU  Initialize Upper Counter
LMID   $F,PCNT Initialize Period Counter
SEMD   PLONF   Initialize Pulse Output Enable Flag
*
LMID   8,TMC   Initialize Timer C Function & Input Clock Period
REMD   IFTC   Clear IFTC to 0
*
LMID   $D,TMB1 Initialize Timer B Function & Input Clock Period
LMID   0,TMB2 Initialize Timer B Function
*
SEMD   IMTB   Timer B Interrupt Disable
REMD   IFTB   Clear IFTB to 0
*
SEMD   IE     All Interrupt Enable
*
SPLMN00 TMD     IFTC     IFTC = "1" ?
        BRS    SPLMN10 Yes. Branch to SPLMN10
        BRS    SPLMN00 No. Branch to SPLMN00
*
REMD   IFTC   Clear IFTC to 0
LMID   9,TWCL Set TCC Reload Value Lower
LMID   0,TWCU Set TCC Reload Value Upper
*
SPLMN05 TMD     IFTC     IFTC = "1" ?
        BRS    SPLMN10 Yes. Branch to SPLMN10
        SEMD   IMTB   Timer B Interrupt Disable

```


	REMD	IFTB	Clear IFTB to 0
	LAI	0	
	LRA	0	Sound off
	BRS	SPLMN05	Branch to SPLMN05
*			
SPLMN10	REMD	IFTC	Clear IFTC to 0
	LAMD	PCNT	Load PCNT
	AI	1	Increment PCNT
	BRS	SPLMN40	PCNT Overflow ? Yes. Branch to SPLMN40
	LMAD	PCNT	No. Save PCNT
	BRS	SPLMN00	Branch to SPLMN00
*			
SPLMN40	LAMD	CNTU	Load CNTL
	LBA		
	LAMD	CNTL	Load CNTU
	P	2	Scale Data Pattern Generation
	LMAD	AWORK	Save Scale Lower Data
	LAB		
	LMAD	BWORK	Save Scale Upper Data
	ALEI	0	Scale Upper Data <= \$0 ? End Sound Play ?
	BRS	SPLMN90	Yes. Branch to SPLMN90
	ALEI	\$E	Scale Upper Data <= \$E ?
	BRS	SPLMN20	Yes. Branch to SPLMN20
	SEMD	IMTB	Timer B Interrupt Disable
	REMD	IFTB	Clear IFTB to 0
	LAI	0	
	LRA	0	R03 Output Terminal is "Low" Output
	BRS	SPLMN30	Branch to SPLMN30
*			
SPLMN20	LAMD	AWORK	Load AWORK
	LMAD	TWBL	Set TCB Reload Value Lower to Scale Data
	LAMD	BWORK	Load BWORK
	LMAD	TWBU	Set TCB Reload Value Upper to Scale Data
	REMD	IFTB	Clear IFTB to 0
	REMD	IMTB	Timer B Interrupt Enable
*			
SPLMN30	LAMD	CNTU	Load Upper Counter
	LBA		
	LAMD	CNTL	Load Lower Counter
	P	3	Time Period Data Pattern Generation
	LMAD	TWCL	Set TCC Reload Value Lower to Time Period Lower Data
	LAB		
	LMAD	TWCU	Set TCC Reload Value Upper to Time Period Upper Data
*			
	LAMD	CNTU	Load Upper Counter
	LBA		
	LAMD	CNTL	Load Lower Counter
	P	4	Time Counter Data Pattern Generation
	LMAD	PCNT	Set PCNT to Time Counter Data
*			
	SEC		Set Carry Flag at 1

```

LAI      0
AMCD    CNTL      Increment Lower Counter
LMAD    CNTL      Save Lower Counter
LAI      0
AMCD    CNTU      If CNTL Overflow, Increment Upper Counter
LMAD    CNTU      Save Upper Counter
BR      *+1
BRS     SPLMN00   Branch to SPLMN00
*
SPLMN90 SEMD      IMTB      Timer B Interrupt Disable
        LMID      0,CNTL    Initialize Lower Counter
        LMID      0,CNTU    Initialize Upper Counter
        LAI      0
        LRA      0          Initialize R0 Port PDR
        LMID      0,TWCL    Initialize TCC Reload Value Lower
        LMID      8,TWCU    Initialize TCC Reload Value Upper
        REMD     IFTC      Clear IFTC to 0
        BRS     SPLMN00   Branch to SPLMN00
*
*****
*       Timer B Interrupt Process
*       ---Pulse Output Routine---
*****
*
SPLINT  REMD      IFTB      Clear IFTB to 0
*
        LMAD     AESC      Store Accumulator
        LAB
        LMAD     BESC      Store B Register
*
        TMD     PLONF     Pulse Enable Flag = "1" ?
        BRS     PLI00     Yes. Branch to PLI00
        LAI     0         No. Stop Output Pulse
        LRA     0         R03 Output Terminal is "Low" Output
        BRS     PLI99     Branch to PLI99
*
PLI00   LAMD     PLCNT     Load Pulse Counter Value
        LBA
        ALEI    1         PLCNT <= $1 ? Is R03 Output Terminal "High" Output ?
        BRS     PLI10     Yes. Branch to PLI10
        LAI     0         No. R03 Output Terminal is "Low" Output
        BRS     PLI20     Branch to PLI20
PLI10   LAI     8
PLI20   LRA     0         R03 Output Terminal is "High" Output
        LAB
        AI      $F       PLCNT + $F <= $F ? Pulse Counter = $0 ?
        BRS     PLI30     No. Branch to PLI30
        LAI     3         Yes. Pulse Counter Initialize
PLI30   LMAD     PLCNT     Save Pulse Counter Value
*
PLI99   LAMD     BESC      Restore B Register

```

LBA
LAMD AESC Restore Accumulator

*

RTNI Return from Interrupt

*

* Scale Data

*

ORG \$0200

*

*** 1st Cycle

*

dc \$1AB 'G' Data. TCB Reload Value = \$AB
dc \$17F 'C' Data. TCB Reload Value = \$7F
dc \$18E 'D' Data. TCB Reload Value = \$8E
dc \$19B 'E' Data. TCB Reload Value = \$9B
dc \$1A1 'F' Data. TCB Reload Value = \$A1

*

dc \$1AB 'G' Data. TCB Reload Value = \$AB
dc \$17F 'C' Data. TCB Reload Value = \$7F
dc \$1FF ' ' Data. TCB Reload Value = \$FF
dc \$17F 'C' Data. TCB Reload Value = \$7F

*

dc \$1B4 'A' Data. TCB Reload Value = \$B4
dc \$1A1 'F' Data. TCB Reload Value = \$A1
dc \$1AB 'G' Data. TCB Reload Value = \$AB
dc \$1B4 'A' Data. TCB Reload Value = \$B4
dc \$1BD 'B' Data. TCB Reload Value = \$BD

*

dc \$1C1 'C' Data. TCB Reload Value = \$C1
dc \$17F 'C' Data. TCB Reload Value = \$7F
dc \$1FF ' ' Data. TCB Reload Value = \$FF
dc \$17F 'C' Data. TCB Reload Value = \$7F

*

dc \$1A1 'F' Data. TCB Reload Value = \$A1
dc \$1AB 'G' Data. TCB Reload Value = \$AB
dc \$1A1 'F' Data. TCB Reload Value = \$A1
dc \$19B 'E' Data. TCB Reload Value = \$9B
dc \$18E 'D' Data. TCB Reload Value = \$8E

*

dc \$19B 'E' Data. TCB Reload Value = \$9B
dc \$1A1 'F' Data. TCB Reload Value = \$A1
dc \$19B 'E' Data. TCB Reload Value = \$9B
dc \$18E 'D' Data. TCB Reload Value = \$8E
dc \$17F 'C' Data. TCB Reload Value = \$7F

*

dc \$17A 'B' Data. TCB Reload Value = \$7A
dc \$17F 'C' Data. TCB Reload Value = \$7F
dc \$18E 'D' Data. TCB Reload Value = \$8E
dc \$19B 'E' Data. TCB Reload Value = \$9B

```

    dc      $17F      'C' Data. TCB Reload Value = $7F
*
    dc      $18E      'D' Data. TCB Reload Value = $8E
*
*** 2nd Cycle
*
    dc      $1AB      'G' Data. TCB Reload Value = $AB
    dc      $17F      'C' Data. TCB Reload Value = $7F
    dc      $18E      'D' Data. TCB Reload Value = $8E
    dc      $19B      'E' Data. TCB Reload Value = $9B
    dc      $1A1      'F' Data. TCB Reload Value = $A1
*
    dc      $1AB      'G' Data. TCB Reload Value = $AB
    dc      $17F      'C' Data. TCB Reload Value = $7F
    dc      $1FF      ' ' Data. TCB Reload Value = $FF
    dc      $17F      'C' Data. TCB Reload Value = $7F
*
    dc      $1B4      'A' Data. TCB Reload Value = $B4
    dc      $1A1      'F' Data. TCB Reload Value = $A1
    dc      $1AB      'G' Data. TCB Reload Value = $AB
    dc      $1B4      'A' Data. TCB Reload Value = $B4
    dc      $1BD      'B' Data. TCB Reload Value = $BD
*
    dc      $1C1      'C' Data. TCB Reload Value = $C1
    dc      $17F      'C' Data. TCB Reload Value = $7F
    dc      $1FF      ' ' Data. TCB Reload Value = $FF
    dc      $17F      'C' Data. TCB Reload Value = $7F
*
    dc      $1A1      'F' Data. TCB Reload Value = $A1
    dc      $1AB      'G' Data. TCB Reload Value = $AB
    dc      $1A1      'F' Data. TCB Reload Value = $A1
    dc      $19B      'E' Data. TCB Reload Value = $9B
    dc      $18E      'D' Data. TCB Reload Value = $8E
*
    dc      $19B      'E' Data. TCB Reload Value = $9B
    dc      $1A1      'F' Data. TCB Reload Value = $A1
    dc      $19B      'E' Data. TCB Reload Value = $9B
    dc      $18E      'D' Data. TCB Reload Value = $8E
    dc      $17F      'C' Data. TCB Reload Value = $7F
*
    dc      $18E      'D' Data. TCB Reload Value = $8E
    dc      $19B      'E' Data. TCB Reload Value = $9B
    dc      $18E      'D' Data. TCB Reload Value = $8E
    dc      $17F      'C' Data. TCB Reload Value = $7F
    dc      $17A      'B' Data. TCB Reload Value = $7A
*
    dc      $17F      'C' Data. TCB Reload Value = $7F
    dc      $1FF      ' ' Data. TCB Reload Value = $FF
*
    dc      $100      ' ' Data. TCB Reload Value = $00
*

```

* Time Period Data

* org \$0300

*** 1st Cycle

*
 dc \$138 'G' Time Period Data. TCC Reload Value = \$38
 dc \$19C 'C' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'D' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'E' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'F' Time Period Data. TCC Reload Value = \$9C

*
 dc \$138 'G' Time Period Data. TCC Reload Value = \$38
 dc \$16A 'C' Time Period Data. TCC Reload Value = \$6A
 dc \$1CE ' ' Time Period Data. TCC Reload Value = \$CE
 dc \$138 'C' Time Period Data. TCC Reload Value = \$38

*
 dc \$138 'A' Time Period Data. TCC Reload Value = \$38
 dc \$19C 'F' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'G' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'A' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'B' Time Period Data. TCC Reload Value = \$9C

*
 dc \$138 'C' Time Period Data. TCC Reload Value = \$38
 dc \$16A 'C' Time Period Data. TCC Reload Value = \$6A
 dc \$1CE ' ' Time Period Data. TCC Reload Value = \$CE
 dc \$138 'C' Time Period Data. TCC Reload Value = \$38

*
 dc \$138 'F' Time Period Data. TCC Reload Value = \$38
 dc \$19C 'G' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'F' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'E' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'D' Time Period Data. TCC Reload Value = \$9C

*
 dc \$138 'E' Time Period Data. TCC Reload Value = \$38
 dc \$19C 'F' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'E' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'D' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'C' Time Period Data. TCC Reload Value = \$9C

*
 dc \$138 'B' Time Period Data. TCC Reload Value = \$38
 dc \$19C 'C' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'D' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'E' Time Period Data. TCC Reload Value = \$9C
 dc \$19C 'C' Time Period Data. TCC Reload Value = \$9C

*
 dc \$138 'D' Time Period Data. TCC Reload Value = \$38

*** 2nd Cycle

```

*
dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38

```

```

*
dc      $138      'A' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38

```

```

*
dc      $138      'F' Time Period Data. TCC Reload Value = $38
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'E' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'D' Time Period Data. TCC Reload Value = $38
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $138      ' ' Time Period Data. TCC Reload Value = $38

```

```

*****

```

```

*      Times Counter Data

```

```

*****

```

```

*      org      $0400

```

```

*
*** 1st Cycle

```

*
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F

*
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'B' Time Counter Data. PCNT = \$F

*
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F

*
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'B' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10D 'D' Time Counter Data. PCNT = \$D

*
*** 2nd Cycle
*

dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F

*

```

dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'B' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10D      'D' Time Counter Data. PCNT = $D

```


*** 2nd Cycle

dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F

*
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'B' Time Counter Data. PCNT = \$F

*
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F

*
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'B' Time Counter Data. PCNT = \$F

*
dc \$10E 'C' Time Counter Data. PCNT = \$E
dc \$10F ' ' Time Counter Data. PCNT = \$F
end

2. H4318/H4359

```
*****
*
*      HMCS400 Series Application Note
*
*      'Sound Play
*      - Minuet : J.S.Bach'
*
*      MCU : H4318/H4359
*
*      External Clock : 4MHz
*      Internal Clock : 1MHz
*      Sub Clock      : 32.768kHz
*
*****
*
*****
*
*      Symbol Definition
*****
*
IE      equ      0,$000      Interrupt Enable Flag
RSP     equ      1,$000      Reset Stack Pointer
IF0     equ      2,$000      INT0 Interrupt Request Flag
IM0     equ      3,$000      INT0 Interrupt Mask
*
IF1     equ      0,$001      INT1 Interrupt Request Flag
IM1     equ      1,$001      INT1 Interrupt Mask
IFTA    equ      2,$001      Timer A Interrupt Request Flag
IMTA    equ      3,$001      Timer A Interrupt Mask
*
IFTB    equ      0,$002      Timer B Interrupt Request Flag
IMTB    equ      1,$002      Timer B Interrupt Mask
IFTC    equ      2,$002      Timer C Interrupt Request Flag
IMTC    equ      3,$002      Timer C Interrupt Mask
*
IFAD    equ      0,$003      A/D Converter Interrupt Request Flag
IMAD    equ      1,$003      A/D Converter Interrupt Mask
IFS     equ      2,$003      Serial Interrupt Request Flag
IMS     equ      3,$003      Serial Interrupt Mask
*
PMRA    equ      $004      Port Mode Register
SMR     equ      $005      Serial Mode Register
SRL     equ      $006      Serial Data Register L
SRU     equ      $007      Serial Data Register U
TMA     equ      $008      Timer Mode Register A
TMB1    equ      $009      Timer Mode Register B1
TRBL    equ      $00A      Timer Read Register BL
TWBL    equ      $00A      Timer Write Register BL
TRBU    equ      $00B      Timer Read Register BU
TWBU    equ      $00B      Timer Write Register BU
```

```

MIS      equ      $00C      Miscellaneous Register
TMC      equ      $00D      Timer Mode Register C
TRCL     equ      $00E      Timer Read Register CL
TWCL     equ      $00E      Timer Write Register CL
TRCU     equ      $00F      Timer Read Register CU
TWCUC    equ      $00F      Timer Write Register CU
ACR      equ      $016      A/D Channel Register
ADRL     equ      $017      A/D Data Register L
ADRU     equ      $018      A/D Data Register U
AMR1     equ      $019      A/D Mode Register 1
AMR2     equ      $01A      A/D Mode Register 2
*
WDON     equ      1,$020     Watchdog on Flag
ADSF     equ      2,$020     A/D Start Flag
*
ICSF     equ      0,$021     Input Capture Status Flag
ICEF     equ      1,$021     Input Capture Error Flag
IAOF     equ      2,$021     IAD off Flag
RAME     equ      3,$021     RAM Enable Flag
*
PMRB     equ      $024      Port Mode Register B
PMRC     equ      $025      Port Mode Register C
TMB2     equ      $026      Timer Mode Register B2
DCD0     equ      $02C      D Port Data Control Register 0
DCD1     equ      $02D      D Port Data Control Register 1
DCD2     equ      $02E      D Port Data Control Register 2
DCR0     equ      $030      R Port Data Control Register 0
DCR1     equ      $031      R Port Data Control Register 1
DCR2     equ      $032      R Port Data Control Register 2
DCR3     equ      $033      R Port Data Control Register 3
DCR4     equ      $034      R Port Data Control Register 4
DCR8     equ      $038      R Port Data Control Register 8
*
*****
*          RAM ALLOCATION
*****
*
AESC     equ      $040      Accumulator Escape
BESC     equ      $041      B Register Escape
*
PLCNT    equ      $090      Pulse Counter
*
PLFLG1   equ      $091      Pulse Flag 1
PLONF    equ      0,PLFLG1  Pulse Output Enable Flag
*
CNTL     equ      $093      Lower Counter
CNTU     equ      $094      Upper Counter
PCNT     equ      $095      Period Counter
AWORK    equ      $096      Accumulator Work RAM Area
BWORK    equ      $097      B Register Work RAM Area
*

```

* Vector Address

```

*
      org      $0000
*
      JMPL    SPLMN    Reset Interrupt
      JMPL    SPLMN    INT0 Interrupt
      JMPL    SPLMN    INT1 Interrupt
      JMPL    SPLMN    Timer A Interrupt
      JMPL    SPLINT   Timer B Interrupt
      JMPL    SPLMN    Timer C Interrupt
      JMPL    SPLMN    A/D Converter Interrupt
      JMPL    SPLMN    Serial Interrupt

```

*

* Main Program

```

*
      org      $1000
*
SPLMN  REMD    RSP      Reset Stack Pointer
*
      LAI     0
      LRA     0          Initialize R0 Port PDR
      LMID    8,DCR0    Initialize R03 Output Terminal Function
      LMID    0,PMRA    Initialize R03 Input/Output Terminal Function
*
      LMID    3,PLCNT   Initialize Pulse Counter
      LMID    0,CNTL   Initialize Lower Counter
      LMID    0,CNTU   Initialize Upper Counter
      LMID    $F,PCNT  Initialize Period Counter
      SEMD    PLONF    Initialize Pulse Output Enable Flag
*
      LMID    8,TMC     Initialize Timer C Function & Input Clock Period
      REMD    IFTC     Clear IFTC to 0
*
      LMID    $D,TMB1  Initialize Timer B Function & Input Clock Period
      LMID    0,TMB2  Initialize Timer B Function
*
      SEMD    IMTB     Timer B Interrupt Disable
      REMD    IFTB     Clear IFTB to 0
*
      SEMD    IE       All Interrupt Enable
*
SPLMN00 TMD      IFTC     IFTC = "1" ?
      BRS    SPLMN10  Yes. Branch to SPLMN10
      BRS    SPLMN00  No. Branch to SPLMN00
*
      REMD    IFTC     Clear IFTC to 0
      LMID    9,TWCL   Set TCC Reload Value Lower

```

```

      LMID      0,TWCU      Set TCC Reload Value Upper
*
SPLMN05  TMD      IFTC      IFTC = "1" ?
          BRS      SPLMN10   Yes. Branch to SPLMN10
          SEMD     IMTB      Timer B Interrupt Disable
          REMD     IFTB      Clear IFTB to 0
          LAI      0
          LRA      0          Sound off
          BRS      SPLMN05   Branch to SPLMN05
*
SPLMN10  REMD     IFTC      Clear IFTC to 0
          LAMD     PCNT      Load PCNT
          AI       1          Increment PCNT
          BRS      SPLMN40   PCNT Overflow ? Yes. Branch to SPLMN40
          LMAD     PCNT      No. Save PCNT
          BRS      SPLMN00   Branch to SPLMN00
*
SPLMN40  LAMD     CNTU      Load CNTL
          LBA
          LAMD     CNTL      Load CNTU
          P        2          Scale Data Pattern Generation
          LMAD     AWORK     Save Scale Lower Data
          LAB
          LMAD     BWORK     Save Scale Upper Data
          ALEI     0          Scale Upper Data <= $0 ? End Sound Play ?
          BRS      SPLMN90   Yes. Branch to SPLMN90
          ALEI     $E        Scale Upper Data <= $E ?
          BRS      SPLMN20   Yes. Branch to SPLMN20
          SEMD     IMTB      Timer B Interrupt Disable
          REMD     IFTB      Clear IFTB to 0
          LAI      0
          LRA      0          R03 Output Terminal is "Low" Output
          BRS      SPLMN30   Branch to SPLMN30
*
SPLMN20  LAMD     AWORK     Load AWORK
          LMAD     TWBL      Set TCB Reload Value Lower to Scale Data
          LAMD     BWORK     Load BWORK
          LMAD     TWBU      Set TCB Reload Value Upper to Scale Data
          REMD     IFTB      Clear IFTB to 0
          REMD     IMTB      Timer B Interrupt Enable
*
SPLMN30  LAMD     CNTU      Load Upper Counter
          LBA
          LAMD     CNTL      Load Lower Counter
          P        3          Time Period Data Pattern Generation
          LMAD     TWCL      Set TCC Reload Value Lower to Time Period Lower Data
          LAB
          LMAD     TWCU      Set TCC Reload Value Upper to Time Period Upper Data
*
          LAMD     CNTU      Load Upper Counter
          LBA

```

```

LAMD  CNTL  Load Lower Counter
P      4      Time Counter Data Pattern Generation
LMAD  PCNT  Set PCNT to Time Counter Data
*
SEC                    Set Carry Flag at 1
LAI    0
AMCD   CNTL  Increment Lower Counter
LMAD   CNTL  Save Lower Counter
LAI    0
AMCD   CNTU  If CNTL Overflow, Increment Upper Counter
LMAD   CNTU  Save Upper Counter
BR     *+1
BRS    SPLMN00  Branch to SPLMN00
*
SPLMN90  SEMD  IMTB  Timer B Interrupt Disable
          LMID  0,CNTL  Initialize Lower Counter
          LMID  0,CNTU  Initialize Upper Counter
          LAI   0
          LRA   0      Initialize R0 Port PDR
          LMID  0,TWCL  Initialize TCC Reload Value Lower
          LMID  8,TWCU  Initialize TCC Reload Value Upper
          REMD  IFTC  Clear IFTC to 0
          BRS   SPLMN00  Branch to SPLMN00
*
*****
*      Timer B Interrupt Process
*      ---Pulse Output Routine---
*****
*
SPLINT  REMD  IFTB  Clear IFTB to 0
*
          LMAD  AESC  Store Accumulator
          LAB
          LMAD  BESC  Store B Register
*
          TMD  PLONF  Pulse Enable Flag = "1" ?
          BRS  PLI00  Yes. Branch to PLI00
          LAI   0      No. Stop Output Pulse
          LRA   0      R03 Output Terminal is "Low" Output
          BRS  PLI99  Branch to PLI99
*
PLI00   LAMD  PLCNT  Load Pulse Counter Value
          LBA                    Store Pulse Counter Value
          ALEI  1      PLCNT <= $1 ? Is R03 Output Terminal "High" Output ?
          BRS  PLI10  Yes. Branch to PLI10
          LAI   0      No. R03 Output Terminal is "Low" Output
          BRS  PLI20  Branch to PLI20
PLI10   LAI   8
PLI20   LRA   0      R03 Output Terminal is "High" Output
          LAB                    Restore Pulse Counter Value
          AI    $F      PLCNT + $F <= $F ? Pulse Counter = $0 ?

```

```

        BRS      PLI30      No. Branch to PLI30
        LAI      3          Yes. Pulse Counter Initialize
PLI30   LMAD     PLCNT     Save Pulse Counter Value
*
PLI99   LAMD     BESC      Restore B Register
        LBA
        LAMD     AESC      Restore Accumulator
*
        RTNI          Return from Interrupt
*
*****
*      Scale Data
*****
*
        ORG      $0200
*
*** 1st Cycle
*
        dc      $1AB      'G' Data. TCB Reload Value = $AB
        dc      $17F      'C' Data. TCB Reload Value = $7F
        dc      $18E      'D' Data. TCB Reload Value = $8E
        dc      $19B      'E' Data. TCB Reload Value = $9B
        dc      $1A1      'F' Data. TCB Reload Value = $A1
*
        dc      $1AB      'G' Data. TCB Reload Value = $AB
        dc      $17F      'C' Data. TCB Reload Value = $7F
        dc      $1FF      ' ' Data. TCB Reload Value = $FF
        dc      $17F      'C' Data. TCB Reload Value = $7F
*
        dc      $1B4      'A' Data. TCB Reload Value = $B4
        dc      $1A1      'F' Data. TCB Reload Value = $A1
        dc      $1AB      'G' Data. TCB Reload Value = $AB
        dc      $1B4      'A' Data. TCB Reload Value = $B4
        dc      $1BD      'B' Data. TCB Reload Value = $BD
*
        dc      $1C1      'C' Data. TCB Reload Value = $C1
        dc      $17F      'C' Data. TCB Reload Value = $7F
        dc      $1FF      ' ' Data. TCB Reload Value = $FF
        dc      $17F      'C' Data. TCB Reload Value = $7F
*
        dc      $1A1      'F' Data. TCB Reload Value = $A1
        dc      $1AB      'G' Data. TCB Reload Value = $AB
        dc      $1A1      'F' Data. TCB Reload Value = $A1
        dc      $19B      'E' Data. TCB Reload Value = $9B
        dc      $18E      'D' Data. TCB Reload Value = $8E
*
        dc      $19B      'E' Data. TCB Reload Value = $9B
        dc      $1A1      'F' Data. TCB Reload Value = $A1
        dc      $19B      'E' Data. TCB Reload Value = $9B
        dc      $18E      'D' Data. TCB Reload Value = $8E
        dc      $17F      'C' Data. TCB Reload Value = $7F

```

*
 dc \$17A 'B' Data. TCB Reload Value = \$7A
 dc \$17F 'C' Data. TCB Reload Value = \$7F
 dc \$18E 'D' Data. TCB Reload Value = \$8E
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$17F 'C' Data. TCB Reload Value = \$7F

*
 dc \$18E 'D' Data. TCB Reload Value = \$8E

*
 *** 2nd Cycle

*
 dc \$1AB 'G' Data. TCB Reload Value = \$AB
 dc \$17F 'C' Data. TCB Reload Value = \$7F
 dc \$18E 'D' Data. TCB Reload Value = \$8E
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$1A1 'F' Data. TCB Reload Value = \$A1

*
 dc \$1AB 'G' Data. TCB Reload Value = \$AB
 dc \$17F 'C' Data. TCB Reload Value = \$7F
 dc \$1FF ' ' Data. TCB Reload Value = \$FF
 dc \$17F 'C' Data. TCB Reload Value = \$7F

*
 dc \$1B4 'A' Data. TCB Reload Value = \$B4
 dc \$1A1 'F' Data. TCB Reload Value = \$A1
 dc \$1AB 'G' Data. TCB Reload Value = \$AB
 dc \$1B4 'A' Data. TCB Reload Value = \$B4
 dc \$1BD 'B' Data. TCB Reload Value = \$BD

*
 dc \$1C1 'C' Data. TCB Reload Value = \$C1
 dc \$17F 'C' Data. TCB Reload Value = \$7F
 dc \$1FF ' ' Data. TCB Reload Value = \$FF
 dc \$17F 'C' Data. TCB Reload Value = \$7F

*
 dc \$1A1 'F' Data. TCB Reload Value = \$A1
 dc \$1AB 'G' Data. TCB Reload Value = \$AB
 dc \$1A1 'F' Data. TCB Reload Value = \$A1
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$18E 'D' Data. TCB Reload Value = \$8E

*
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$1A1 'F' Data. TCB Reload Value = \$A1
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$18E 'D' Data. TCB Reload Value = \$8E
 dc \$17F 'C' Data. TCB Reload Value = \$7F

*
 dc \$18E 'D' Data. TCB Reload Value = \$8E
 dc \$19B 'E' Data. TCB Reload Value = \$9B
 dc \$18E 'D' Data. TCB Reload Value = \$8E
 dc \$17F 'C' Data. TCB Reload Value = \$7F
 dc \$17A 'B' Data. TCB Reload Value = \$7A

*


```

dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
*
dc      $100      ' ' Data. TCB Reload Value = $00
*

```

* Time Period Data

```

*
org      $0300
*

```

*** 1st Cycle

*

```

dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
*

```

```

dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38
*

```

```

dc      $138      'A' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*

```

```

dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38
*

```

```

dc      $138      'F' Time Period Data. TCC Reload Value = $38
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
*

```

```

dc      $138      'E' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*

```

```

dc      $138      'B' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C

```



```

      dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'D' Time Period Data. TCC Reload Value = $38
*
*** 2nd Cycle
*
      dc      $138      'G' Time Period Data. TCC Reload Value = $38
      dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'G' Time Period Data. TCC Reload Value = $38
      dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
      dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
      dc      $138      'C' Time Period Data. TCC Reload Value = $38
*
      dc      $138      'A' Time Period Data. TCC Reload Value = $38
      dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'C' Time Period Data. TCC Reload Value = $38
      dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
      dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
      dc      $138      'C' Time Period Data. TCC Reload Value = $38
*
      dc      $138      'F' Time Period Data. TCC Reload Value = $38
      dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'E' Time Period Data. TCC Reload Value = $38
      dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'D' Time Period Data. TCC Reload Value = $38
      dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
      dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*
      dc      $138      'C' Time Period Data. TCC Reload Value = $38
      dc      $138      ' ' Time Period Data. TCC Reload Value = $38
*

```

* Time Counter Data

*
org \$0400
*
*** 1st Cycle
*
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F

*
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'A' Time Counter Data. PCNT = \$F
dc \$10F 'B' Time Counter Data. PCNT = \$F

*
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F ' ' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'G' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F

*
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'F' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10F 'B' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F
dc \$10F 'D' Time Counter Data. PCNT = \$F
dc \$10F 'E' Time Counter Data. PCNT = \$F
dc \$10F 'C' Time Counter Data. PCNT = \$F

*
dc \$10D 'D' Time Counter Data. PCNT = \$D

*
*** 2nd Cycle
*
dc \$10F 'G' Time Counter Data. PCNT = \$F



```

dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10E      'C' Time Counter Data. PCNT = $E
dc      $10F      ' ' Time Counter Data. PCNT = $F
*
end

```

3. H4369

```
*****
*
*       HMCS400 Series Application Note
*
*       'Sound Play
*       - Minuet : J.S.Bach'
*
*       MCU : H4369
*
*       External Clock : 4MHz
*       Internal Clock : 1MHz
*       Sub Clock      : 32.768kHz
*
*****
*
*****
*
*       Symbol Definition
*****
*
IE      equ    0,$000    Interrupt Enable Flag
RSP     equ    1,$000    Reset Stack Pointer
IF0     equ    2,$000    INT0 Interrupt Request Flag
IM0     equ    3,$000    INT0 Interrupt Mask
*
IF1     equ    0,$001    INT1 Interrupt Request Flag
IM1     equ    1,$001    INT1 Interrupt Mask
IFTA    equ    2,$001    Timer A Interrupt Request Flag
IMTA    equ    3,$001    Timer A Interrupt Mask
*
IFTB    equ    0,$002    Timer B Interrupt Request Flag
IMTB    equ    1,$002    Timer B Interrupt Mask
IFTC    equ    2,$002    Timer C Interrupt Request Flag
IMTC    equ    3,$002    Timer C Interrupt Mask
*
IFAD    equ    0,$003    A/D Converter Interrupt Request Flag
IMAD    equ    1,$003    A/D Converter Interrupt Mask
IFS     equ    2,$003    Serial Interrupt Request Flag
IMS     equ    3,$003    Serial Interrupt Mask
*
PMRA    equ    $004      Port Mode Register
SMR     equ    $005      Serial Mode Register
SRL     equ    $006      Serial Data Register L
SRU     equ    $007      Serial Data Register U
TMA     equ    $008      Timer Mode Register A
TMB1    equ    $009      Timer Mode Register B1
TRBL    equ    $00A      Timer Read Register BL
TWBL    equ    $00A      Timer Write Register BL
TRBU    equ    $00B      Timer Read Register BU
TWBU    equ    $00B      Timer Write Register BU
```

MIS	equ	\$00C	Miscellaneous Register
TMC	equ	\$00D	Timer Mode Register C
TRCL	equ	\$00E	Timer Read Register CL
TWCL	equ	\$00E	Timer Write Register CL
TRCU	equ	\$00F	Timer Read Register CU
TWCU	equ	\$00F	Timer Write Register CU
*			
ACR	equ	\$016	A/D Channel Register
ADRL	equ	\$017	A/D Data Register L
ADRU	equ	\$018	A/D Data Register U
AMR1	equ	\$019	A/D Mode Register 1
AMR2	equ	\$01A	A/D Mode Register 2
*			
LSON	equ	0,\$020	Low Speed on Flag
WDON	equ	1,\$020	Watchdog on Flag
ADSF	equ	2,\$020	A/D Start Flag
DTON	equ	3,\$020	Direct Transfer on Flag
*			
ICSF	equ	0,\$021	Input Capture Status Flag
ICEF	equ	1,\$021	Input Capture Error Flag
IAOF	equ	2,\$021	IAD off Flag
RAME	equ	3,\$021	RAM Enable Flag
*			
PMRB	equ	\$024	Port Mode Register B
PMRC	equ	\$025	Port Mode Register C
TMB2	equ	\$026	Timer Mode Register B2
SSR1	equ	\$027	System Clock Selection Register 1
SSR2	equ	\$028	System Clock Selection Register 2
*			
DCD0	equ	\$02C	D Port Data Control Register 0
DCD1	equ	\$02D	D Port Data Control Register 1
DCD2	equ	\$02E	D Port Data Control Register 2
DCD3	equ	\$02F	D Port Data Control Register 3
DCR0	equ	\$030	R Port Data Control Register 0
DCR1	equ	\$031	R Port Data Control Register 1
DCR2	equ	\$032	R Port Data Control Register 2
DCR3	equ	\$033	R Port Data Control Register 3
DCR4	equ	\$034	R Port Data Control Register 4
DCR5	equ	\$035	R Port Data Control Register 5
DCR6	equ	\$036	R Port Data Control Register 6
SCR7	equ	\$037	R Port Data Control Register 7
DCR8	equ	\$038	R Port Data Control Register 8
*			

*			
			RAM ALLOCATION

*			
AESC	equ	\$040	Accumulator Escape
BESC	equ	\$041	B Register Escape
*			
PLCNT	equ	\$090	Pulse Counter

```

*
PLFLG1 equ $091 Pulse Flag 1
PLONF equ 0,PLFLG1 Pulse Output Enable Flag
*
CNTL equ $093 Lower Counter
CNTU equ $094 Upper Counter
PCNT equ $095 Period Counter
AWORK equ $096 Accumulator Work RAM Area
BWORK equ $097 B Register Work RAM Area
*

```

```

*****
* Vector Address
*****

```

```

*
org $0000
*
JMPL SPLMN Reset Interrupt
JMPL SPLMN INT0 Interrupt
JMPL SPLMN INT1 Interrupt
JMPL SPLMN Timer A Interrupt
JMPL SPLINT Timer B Interrupt
JMPL SPLMN Timer C Interrupt
JMPL SPLMN A/D Converter Interrupt
JMPL SPLMN Serial Interrupt
*

```

```

*****
* Main Program
*****

```

```

*
org $1000
*
SPLMN REMD RSP Reset Stack Pointer
LMID $2,SSR1 Set System Clock to 1.6 - 5.0MHz
*
LAI 0
LRA 0 Initialize R0 Port PDR
LMID 8,DCR0 Initialize R03 Output Terminal Function
LMID 0,PMRA Initialize R03 Input/Output Terminal Function
*
LMID 3,PLCNT Initialize Pulse Counter
LMID 0,CNTL Initialize Lower Counter
LMID 0,CNTU Initialize Upper Counter
LMID $F,PCNT Initialize Period Counter
SEMD PLONF Initialize Pulse Output Enable Flag
*
LMID 8,TMC Initialize Timer C Function & Input Clock Period
REMD IFTC Clear IFTC to 0
*
LMID $D,TMB1 Initialize Timer B Function & Input Clock Period
LMID 0,TMB2 Initialize Timer B Function
*

```



	SEMD	IMTB	Timer B Interrupt Disable
	REMD	IFTB	Clear IFTB to 0
*			
	SEMD	IE	All Interrupt Enable
*			
SPLMN00	TMD	IFTC	IFTC = "1" ?
	BRS	SPLMN10	Yes. Branch to SPLMN10
	BRS	SPLMN00	No. Branch to SPLMN00
*			
	REMD	IFTC	Clear IFTC to 0
	LMID	9,TWCL	Set TCC Reload Value Lower
	LMID	0,TWCU	Set TCC Reload Value Upper
*			
SPLMN05	TMD	IFTC	IFTC = "1" ?
	BRS	SPLMN10	Yes. Branch to SPLMN10
	SEMD	IMTB	Timer B Interrupt Disable
	REMD	IFTB	Clear IFTB to 0
	LAI	0	
	LRA	0	Sound off
	BRS	SPLMN05	Branch to SPLMN05
*			
SPLMN10	REMD	IFTC	Clear IFTC to 0
	LAMD	PCNT	Load PCNT
	AI	1	Increment PCNT
	BRS	SPLMN40	PCNT Overflow ? Yes. Branch to SPLMN40
	LMAD	PCNT	No. Save PCNT
	BRS	SPLMN00	Branch to SPLMN00
*			
SPLMN40	LAMD	CNTU	Load CNTL
	LBA		
	LAMD	CNTL	Load CNTU
	P	2	Scale Data Pattern Generation
	LMAD	AWORK	Save Scale Lower Data
	LAB		
	LMAD	BWORK	Save Scale Upper Data
	ALEI	0	Scale Upper Data <= \$0 ? End Sound Play ?
	BRS	SPLMN90	Yes. Branch to SPLMN90
	ALEI	\$E	Scale Upper Data <= \$E ?
	BRS	SPLMN20	Yes. Branch to SPLMN20
	SEMD	IMTB	Timer B Interrupt Disable
	REMD	IFTB	Clear IFTB to 0
	LAI	0	
	LRA	0	R03 Output Terminal is "Low" Output
	BRS	SPLMN30	Branch to SPLMN30
*			
SPLMN20	LAMD	AWORK	Load AWORK
	LMAD	TWBL	Set TCB Reload Value Lower to Scale Data
	LAMD	BWORK	Load BWORK
	LMAD	TWBU	Set TCB Reload Value Upper to Scale Data
	REMD	IFTB	Clear IFTB to 0
	REMD	IMTB	Timer B Interrupt Enable


```

*
SPLMN30  LAMD  CNTU      Load Upper Counter
          LBA
          LAMD  CNTL      Load Lower Counter
          P      3        Time Period Data Pattern Generation
          LMAD  TWCL      Set TCC Reload Value Lower to Time Period Lower Data
          LAB
          LMAD  TWCU      Set TCC Reload Value Upper to Time Period Upper Data
*
          LAMD  CNTU      Load Upper Counter
          LBA
          LAMD  CNTL      Load Lower Counter
          P      4        Time Counter Data Pattern Generation
          LMAD  PCNT      Set PCNT to Time Counter Data
*
          SEC          Set Carry Flag at 1
          LAI          0
          AMCD  CNTL      Increment Lower Counter
          LMAD  CNTL      Save Lower Counter
          LAI          0
          AMCD  CNTU      If CNTL Overflow, Increment Upper Counter
          LMAD  CNTU      Save Upper Counter
          BR      *+1
          BRS  SPLMN00    Branch to SPLMN00
*
SPLMN90  SEMD  IMTB      Timer B Interrupt Disable
          LMID  0,CNTL    Initialize Lower Counter
          LMID  0,CNTU    Initialize Upper Counter
          LAI          0
          LRA          0        Initialize R0 Port PDR
          LMID  0,TWCL    Initialize TCC Reload Value Lower
          LMID  8,TWCU    Initialize TCC Reload Value Upper
          REMD  IFTC      Clear IFTC to 0
          BRS  SPLMN00    Branch to SPLMN00
*
*****
*      Timer B Interrupt Process
*      ---Pulse Output Routine---
*****
*
SPLINT   REMD  IFTB      Clear IFTB to 0
*
          LMAD  AESC      Store Accumulator
          LAB
          LMAD  BESC      Store B Register
*
          TMD  PLONF      Pulse Enable Flag = "1" ?
          BRS  PLI00      Yes. Branch to PLI00
          LAI  0          No. Stop Output Pulse
          LRA  0          R03 Output Terminal is "Low" Output
          BRS  PLI99      Branch to PLI99

```

```

*
PLI00    LAMD    PLCNT    Load Pulse Counter Value
         LBA      Store Pulse Counter Value
         ALEI    1      PLCNT <= $1 ? Is R03 Output Terminal "High" Output ?
         BRS    PLI10   Yes. Branch to PLI10
         LAI    0      No. R03 Output Terminal is "Low" Output
         BRS    PLI20   Branch to PLI20
PLI10    LAI    8
PLI20    LRA    0      R03 Output Terminal is "High" Output
         LAB      Restore Pulse Counter Value
         AI     $F     PLCNT + $F <= $F ? Pulse Counter = $0 ?
         BRS    PLI30   No. Branch to PLI30
         LAI    3      Yes. Pulse Counter Initialize
PLI30    LMAD    PLCNT    Save Pulse Counter Value
*
PLI99    LAMD    BESC     Restore B Register
         LBA
         LAMD    AESC     Restore Accumulator
*
         RTNI          Return from Interrupt
*
*****
*          Scale Data
*****
*
         ORG      $0200
*
*** 1st Cycle
*
         dc      $1AB    'G' Data. TCB Reload Value = $AB
         dc      $17F    'C' Data. TCB Reload Value = $7F
         dc      $18E    'D' Data. TCB Reload Value = $8E
         dc      $19B    'E' Data. TCB Reload Value = $9B
         dc      $1A1    'F' Data. TCB Reload Value = $A1
*
         dc      $1AB    'G' Data. TCB Reload Value = $AB
         dc      $17F    'C' Data. TCB Reload Value = $7F
         dc      $1FF    ' ' Data. TCB Reload Value = $FF
         dc      $17F    'C' Data. TCB Reload Value = $7F
*
         dc      $1B4    'A' Data. TCB Reload Value = $B4
         dc      $1A1    'F' Data. TCB Reload Value = $A1
         dc      $1AB    'G' Data. TCB Reload Value = $AB
         dc      $1B4    'A' Data. TCB Reload Value = $B4
         dc      $1BD    'B' Data. TCB Reload Value = $BD
*
         dc      $1C1    'C' Data. TCB Reload Value = $C1
         dc      $17F    'C' Data. TCB Reload Value = $7F
         dc      $1FF    ' ' Data. TCB Reload Value = $FF
         dc      $17F    'C' Data. TCB Reload Value = $7F
*

```

```

dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
*
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $17A      'B' Data. TCB Reload Value = $7A
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $18E      'D' Data. TCB Reload Value = $8E
*
*** 2nd Cycle
*
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $1A1      'F' Data. TCB Reload Value = $A1
*
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $1B4      'A' Data. TCB Reload Value = $B4
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $1B4      'A' Data. TCB Reload Value = $B4
dc      $1BD      'B' Data. TCB Reload Value = $BD
*
dc      $1C1      'C' Data. TCB Reload Value = $C1
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
*
dc      $19B      'E' Data. TCB Reload Value = $9B

```

```

dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $17A      'B' Data. TCB Reload Value = $7A
*
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
*
dc      $100      ' ' Data. TCB Reload Value = $00
*

```

```

*****
*      Time Period Data
*****

```

```

*      org      $0300

```

```

*      *** 1st Cycle

```

```

*      dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C

```

```

*      dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38

```

```

*      dc      $138      'A' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C

```

```

*      dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38

```

```

*      dc      $138      'F' Time Period Data. TCC Reload Value = $38
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C

```

```

*
dc      $138      'E' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'B' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'D' Time Period Data. TCC Reload Value = $38
*
*** 2nd Cycle
*
dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38
*
dc      $138      'A' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38
*
dc      $138      'F' Time Period Data. TCC Reload Value = $38
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'E' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*

```

```

dc      $138      'D' Time Period Data. TCC Reload Value = $38
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C

```

*

```

dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $138      ' ' Time Period Data. TCC Reload Value = $38

```

*

* Time Counter Data

*

```

org      $0400

```

*

*** 1st Cycle

*

```

dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F

```

*

```

dc      $10F      'B' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10D      'D' Time Counter Data. PCNT = $D
*
*** 2nd Cycle
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10E      'C' Time Counter Data. PCNT = $E

```

dc \$10F ' ' Time Counter Data. PCNT = \$F

*

end

4. H4889

```
*****
*
*       HMCS400 Series Application Note
*
*       'Sound Play
*       - Minuet : J.S.Bach'
*
*       MCU : H4889
*
*       External Clock : 4MHz
*       Internal Clock : 1MHz
*       Sub Clock      : 32.768kHz
*
*****
*
*****
*
*       Symbol Definition
*****
*
IE      equ    0,$000    Interrupt Enable Flag
RSP     equ    1,$000    Reset Stack Pointer
IFWU    equ    2,$000    WU0-WU3 Interrupt Request Flag
IMWU    equ    3,$000    WU0-WU3 Interrupt Mask
*
IF0     equ    0,$001    INTO Interrupt Request Flag
IM0     equ    1,$001    INTO Interrupt Mask
IF1     equ    2,$001    INT1 Interrupt Request Flag
IM1     equ    3,$001    INT1 Interrupt Mask
*
IFTA    equ    0,$002    Timer A Interrupt Request Flag
IMTA    equ    1,$002    Timer A Interrupt Mask
IFTB    equ    2,$002    Timer B Interrupt Request Flag
IMTB    equ    3,$002    Timer B Interrupt Mask
*
IFTC    equ    0,$003    Timer C Interrupt Request Flag
IMTC    equ    1,$003    Timer C Interrupt Mask
IFAD    equ    2,$003    A/D Converter Interrupt Request Flag
IMAD    equ    3,$003    A/D Converter Interrupt Mask
*
SSR     equ    $004      System Clock selection Register
MIS     equ    $005      Miscellaneous Register
ESR     equ    $006      Edge Detect Selection Register
*
PMR0    equ    $008      Port Mode Register 0
PMR1    equ    $009      Port Mode Register 1
PMR2    equ    $00A      Port Mode Register 2
PMR3    equ    $00B      Port Mode Register 3
PMR4    equ    $00C      Port Mode Register 4
MSR1    equ    $00D      Module Standby Register 1
```

MSR2	equ	\$00E	Module Standby register 2
TMA	equ	\$00F	Timer Mode Register A
TMB1	equ	\$010	Timer Mode Register B1
TMB2	equ	\$011	Timer Mode register B2
TRBL	equ	\$012	Timer Read Register BL
TWBL	equ	\$012	Timer Write Register BL
TRBU	equ	\$013	Timer Read Register BU
TWBU	equ	\$013	Timer Write Register BU
TMC1	equ	\$014	Timer Mode Register C1
TMC2	equ	\$015	Timer Mode Register C2
TRCL	equ	\$016	Timer Read Register CL
TWCL	equ	\$016	Timer Write Register CL
TRCU	equ	\$017	Timer Read Register CU
TWCU	equ	\$017	Timer Write Register CU
TMD1	equ	\$018	Timer Mode Register D1
TMD2	equ	\$019	Timer Mode Register D2
TRDL	equ	\$01A	Timer Read Register DL
TWDL	equ	\$01A	Timer Write Register DL
TRDU	equ	\$01B	Timer Read Register DU
TWDU	equ	\$01B	Timer Write Register DU
*			
LSON	equ	0,\$020	Low Speed on Flag
WDON	equ	1,\$020	Watchdog on Flag
ADSF	equ	2,\$020	A/D Start Flag
DTON	equ	3,\$020	Direct Transfer on Flag
*			
ICSF	equ	0,\$021	Input Capture Status Flag
ICEF	equ	1,\$021	Input Capture Error Flag
GEF	equ	3,\$021	Gear Enable Flag
*			
IFTD	equ	2,\$022	Timer D Interrupt Request Flag
IMTD	equ	3,\$022	Timer D Interrupt Mask
*			
IFS	equ	2,\$023	Serial Interrupt Request Flag
IMS	equ	3,\$023	Serial Interrupt Mask
*			
SMR1	equ	\$024	Serial Mode Register 1
SMR2	equ	\$025	Serial Mode Register 2
SRL	equ	\$026	Serial Data Register L
SRU	equ	\$027	Serial Data Register U
AMR	equ	\$028	A/D Mode Register
*			
ADRL	equ	\$02A	A/D Data Register L
ADRU	equ	\$02B	A/D Data Register U
LCR	equ	\$02C	LCD Control Register
LMR	equ	\$02D	LCD Mode Register
BMR	equ	\$02E	Buzzer Mode Register
*			
DCD0	equ	\$030	D Port Data Control Register 0
DCD1	equ	\$031	D Port Data Control Register 1
DCD2	equ	\$032	D Port Data Control Register 2

```

*
DCR0    equ    $034    R Port Data Control Register 0
DCR1    equ    $035    R Port Data Control Register 1
DCR2    equ    $036    R Port Data Control Register 2
DCR3    equ    $037    R Port Data Control Register 3
DCR4    equ    $038    R Port Data Control Register 4
DCR5    equ    $039    R Port Data Control Register 5
DCR6    equ    $03A    R Port Data Control Register 6
DCR7    equ    $03B    R Port Data Control Register 7
DCR8    equ    $03C    R port Data Control Register 8

```

```

*
V        equ    $03F    Bank Register

```

```

*****

```

```

*          RAM ALLOCATION

```

```

*****

```

```

*
AESC    equ    $040    Accumulator Escape
BESC    equ    $041    B Register Escape
*
PLCNT   equ    $090    Pulse Counter
*
PLFLG1  equ    $091    Pulse Flag 1
PLONF   equ    0,PLFLG1 Pulse Output Enable Flag
*
CNTL    equ    $093    Lower Counter
CNTU    equ    $094    Upper Counter
PCNT    equ    $095    Period Counter
AWORK   equ    $096    Accumulator Work RAM Area
BWORK   equ    $097    B Register Work RAM Area

```

```

*****
*          Vector Address

```

```

*****

```

```

*          org    $0000
*
JMWPL   SPLMN   Reset Interrupt
JMWPL   SPLMN   WU0-WU3 Interrupt
JMWPL   SPLMN   INT0 Interrupt
JMWPL   SPLMN   INT1 Interrupt
JMWPL   SPLMN   Timer A Interrupt
JMWPL   SPLINT  Timer B/D Interrupt
JMWPL   SPLMN   Timer C Interrupt
JMWPL   SPLMN   A/D Converter/Serial Interrupt

```

```

*****
*          Main Program

```

```

*****

```

```

*          org    $1000

```



```

*
SPLMN  REMD  RSP      Reset Stack Pointer
        LMID  $2,SSR   Set System Clock to 1.6 - 4.5MHz
*
        LAI   $0
        LRA   $1      Initialize R1 Port PDR
        LMID  $4,DCR1  Initialize R12 Output Terminal Function
        LMID  $0,PMR2  Initialize R12 Input/Output Terminal Function
*
        LMID  $3,PLCNT Initialize Pulse Counter
        LMID  $0,CNTL  Initialize Lower Counter
        LMID  $0,CNTU  Initialize Upper Counter
        LMID  $F,PCNT  Initialize Period Counter
        SEMD  PLONF    Initialize Pulse Output Enable Flag
*
        LMID  $8,TMC1  Initialize Timer C Function & Input Clock Period
        REMD  IFTC     Clear IFTC to 0
*
        LMID  $D,TMB1  Initialize Timer B Function & Input Clock Period
        LMID  $0,TMB2  Initialize Timer B Function
*
        SEMD  IMTB     Timer B Interrupt Disable
        REMD  IFTB     Clear IFTB to 0
*
        SEMD  IE       All Interrupt Enable
*
SPLMN00 TMD    IFTC     IFTC = "1" ?
        BRS   SPLMN10  Yes. Branch to SPLMN10
        BRS   SPLMN00  No. Branch to SPLMN00
*
        REMD  IFTC     Clear IFTC to 0
        LMID  $9,TWCL  Set TCC Reload Value Lower
        LMID  $0,TWCU  Set TCC Reload Value Upper
*
SPLMN05 TMD    IFTC     IFTC = "1" ?
        BRS   SPLMN10  Yes. Branch to SPLMN10
        SEMD  IMTB     Timer B Interrupt Disable
        REMD  IFTB     Clear IFTB to 0
        LAI   $0
        LRA   $1      Sound off
        BRS   SPLMN05  Branch to SPLMN05
*
SPLMN10 REMD  IFTC     Clear IFTC to 0
        LAMD  PCNT     Load PCNT
        AI    $1       Increment PCNT
        BRS   SPLMN40  PCNT Overflow ? Yes. Branch to SPLMN40
        LMAD  PCNT     No. Save PCNT
        BRS   SPLMN00  Branch to SPLMN00
*
SPLMN40 LAMD  CNTU     Load CNTL
        LBA

```

	LAMD	CNTL	Load CNTU
	P	\$2	Scale Data Pattern Generation
	LMAD	AWORK	Save Scale Lower Data
	LAB		
	LMAD	BWORK	Save Scale Upper Data
	ALEI	\$0	Scale Upper Data <= \$0 ? End Sound Play ?
	BRS	SPLMN90	Yes. Branch to SPLMN90
	ALEI	\$E	Scale Upper Data <= \$E ?
	BRS	SPLMN20	Yes. Branch to SPLMN20
	SEMD	IMTB	Timer B Interrupt Disable
	REMD	IFTB	Clear IFTB to 0
	LAI	\$0	
	LRA	\$1	R12 Output Terminal is "Low" Output
	BRS	SPLMN30	Branch to SPLMN30
*			
SPLMN20	LAMD	AWORK	Load AWORK
	LMAD	TWBL	Set TCB Reload Value Lower to Scale Data
	LAMD	BWORK	Load BWORK
	LMAD	TWBU	Set TCB Reload Value Upper to Scale Data
	REMD	IFTB	Clear IFTB to 0
	REMD	IMTB	Timer B Interrupt Enable
*			
SPLMN30	LAMD	CNTU	Load Upper Counter
	LBA		
	LAMD	CNTL	Load Lower Counter
	P	\$3	Time Period Data Pattern Generation
	LMAD	TWCL	Set TCC Reload Value Lower to Time Period Lower Data
	LAB		
	LMAD	TWCU	Set TCC Reload Value Upper to Time Period Upper Data
*			
	LAMD	CNTU	Load Upper Counter
	LBA		
	LAMD	CNTL	Load Lower Counter
	P	\$4	Time Counter Data Pattern Generation
	LMAD	PCNT	Set PCNT to Time Counter Data
*			
	SEC		Set Carry Flag at 1
	LAI	\$0	
	AMCD	CNTL	Increment Lower Counter
	LMAD	CNTL	Save Lower Counter
	LAI	\$0	
	AMCD	CNTU	If CNTL Overflow, Increment Upper Counter
	LMAD	CNTU	Save Upper Counter
	BR	*+1	
	BRS	SPLMN00	Branch to SPLMN00
*			
SPLMN90	SEMD	IMTB	Timer B Interrupt Disable
	LMID	\$0,CNTL	Initialize Lower Counter
	LMID	\$0,CNTU	Initialize Upper Counter
	LAI	\$0	
	LRA	\$1	Initialize R1 Port PDR

```

LMID    $0,TWCL    Initialize TCC Reload Value Lower
LMID    $8,TWCU    Initialize TCC Reload Value Upper
REMD    IFTC      Clear IFTC to 0
BRS     SPLMN00   Branch to SPLMN00

```

```

*
*****

```

```

*       Timer B Interrupt Process
*       ---Pulse Output Routine---

```

```

*****

```

```

*
SPLINT  REMD    IFTB      Clear IFTB to 0
*
        LMAD    AESC      Store Accumulator
        LAB
        LMAD    BESC      Store B Register
*
        TMD     PLONF     Pulse Enable Flag = "1" ?
        BRS     PLI00     Yes. Branch to PLI00
        LAI     $0        No. Stop Output Pulse
        LRA     $1        R12 Output Terminal is "Low" Output
        BRS     PLI99     Branch to PLI99
*
PLI00   LAMD    PLCNT     Load Pulse Counter Value
        LBA                      Store Pulse Counter Value
        ALEI    $1        PLCNT <= $1 ? Is R12 Output Terminal "High" Output ?
        BRS     PLI10     Yes. Branch to PLI10
        LAI     $0        No. R12 Output Terminal is "Low" Output
        BRS     PLI20     Branch to PLI20
PLI10   LAI     $4
PLI20   LRA     $1        R03 Output Terminal is "High" Output
        LAB                      Restore Pulse Counter Value
        AI      $F        PLCNT + $F <= $F ? Pulse Counter = $0 ?
        BRS     PLI30     No. Branch to PLI30
        LAI     $3        Yes. Pulse Counter Initialize
PLI30   LMAD    PLCNT     Save Pulse Counter Value
*
PLI99   LAMD    BESC      Restore B Register
        LBA
        LAMD    AESC      Restore Accumulator
*
        RTNI           Return from Interrupt
*

```

```

*****

```

```

*       Scale Data

```

```

*****

```

```

*       ORG     $0200

```

```

*
*** 1st Cycle

```

```

*       dc     $1AB      'G' Data. TCB Reload Value = $AB

```

dc	\$17F	'C' Data. TCB Reload Value = \$7F
dc	\$18E	'D' Data. TCB Reload Value = \$8E
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
*		
dc	\$1AB	'G' Data. TCB Reload Value = \$AB
dc	\$17F	'C' Data. TCB Reload Value = \$7F
dc	\$1FF	' ' Data. TCB Reload Value = \$FF
dc	\$17F	'C' Data. TCB Reload Value = \$7F
*		
dc	\$1B4	'A' Data. TCB Reload Value = \$B4
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
dc	\$1AB	'G' Data. TCB Reload Value = \$AB
dc	\$1B4	'A' Data. TCB Reload Value = \$B4
dc	\$1BD	'B' Data. TCB Reload Value = \$BD
*		
dc	\$1C1	'C' Data. TCB Reload Value = \$C1
dc	\$17F	'C' Data. TCB Reload Value = \$7F
dc	\$1FF	' ' Data. TCB Reload Value = \$FF
dc	\$17F	'C' Data. TCB Reload Value = \$7F
*		
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
dc	\$1AB	'G' Data. TCB Reload Value = \$AB
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$18E	'D' Data. TCB Reload Value = \$8E
*		
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$18E	'D' Data. TCB Reload Value = \$8E
dc	\$17F	'C' Data. TCB Reload Value = \$7F
*		
dc	\$17A	'B' Data. TCB Reload Value = \$7A
dc	\$17F	'C' Data. TCB Reload Value = \$7F
dc	\$18E	'D' Data. TCB Reload Value = \$8E
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$17F	'C' Data. TCB Reload Value = \$7F
*		
dc	\$18E	'D' Data. TCB Reload Value = \$8E
*		
***	2nd Cycle	
*		
dc	\$1AB	'G' Data. TCB Reload Value = \$AB
dc	\$17F	'C' Data. TCB Reload Value = \$7F
dc	\$18E	'D' Data. TCB Reload Value = \$8E
dc	\$19B	'E' Data. TCB Reload Value = \$9B
dc	\$1A1	'F' Data. TCB Reload Value = \$A1
*		
dc	\$1AB	'G' Data. TCB Reload Value = \$AB
dc	\$17F	'C' Data. TCB Reload Value = \$7F

```

dc      $1FF      ' ' Data. TCB Reload Value = $FF
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $1B4      'A' Data. TCB Reload Value = $B4
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $1B4      'A' Data. TCB Reload Value = $B4
dc      $1BD      'B' Data. TCB Reload Value = $BD
*
dc      $1C1      'C' Data. TCB Reload Value = $C1
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $1AB      'G' Data. TCB Reload Value = $AB
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
*
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $1A1      'F' Data. TCB Reload Value = $A1
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $17F      'C' Data. TCB Reload Value = $7F
*
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $19B      'E' Data. TCB Reload Value = $9B
dc      $18E      'D' Data. TCB Reload Value = $8E
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $17A      'B' Data. TCB Reload Value = $7A
*
dc      $17F      'C' Data. TCB Reload Value = $7F
dc      $1FF      ' ' Data. TCB Reload Value = $FF
*
dc      $100      ' ' Data. TCB Reload Value = $00
*

```

```

*****
*      Time Period Data
*****

```

```

*
*      org      $0300
*

```

```

*** 1st Cycle
*

```

```

dc      $138      'G' Time Period Data. TCC Reload Value = $38
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
*

```


dc	\$138	'G'	Time Period Data.	TCC Reload Value = \$38
dc	\$16A	'C'	Time Period Data.	TCC Reload Value = \$6A
dc	\$1CE	' '	Time Period Data.	TCC Reload Value = \$CE
dc	\$138	'C'	Time Period Data.	TCC Reload Value = \$38
*				
dc	\$138	'A'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'F'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'G'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'A'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'B'	Time Period Data.	TCC Reload Value = \$9C
*				
dc	\$138	'C'	Time Period Data.	TCC Reload Value = \$38
dc	\$16A	'C'	Time Period Data.	TCC Reload Value = \$6A
dc	\$1CE	' '	Time Period Data.	TCC Reload Value = \$CE
dc	\$138	'C'	Time Period Data.	TCC Reload Value = \$38
*				
dc	\$138	'F'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'G'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'F'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'E'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'D'	Time Period Data.	TCC Reload Value = \$9C
*				
dc	\$138	'E'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'F'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'E'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'D'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'C'	Time Period Data.	TCC Reload Value = \$9C
*				
dc	\$138	'B'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'C'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'D'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'E'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'C'	Time Period Data.	TCC Reload Value = \$9C
*				
dc	\$138	'D'	Time Period Data.	TCC Reload Value = \$38
*				
***	2nd Cycle			
*				
dc	\$138	'G'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'C'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'D'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'E'	Time Period Data.	TCC Reload Value = \$9C
dc	\$19C	'F'	Time Period Data.	TCC Reload Value = \$9C
*				
dc	\$138	'G'	Time Period Data.	TCC Reload Value = \$38
dc	\$16A	'C'	Time Period Data.	TCC Reload Value = \$6A
dc	\$1CE	' '	Time Period Data.	TCC Reload Value = \$CE
dc	\$138	'C'	Time Period Data.	TCC Reload Value = \$38
*				
dc	\$138	'A'	Time Period Data.	TCC Reload Value = \$38
dc	\$19C	'F'	Time Period Data.	TCC Reload Value = \$9C

```

dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'A' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $16A      'C' Time Period Data. TCC Reload Value = $6A
dc      $1CE      ' ' Time Period Data. TCC Reload Value = $CE
dc      $138      'C' Time Period Data. TCC Reload Value = $38
*
dc      $138      'F' Time Period Data. TCC Reload Value = $38
dc      $19C      'G' Time Period Data. TCC Reload Value = $9C
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'E' Time Period Data. TCC Reload Value = $38
dc      $19C      'F' Time Period Data. TCC Reload Value = $9C
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'D' Time Period Data. TCC Reload Value = $38
dc      $19C      'E' Time Period Data. TCC Reload Value = $9C
dc      $19C      'D' Time Period Data. TCC Reload Value = $9C
dc      $19C      'C' Time Period Data. TCC Reload Value = $9C
dc      $19C      'B' Time Period Data. TCC Reload Value = $9C
*
dc      $138      'C' Time Period Data. TCC Reload Value = $38
dc      $138      ' ' Time Period Data. TCC Reload Value = $38

```

```

*****

```

```

*      Time Counter Data

```

```

*****

```

```

*      org      $0400

```

```

*      *** 1st Cycle

```

```

*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F

```

```

dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'B' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10D      'D' Time Counter Data. PCNT = $D
*
*** 2nd Cycle
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
*
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'A' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      ' ' Time Counter Data. PCNT = $F

```

```

dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'G' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
*
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'F' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
*
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'E' Time Counter Data. PCNT = $F
dc      $10F      'D' Time Counter Data. PCNT = $F
dc      $10F      'C' Time Counter Data. PCNT = $F
dc      $10F      'B' Time Counter Data. PCNT = $F
*
dc      $10E      'C' Time Counter Data. PCNT = $E
dc      $10F      ' ' Time Counter Data. PCNT = $F
*
end

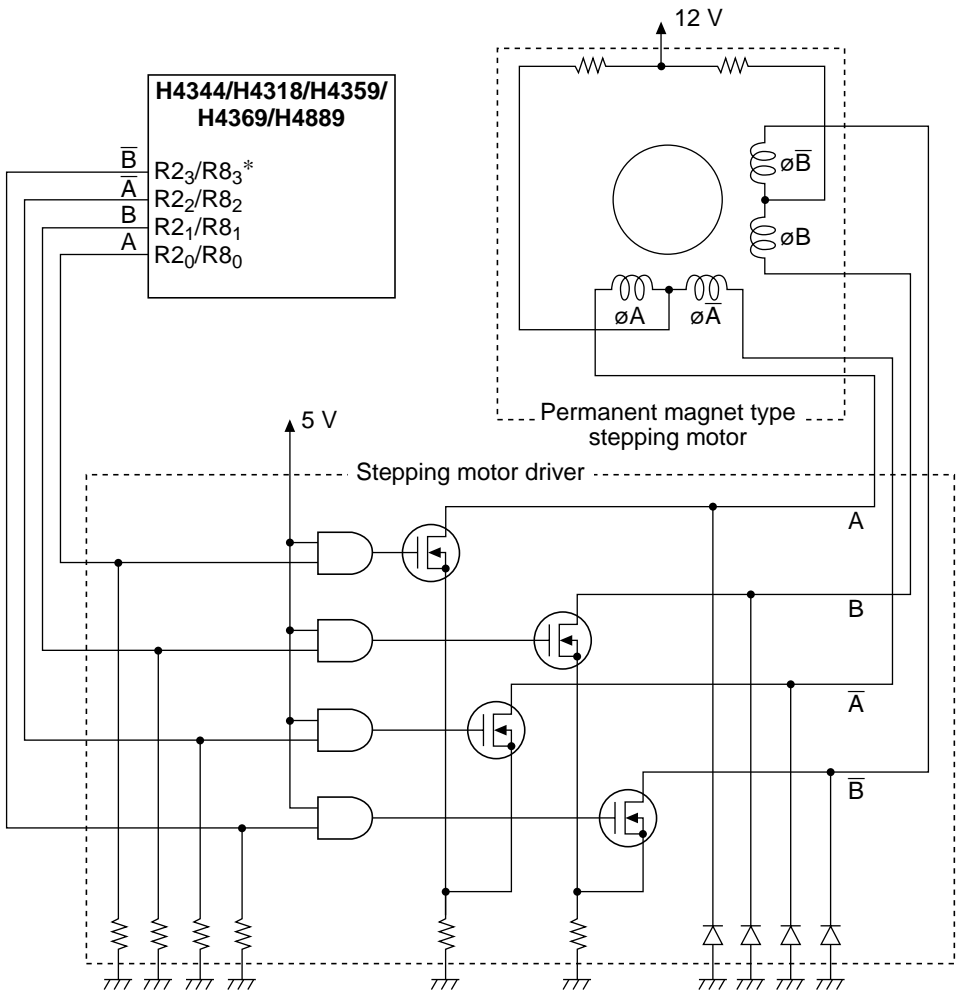
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2.2 Stepping Motor Control

Stepping Motor Control	MCU: H4344/H4318/H4359/ H4369/H4889	Functions Used: R2/R8 Port and Timer B
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Specifications

1. The H4344/H4318/H4359/H4369/H4889 Series are used for stepping motor control. The stepping motor is of the permanent magnet type.
2. The stepping motor repeats a forward run, stop, and reverse run cycle.
3. The stepping motor is run for approximately 4 seconds in forward, in stop, and in reverse.
4. Figure 1 shows the example stepping motor control circuit used in this example task.



Note: * $R2_0$ to $R2_3$ pins are used in the H4344/H4889 Series.
 $R8_0$ to $R8_3$ pins are used in the H4318/H4359/H4369 Series.

Figure 1 Example Stepping Motor Control Circuit

Concepts

1. Stepping motors have superb starting, stopping, and positional control characteristics.
2. Stepping motors are synchronous motors that run in sync with the pulse signals output from a pulse oscillator. The motor is run in sync with the pulse signals, so, because there is no speed fluctuation due to load fluctuations, it will stop exactly at the intended position.
3. Stepping motors have the following features:
 - a. The rotational angle of stepping motors is proportional to the number of input pulses.
 - b. There is minimal angle error per step, and no cumulative error.
 - c. Stepping motors have superb starting and stopping response.
 - d. By direct connection to the motor shaft, it's possible to achieve synchronous rotation at extremely low speeds.
 - e. The self holding capacity of stepping motors means that the stop position can be maintained.
 - f. Superb control characteristics can be achieved using open-loop control.
4. The following shows the method of excitation (the method of turning on the current to the windings of the stepping motor in order) of a 2-phase stepping motor.

- Single-phase excitation

In this method, only one phase excitation is performed at all times. This results in lower power dissipation, but because of the small amount of damping, vibration is more likely. Figure 2 shows the excitation sequence in single-phase excitation.

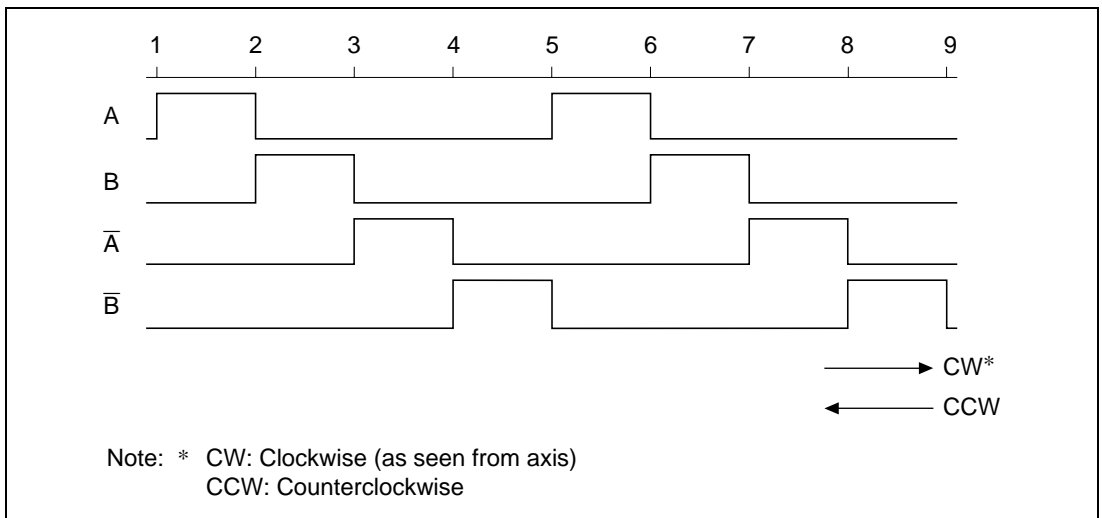


Figure 2 Excitation Sequence in Single-Phase Excitation

- Two-phase excitation

In this method, two-phase excitation is performed at all times. Twice the input is required over single-phase excitation, but the output torque is greater and damping is superior.

Figure 3 shows the excitation sequence in two-phase excitation.

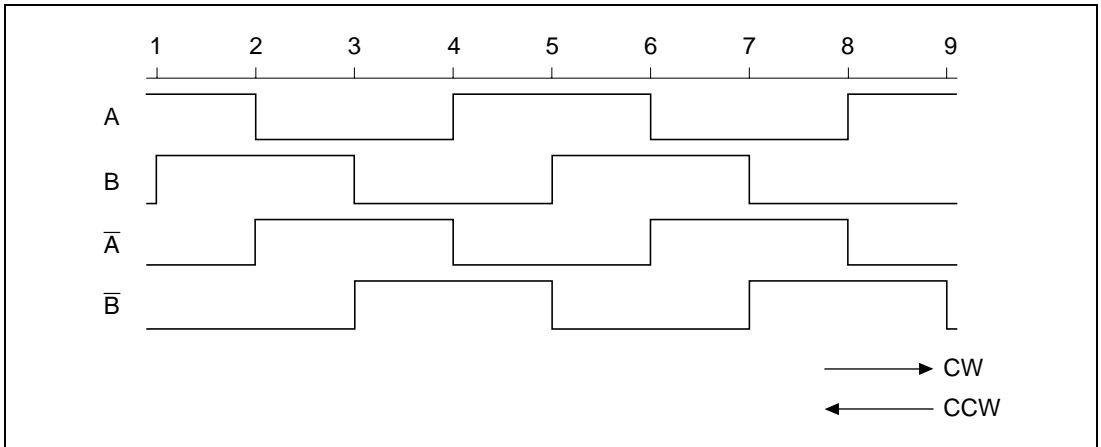


Figure 3 Excitation Sequence in Two-Phase Excitation

- 1-2-phase excitation

In this method, single-phase excitation and two-phase excitation are alternated. When a stepping motor is driven using this method, the motor's step angle is halved. Because the step angle is halved, running is smoother and there is minimal vibration. Figure 4 shows the excitation sequence in 1-2-phase excitation.

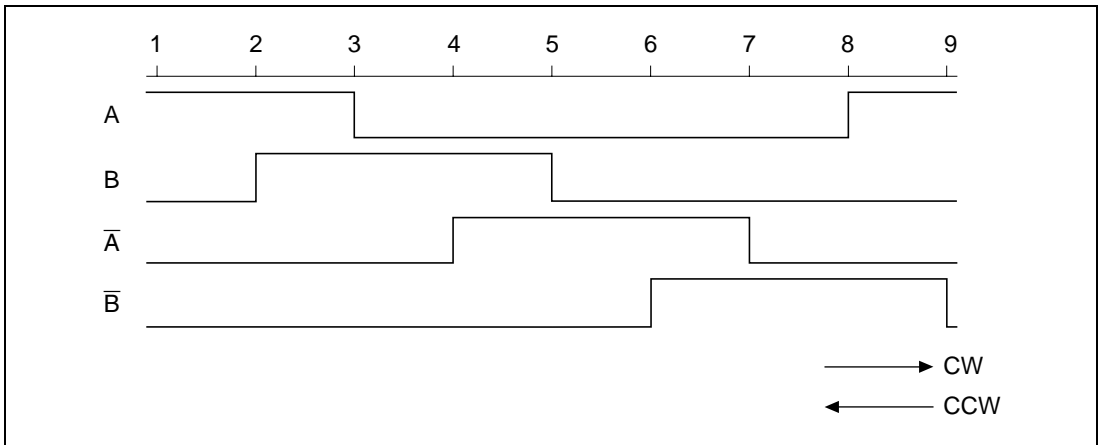


Figure 4 Excitation Sequence in 1-2-Phase Excitation

5. In this example task, the stepping motor is controlled using two-phase excitation. Figure 5 shows an example of port output when the motor is run in the forward direction in this task.

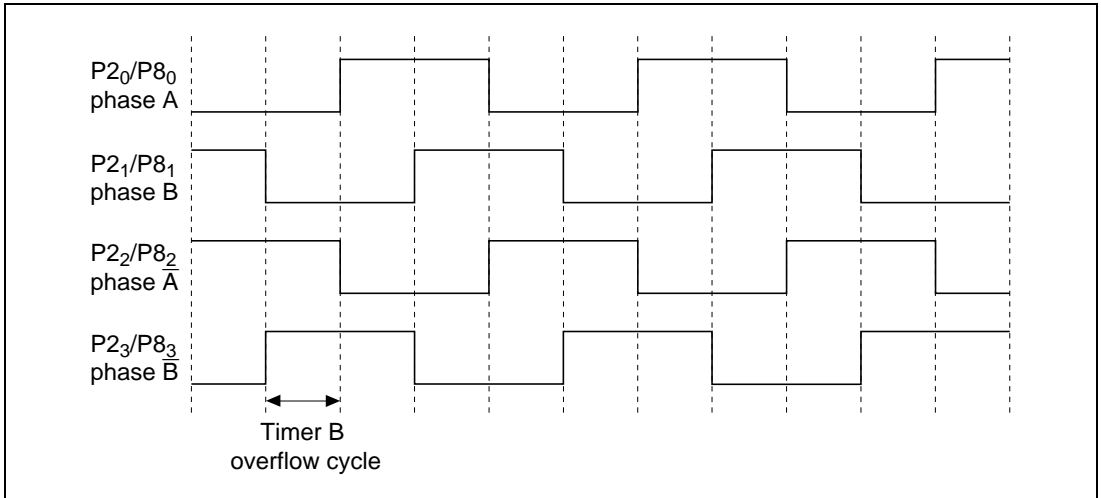


Figure 5 Example Port Output With Motor Running in Forward Direction

Description of Functions

1. In this example task, we use a permanent magnet type of stepping motor (KP6P8-701 from Japan Servo Co., Ltd.) Table 1 shows the standard specifications of the KP6P8-701. Figure 6 shows the wiring.

Table 1 **KP6P8-701 Standard Specifications**

Item	Unit	Value
Model No.	—	KP6P8-701
No. of phases	—	2
Step angle	deg./step	7.5
Voltage	V	12
Current	A/PHASE	0.33
Winding resistance	Ω /PHASE	36
Inductance	mH/PHASE	28
Maximum holding torque	gf·cm	800
Détente torque	gf·cm	160
Rotor inertia	gf·cm ²	23.7
Weight	kg	0.25
Insulation class	—	Type E or equivalent
Insulation resistance	—	500 V DC 100 M Ω 1 min.
Dielectric strength	—	500 V AC 50 Hz 1 min.
Operating temperature range	°C	-10 to +45
Temperature rise	deg	70
Lead specifications	—	AWG #22 UL3266

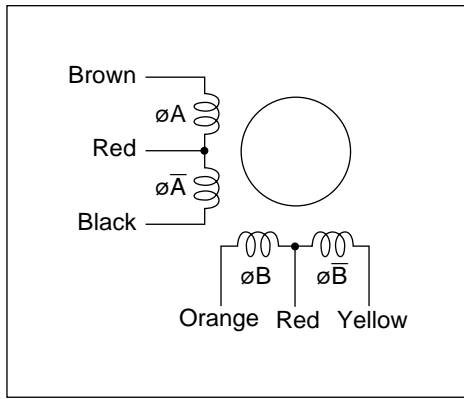


Figure 6 KP6P8-701 Wiring

2. This section describes the functions of the H4344/H4318/H4359/H4369/H4889 used in stepping motor control. Figure 7 is a block diagram of the functions used in this example task.

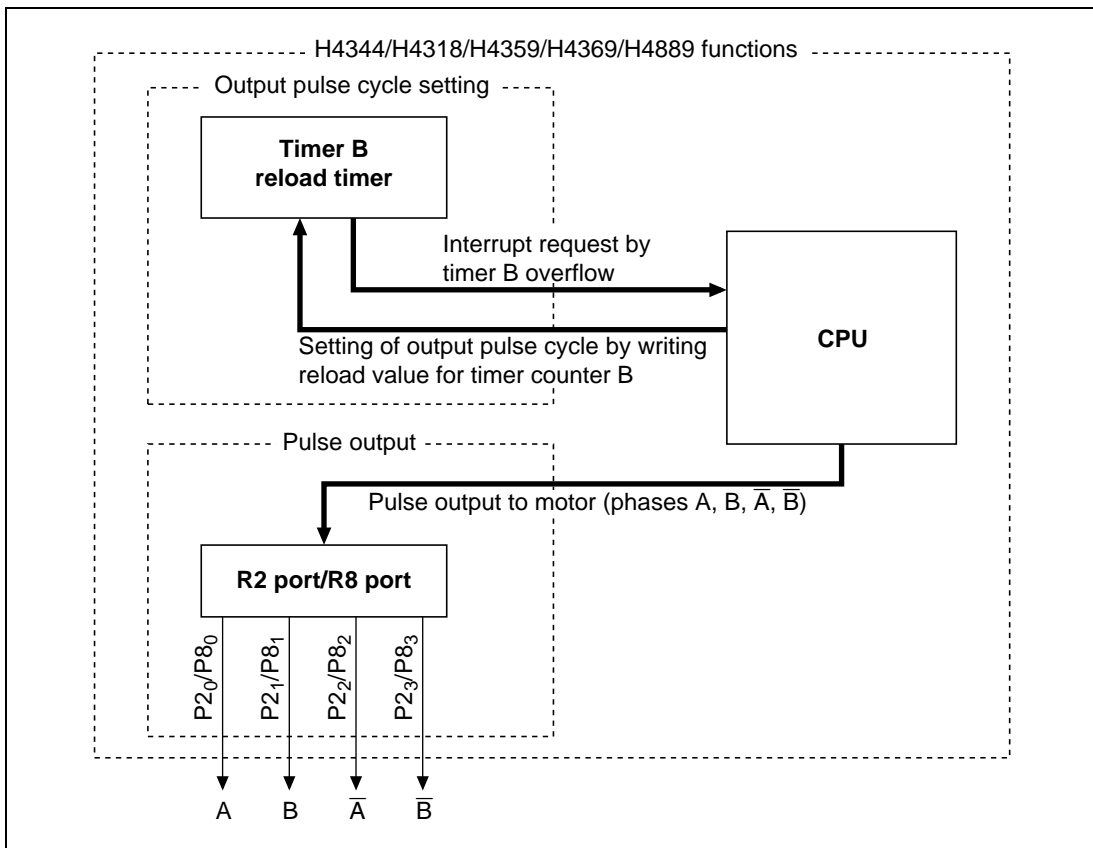


Figure 7 Block Diagram of Functions H4344/H4318/H4359/H4369/H4889 Used in Stepping Motor Control

- **Timer B reload timer functions**
Sets the output pulse cycle. The output pulse cycle is determined from the timer counter B reload value. The reload value to be set is referenced from the data table.
- **R2 port/R8 port functions**
These are the output pins for the pulses (phases A, B, \bar{A} , \bar{B}) output to the stepping motor.

3. The following describes the functions of timer B and the R2/R8 port.

a. Figure 8 is a block diagram of timer B functions.

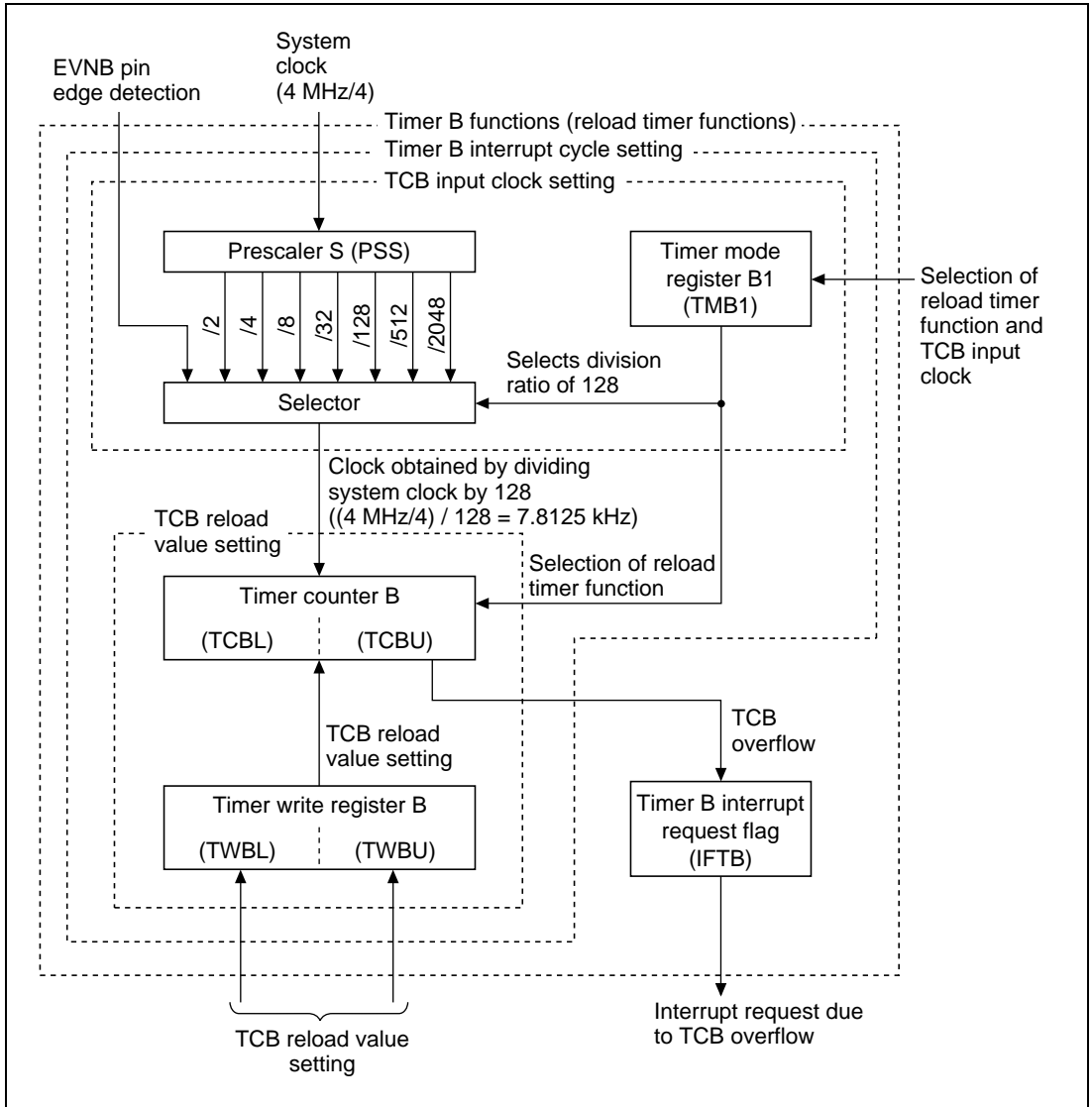


Figure 8 Block Diagram of Timer B Functions

- b. Timer B is an 8-bit multifunction timer (free running/event counter/reload timer/input capture^{*1}). In this example task, timer B is used as a reload timer. Table 2 describes the timer B functions.

Table 2 Timer B Functions

Timer Mode Register B1 (TMB1)	
Function	TMB1 is a 4-bit write-only register. It selects the timer B function (free-running/reload timer) and operating clock. TMB1 is initialized to \$0 when reset and in stop mode.
Timer Write Register BL, U (TWBL, TWBU)	
Function	TWBL and TWBU form an 8-bit write-only register, which is made up of the lower digit (TWBL) and upper digit (TWBU). TWBL and TWBU are used for the initial TCB setting (the reload setting when operation as a reload timer).
Timer Counter B (TCB)	
Function	TCB is an 8-bit up-counter, which is incremented by the input internal clock. The TCB input clock is selected using bits TMB12 to TMB10 of TMB1. The value written to TWBL and TWBU is also written to TCB. When TCB overflows, the timer B interrupt request flag (IFTB) is set to "1". If, at this point, timer B is set as a reload timer, the value of TWBL and TWBU is written to this counter and the count starts from this value. TCB is initialized to \$00 when reset and in stop mode.
Prescaler S (PSS)	
Function	PSS is an 11-bit counter to which the system clock is input when in active mode and standby mode, and the subsystem clock is input when in subactive mode ^{*2} . PSS is initialized to \$000 at a reset, and starts to count the system clock when the reset is canceled. PSS operation is halted when reset, in stop mode, and in watch mode ^{*2} . However, it runs in other operating modes. The PSS output is shared by the internal peripheral modules, the division ratio being set independently for each of the internal peripheral modules.
Timer B Interrupt Request Flag (IFTB)	
Function	IFTB reflects the existence of the timer B interrupt request. When timer B overflows, IFTB is set to "1". IFTB can only be read/written to (only "0" can be written) using bit operation commands. Note that IFTB is not automatically cleared even when the interrupt is received, and must be cleared by writing "0" using software. IFTB is cleared at a reset and in stop mode.
Timer B Interrupt Mask (IMTB)	
Function	IMTB is the bit that masks IFTB. When IFTB is set to "1" and, additionally, IMTB is "0", a timer B interrupt request is sent to the CPU (when IE = "1"). If IFTB is set to "1" but IMTB is "1", no interrupt request is sent to the CPU and the timer B interrupt is held. IMTB can only be read or written to using bit operation commands. It is set to "1" at a reset and in stop mode.

- Notes: 1. Applies to H4318/H4359/H4369 Series only. In the H4344/H4889 Series, timer B has no input capture function.
 2. Applies only to H4369/H4889 Series.

- c. Figure 9 is a block diagram of the R2 port functions used in the H4344; figure 10 is a block diagram of the R2 port functions used in the H4889; figure 11 is a block diagram of the R8 port functions used in the H4318/H4359/H4369.

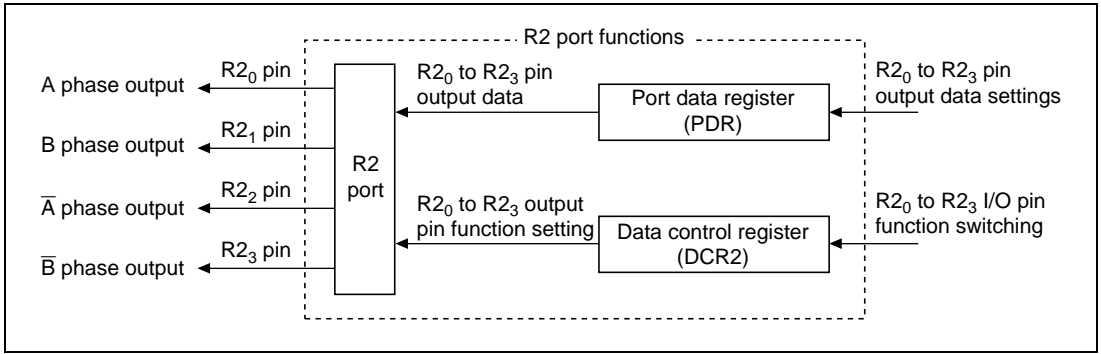


Figure 9 Block Diagram of Port R2 Functions in H4344 Series

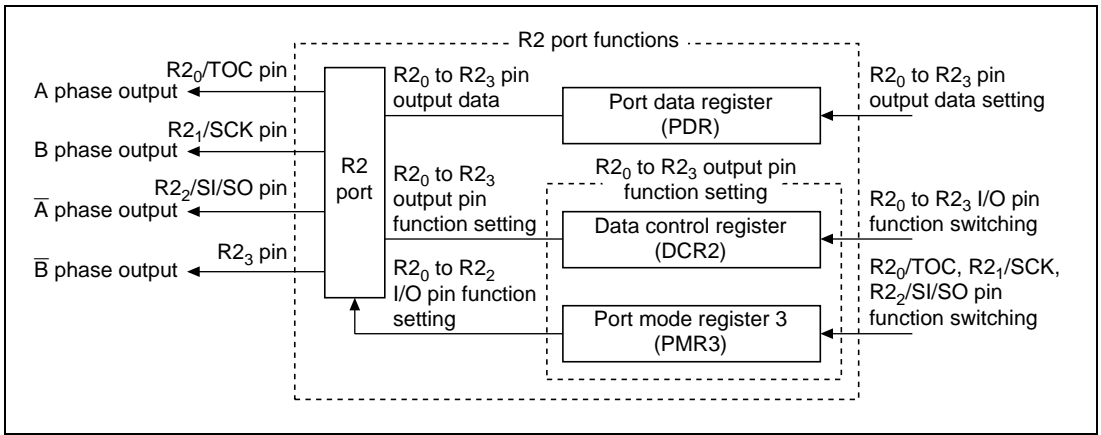


Figure 10 Block Diagram of Port R2 Functions in H4889 Series

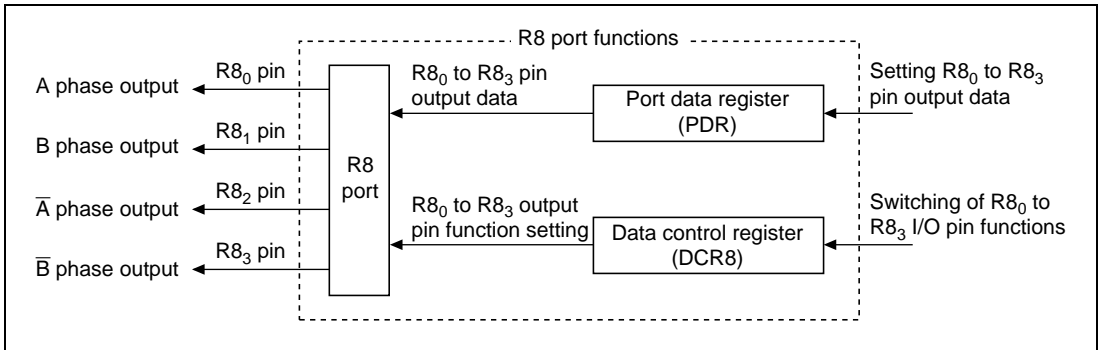


Figure 11 Block Diagram of Port R8 Functions in H4318/H4359/H4369 Series

- d. The R2 port in the H4344/H4889 and the R8 port in the H4318/H4359/H4369 are 4-bit I/O ports. Both R2 and R8 are capable of 4-bit input using the LAR and LBR commands, and 4-bit output using the LRA and LRB commands. The output data is stored in the PDR of the respective pins.

In this example task, the R2₀ to R2₃ pins in the H4344/H4889 Series and the R8₀ to R8₃ pins in the H4318/H4359/H4369 Series are set for output and used to output pulses to the stepping motor.

Table 3 describes the functions of the R2 port in the H4344/H4889 and the R8 port in the H4318/H4359/H4369.

Table 3 R2 Port Functions in H4344/H4889 and R8 Port Functions in H4318/H4359/H4369

Data Control Register R2 (DCR2)		Note: Applies to H4344/H4889 Series
Function	DCR2 switches the I/O pin function of the R2 port. When any bit of DCR2 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR2 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.	
Data Control Register R8 (DCR8)		Note: Applies to H4318/H4359/H4369 Series
Function	DCR8 switches the I/O pin function of the R8 port. When any bit of DCR8 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR8 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.	
Port Mode Register 3 (PMR3)		Note: Applies to H4889 Series
Function	PMR3 is a 4-bit write-only register. Bits PMR33 to PMR30 switch the functions of the R2 port's dual-function pins.	
Port Data Register (PDR)		
Function	The I/O pins of the R ports have built-in PDRs to store the output data. When the LRA and LRB commands are executed, the contents of the accumulator (A) and B register (B) are transferred to the PDR of the specified R port. When the corresponding bit of the DCR of the R port is "1", the output buffer of the appropriate pin is set ON and the value in the PDR is output via that pin. The PDR is initialized to \$F at a reset.	

3. Table 4 shows the allocation of functions in this example task.

Table 4 Function Allocation

Function	Function Allocation
System clock	The system clock is obtained by dividing the clock output from the system clock oscillator by 4. It is used for operating the CPU and internal peripheral modules. In this example task, a 4 MHz system clock oscillator is used, so the clock supplied to the CPU and internal peripheral modules is 1 MHz. The clock used by timer B is obtained by dividing the 1 MHz clock at PSS.
PSS	The clock input to timer B is obtained by dividing the system clock. The clock supplied to timer B is obtained by dividing the system clock by 128.
TCB	This is an 8-bit up-counter. The count starts from the value set in TWBL and TWBU. When an overflow occurs, IFTB is set to "1". After an overflow, the reload value set in TWBL and TWBU is set in TCB.
TWBL, TWBU	The TCB reload value is set in TWBL and TWBU. The reload value is determined from the pulse cycle to be output to the stepping motor.
TMB1	TMB1 selects the reload timer function for timer B and a clock obtained by dividing the system clock by 128 as the TCB input clock.
IFTB	IFTB reflects the existence of a timer B interrupt request. The pulse output pin output level is set in the timer B interrupt processing.
IMTB	Enables/disables timer B interrupt requests.
DCR2 (H4344/H4889) DCR8 (H4318/H4359/ H4369)	Sets the R _{2₀} to R _{2₃} pins (H4344/H4889) and R _{8₀} to R _{8₃} pins (H4318/H4359/H4369 Series) as output pins.
PMR3 (H4889)	Sets the R _{2₀} /TOC dual-function pin as an R _{2₀} I/O pin and the R _{2₁} /SCK dual-function pin as an R _{2₁} pin.
PDR	Stores the output data for the R _{2₀} to R _{2₃} /R _{8₀} to R _{8₃} pins.
R _{2₀} to R _{2₃} pins	Output pins for the pulse output to the stepping motor in the H4344/H4889 Series.
R _{8₀} to R _{8₃} pins	Output pins for the pulse output to the stepping motor in H4318/H4359/ H4369 Series.

Description of Operation

1. Figure 12 is a flowchart of the stepping motor control.

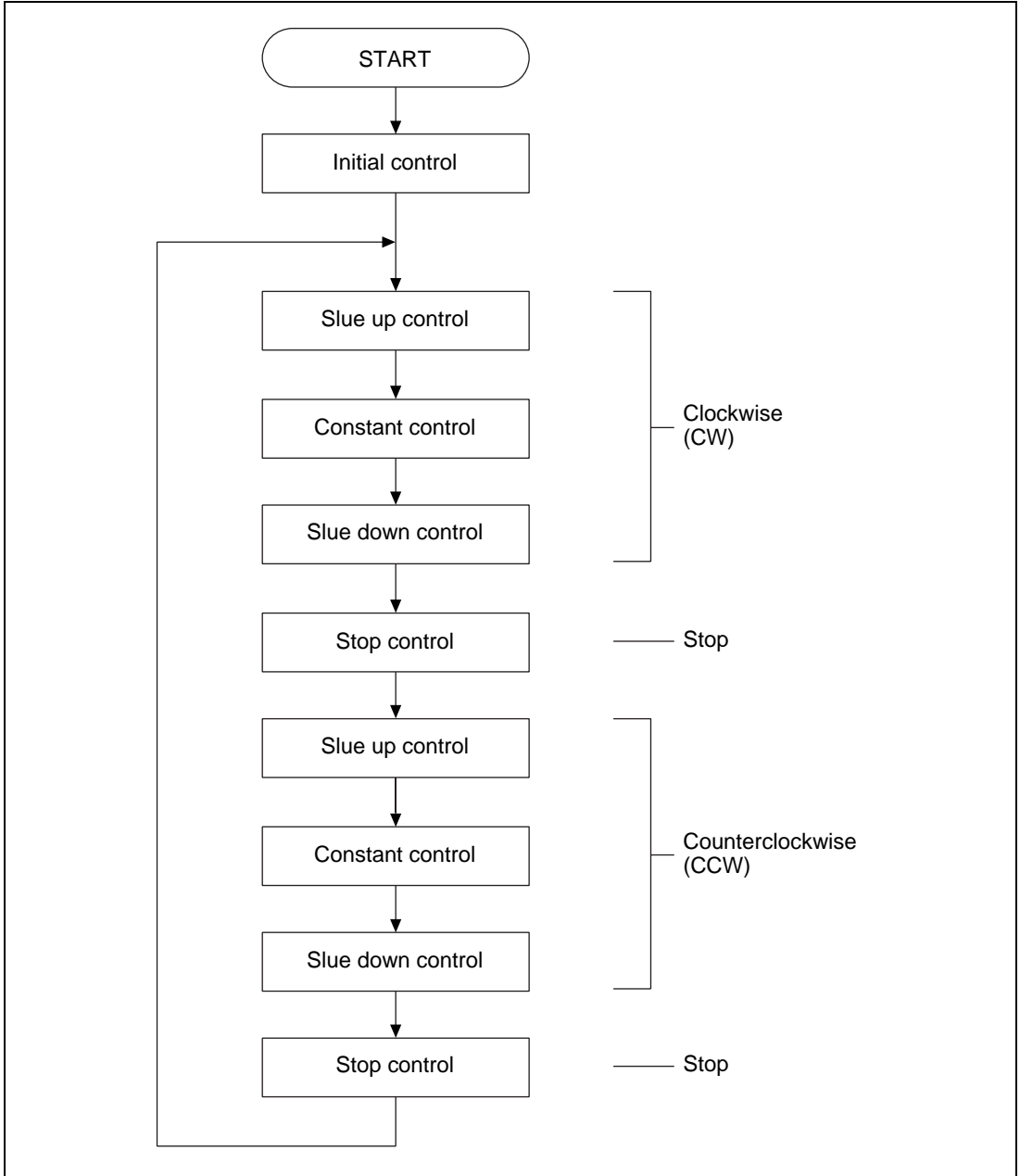


Figure 12 Flowchart of Stepping Motor Control

2. Figure 13 shows the operating principle of initial control.

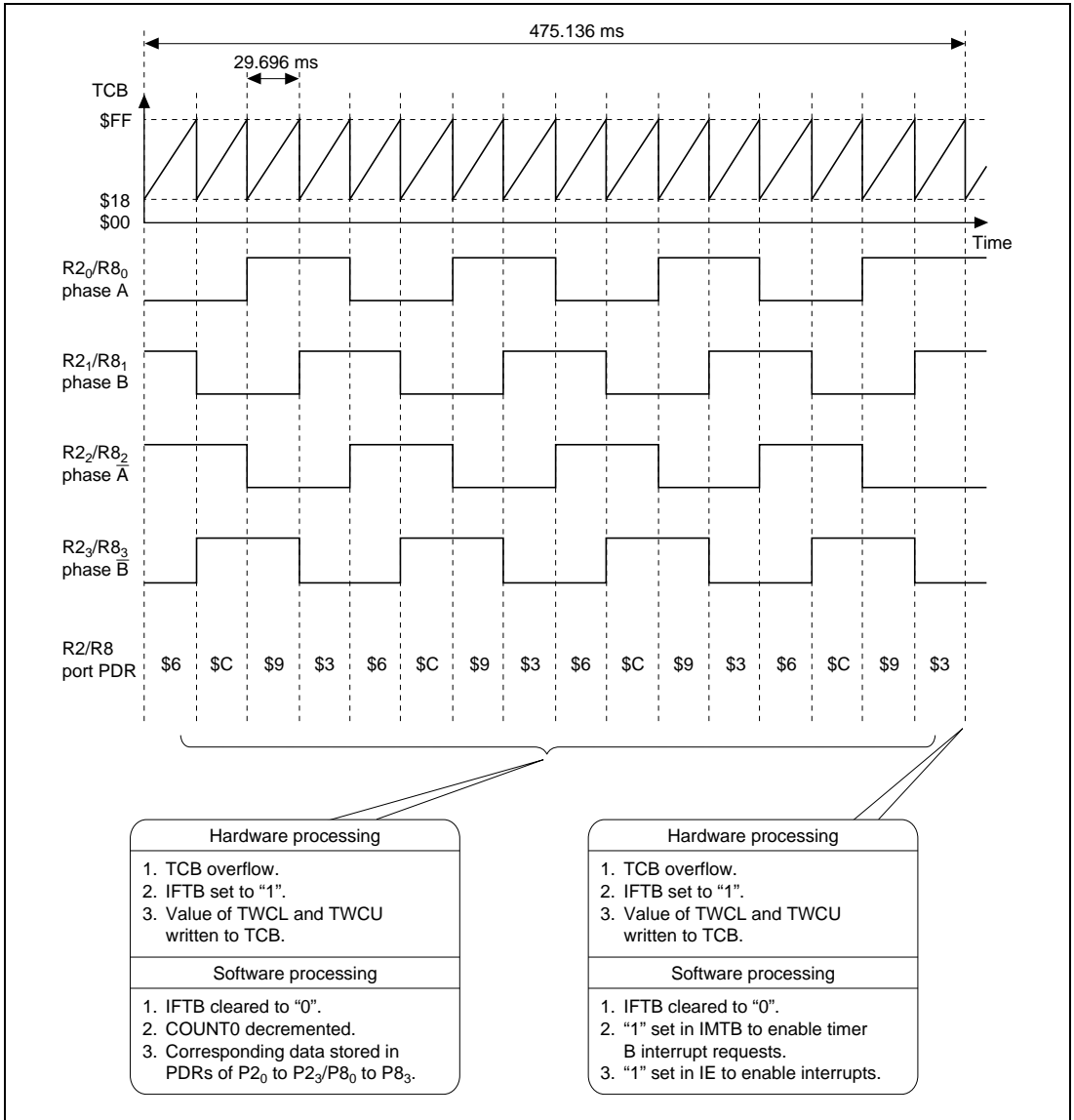


Figure 13 Operating Principle of Initial Control

3. Figure 14 shows the operating principle of Slue up control when the motor is running clockwise.

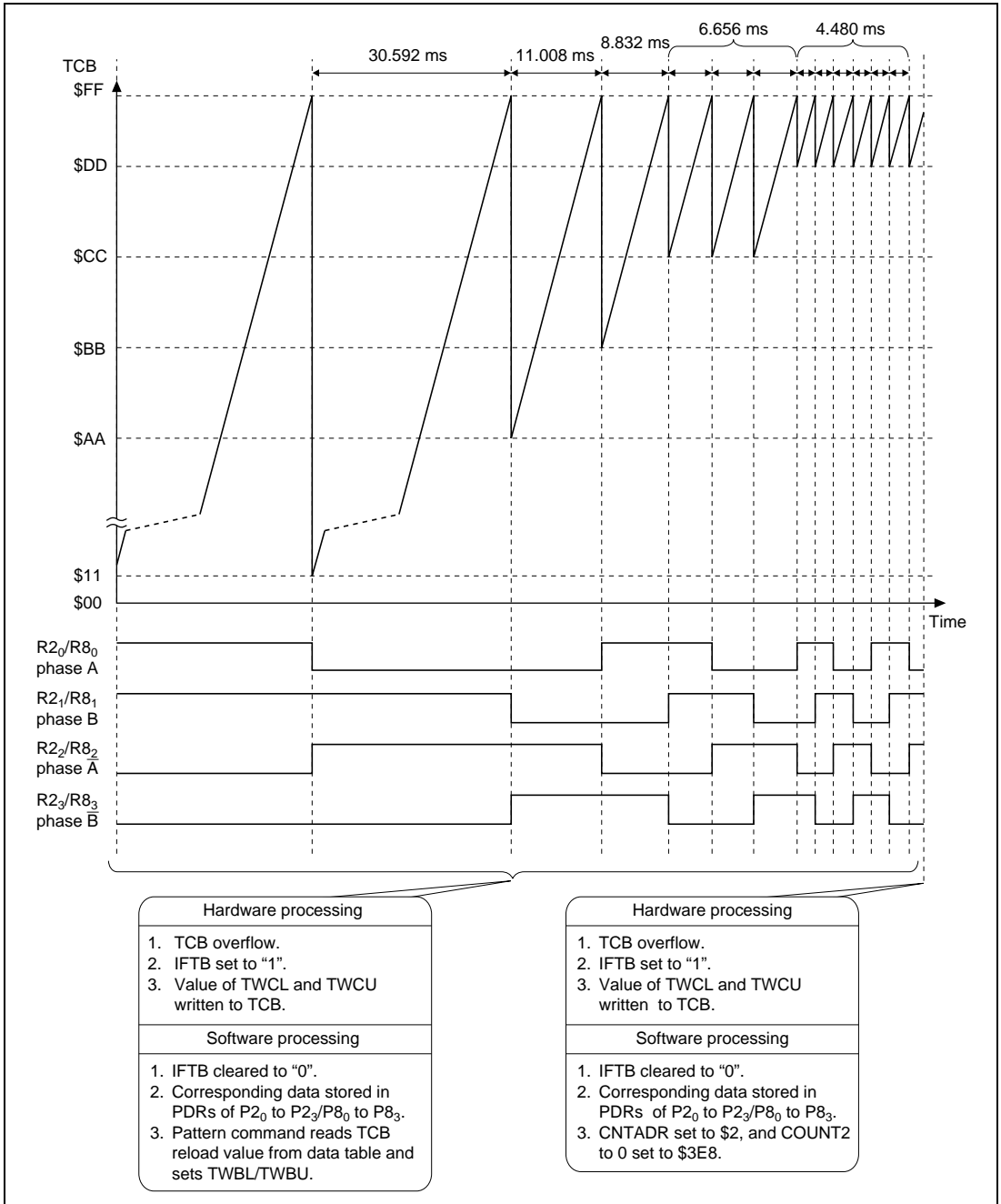


Figure 14 Operating Principle of Slue up Control When Motor Running Clockwise

4. Figure 15 shows the operating principle of Constant control when the motor is running clockwise.

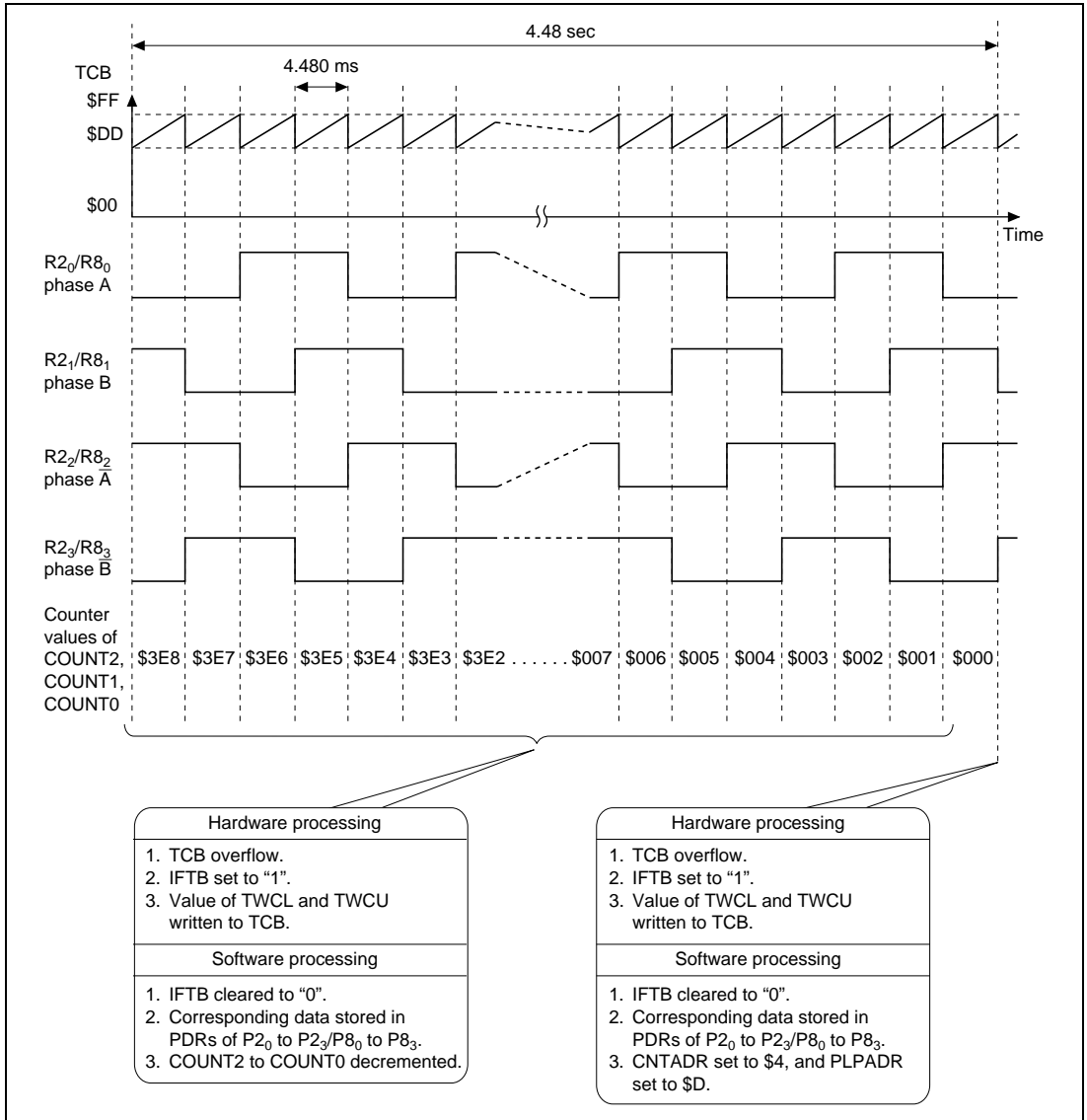


Figure 15 Operating Principle of Constant Control When Motor Running Clockwise

5. Figure 16 shows the operating principle of Slue down control when the motor is running clockwise.

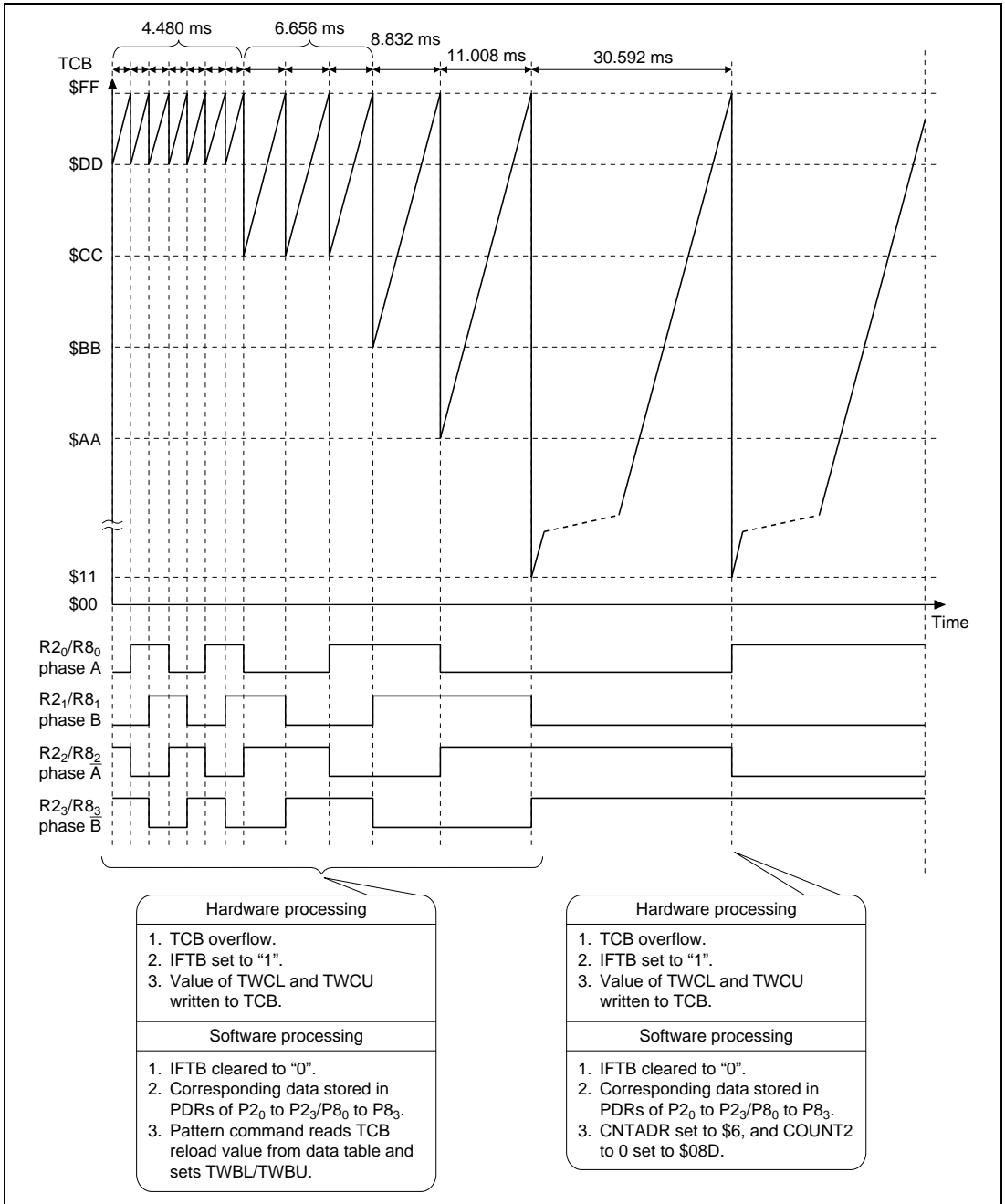


Figure 16 Operating Principle of Slue down Control When Motor Running Clockwise

6. Figure 17 shows the operating principle of Stop control when the motor is running clockwise.

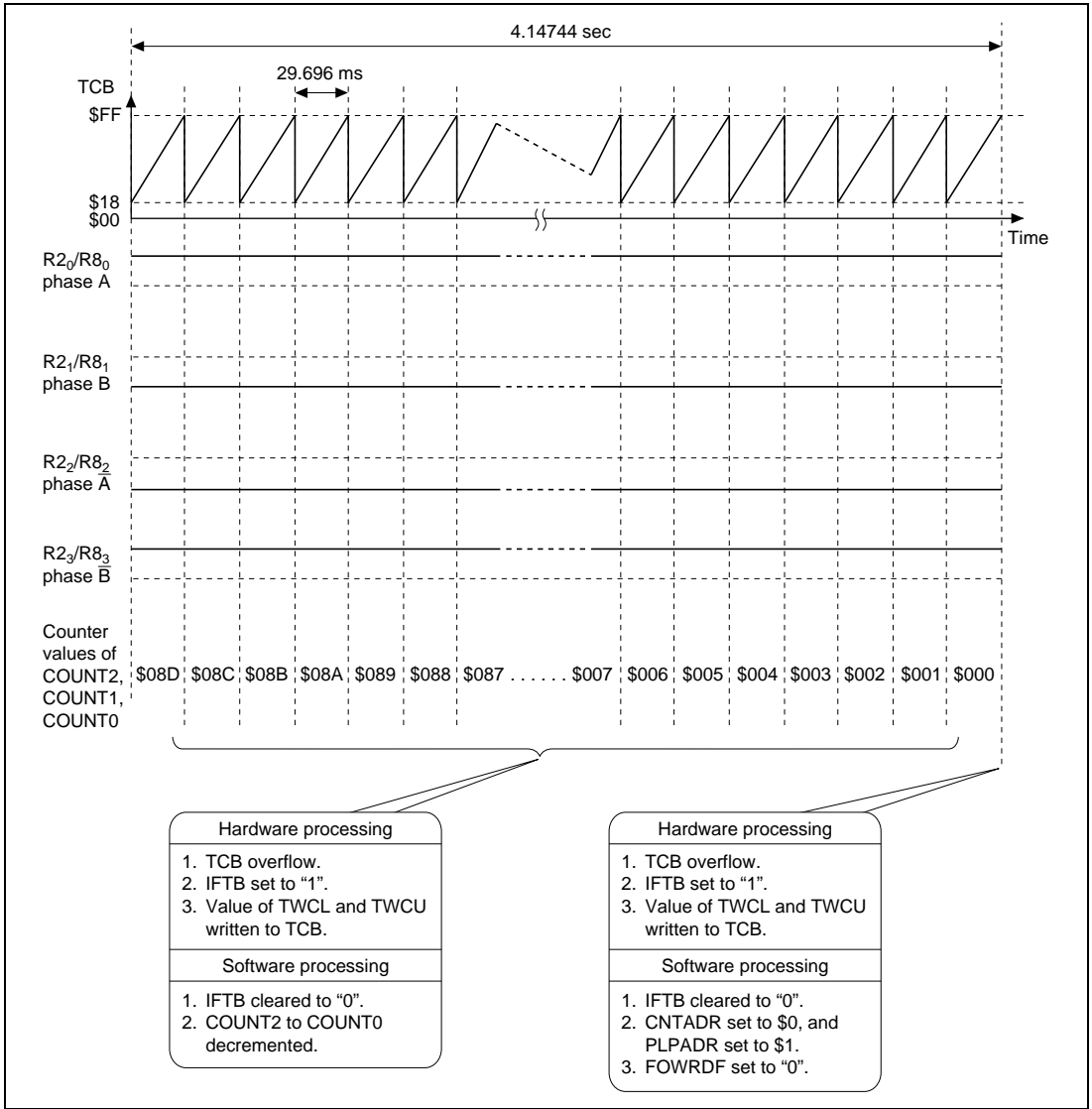


Figure 17 Operating Principle of Stop Control When Motor Running Clockwise

7. Figure 18 shows the operating principle of Slue up control when the motor is running counterclockwise.

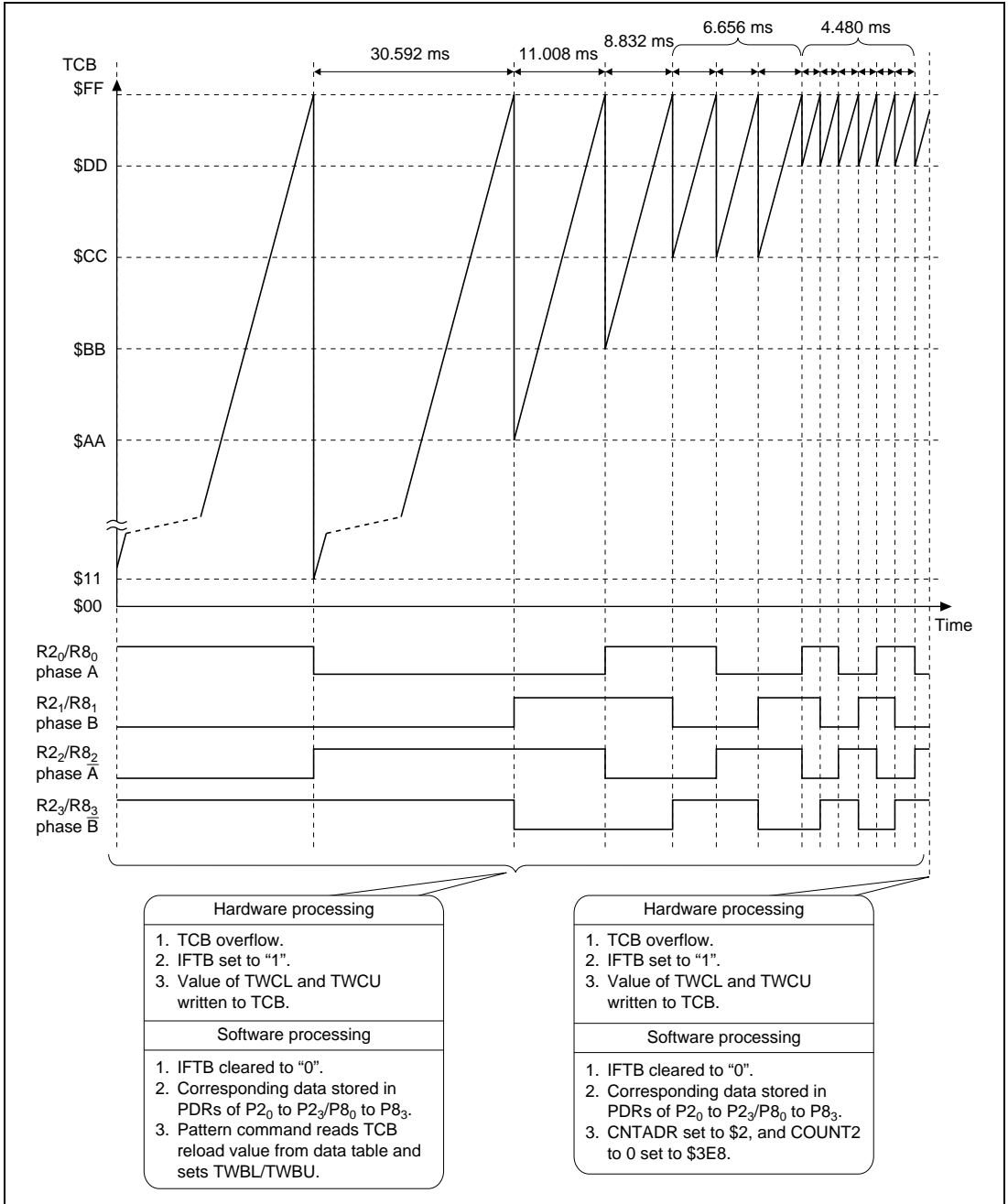


Figure 18 Operating Principle of Slue up Control When Motor Running Counterclockwise

8. Figure 19 shows the operating principle of Constant control when the motor is running counterclockwise.

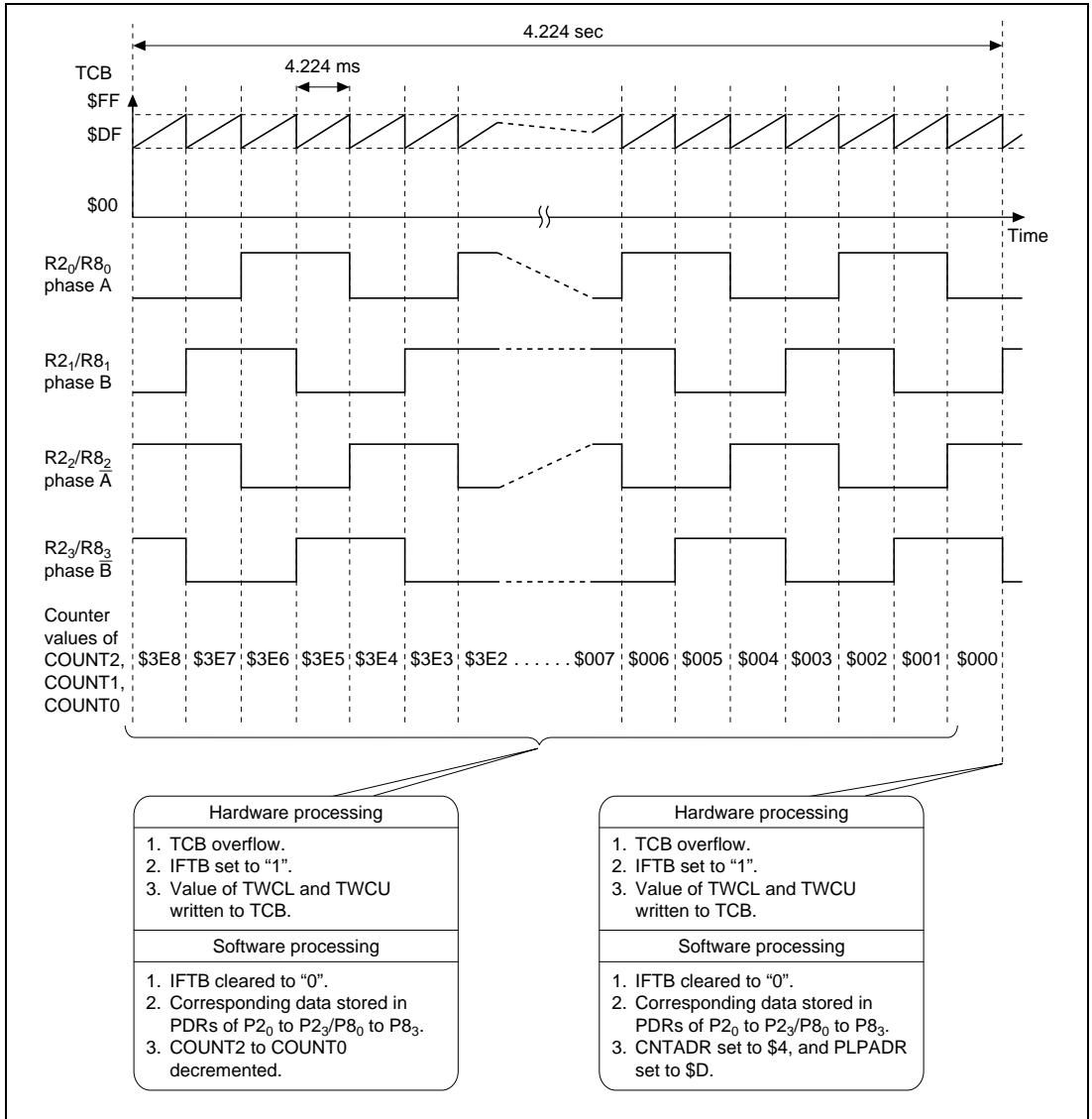


Figure 19 Operating Principle of Constant Control When Motor Running Counterclockwise

9. Figure 20 shows the operating principle of Slue down control when the motor is running counterclockwise.

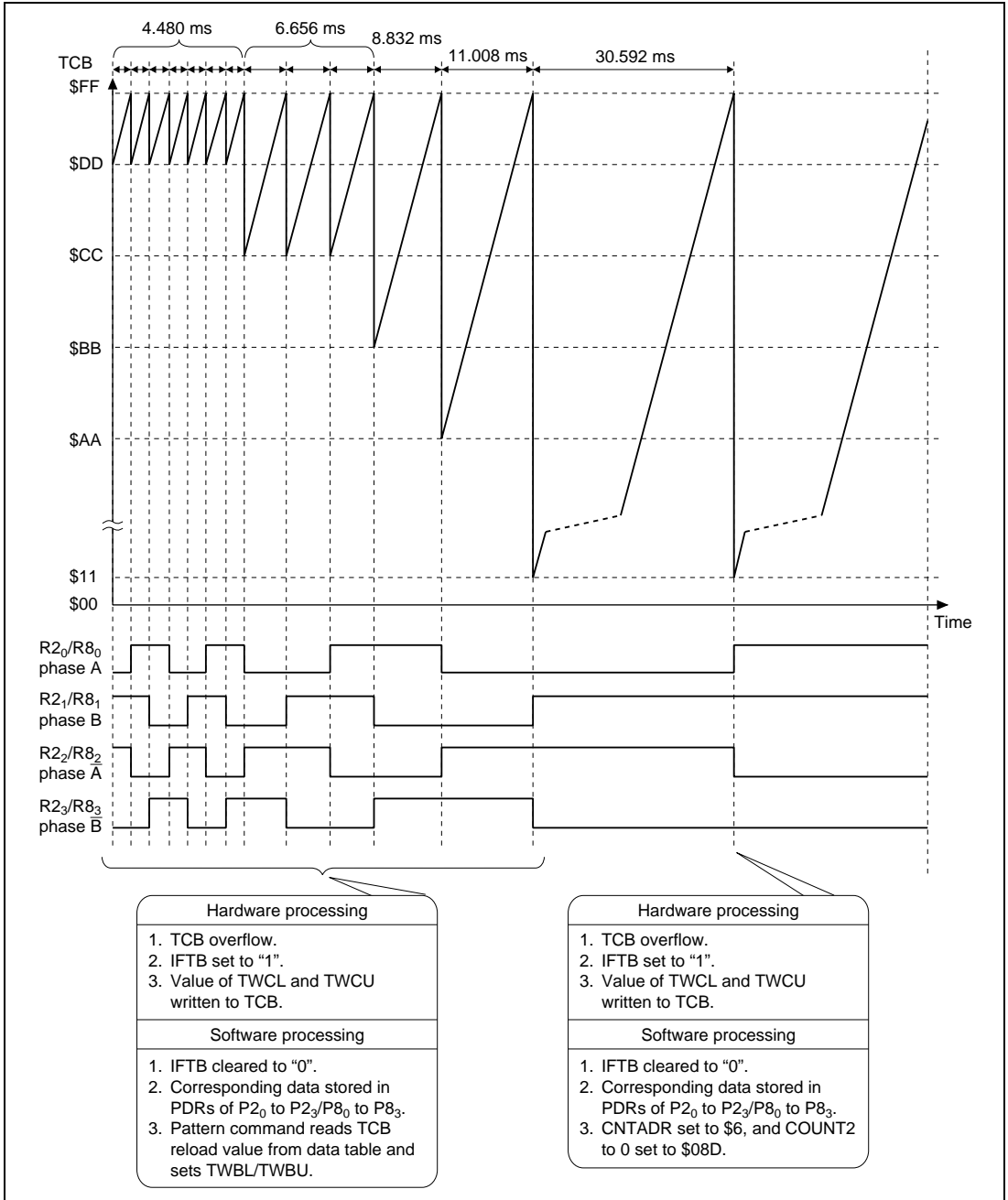


Figure 20 Operating Principle of Slue down Control When Motor Running Counterclockwise

10. Figure 21 shows the operating principle of Stop control when the motor is running counterclockwise.

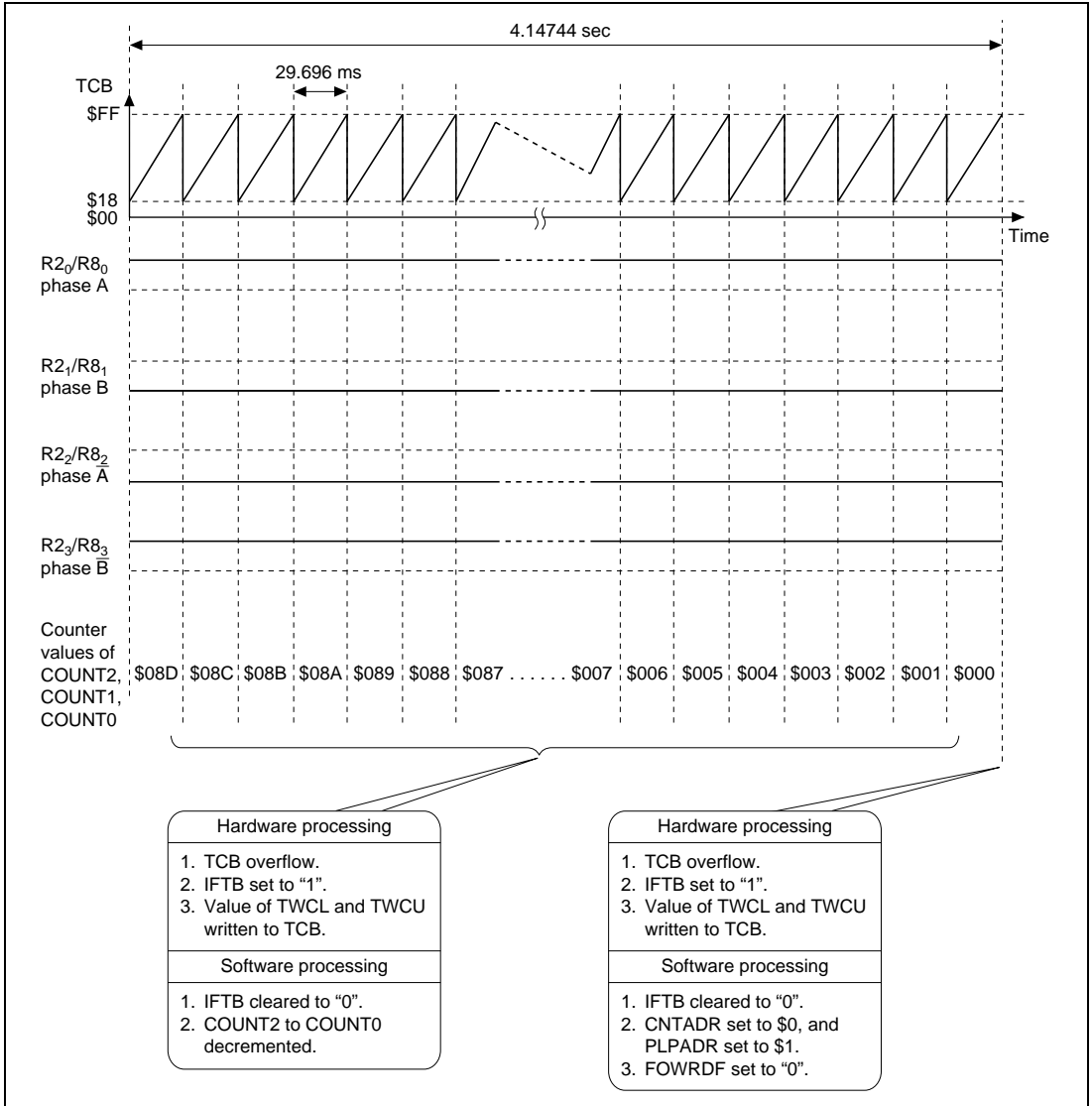


Figure 21 Operating Principle of Stop Control When Motor Running Counterclockwise

Description of Functions

1. Description of Modules

Table 5 describes the modules used in this example task.

Table 5 **Description of Modules**

Module	Label	Function
Main routine	STEPMN	This routine makes the initial stack pointer, RAM, I/O port, and timer B settings, performs initial stepping motor control, and enables interrupts.
Timer B interrupt processing routine	STPCNT	This routine saves the contents of the registers, makes table branch settings, and restores the registers.
Pulse output subroutine table	PLOUT	Branches to the subroutine for pulse output (POUT).
Decrement subroutine table	DEC	Branches to the subroutine for decrementing the count (DECR).
Pulse output	POUT	Rotates the output pulse data and stores it in the PDR of the output port.
Decrement	DECR	Decrements the 12-bit counter made up of COUNT2, COUNT1, and COUNT0.
Slue up control	SLUP	Reads the timer B reload value data using the pattern command and, by increasing the output pulse cycle, performs Slue up control of the stepping motor.
Constant control	CNST	Performs Constant control of the stepping motor by maintaining the output pulse cycle at a constant rate.
Slue down control	SLDOWN	Reads the timer B reload value data using the pattern command and, by decreasing the output pulse cycle, performs Slue down control of the stepping motor.
Stop control	STOP	Performs Stop control by stopping the pulse output.

2. Description of Arguments

No arguments are used in this example task.

3. Description of Internal Registers

a. Table 6 describes the internal registers used in the H4344.

Table 6 Internal Registers Used in H4344/H4318/H4359/H4369

Register	Description	RAM Address	Setting
IE	Interrupt Enable Flag This flag controls reception of all interrupts by the CPU. <ul style="list-style-type: none"> When IE = "0", CPU reception of all interrupts is disabled. When IE = "1", CPU reception is enabled. 	0, \$000	1
RSP	Reset Stack Pointer Clearing RSP to "0" initializes the stack pointer.	1, \$000	0
IFTB	Timer B Interrupt Request Flag Reflects the existence of a timer B interrupt request. <ul style="list-style-type: none"> When IFTB = "0", no timer B interrupt is requested. When IFTB = "1", a timer B interrupt is requested. 	0, \$002	0
IMTB	Timer B Interrupt Mask This bit masks IFTB. <ul style="list-style-type: none"> When IMTB = "0", IFTB is enabled. When IMTB = "1", IFTB is masked. 	1, \$001	1
TMB1	Timer Mode Register B1 TMB13 selects the timer B functions. TMB12 to TMB10 select the operating clock. <ul style="list-style-type: none"> When TMB13 = "1", TMB12 = "0", TMB11 = "1", and TMB10 = "0", timer B functions as a reload timer, and the operating clock for timer B is set to the system clock divided by 128. 	\$009	\$A
TWBL	Timer Write Register BL Sets the lower digit of the TCB reload value.	\$00A	\$8
TWBU	Timer Write Register BU Sets the upper digit of the TCB reload value.	\$00B	\$1

Table 6 Internal Registers Used in H4344/H4318/H4359/H4369 (cont)

Register	Description	RAM Address	Setting
TMB2	<p>Timer Mode Register B2</p> <p>Sets the input capture function and selects the detection edge for EVNB pin input.</p> <ul style="list-style-type: none"> When TMB22 = "0", timer B functions as a free-running/reload timer. When TMB22 = "1", timer B functions as an input capture timer. <p>Note: TMB22 is not used in the H4344.</p> <ul style="list-style-type: none"> When TMB21 = "0" and TMB20 = "0", no edge detection is performed on EVNB pin input. 	\$026	\$0
SSR1	<p>System Clock Selection Register 1</p> <p>Sets the oscillation frequency of the system clock, sets the division for the subsystem clock frequency, and sets the subsystem clock oscillation in stop mode.</p> <ul style="list-style-type: none"> When SSR11 = "0", the system clock oscillation frequency is set to 0.4 to 1MHz. When SSR11 = "1", the system clock oscillation frequency is set to 1.6 to 5 MHz. <p>Note: Applies only to H4369.</p>	\$027	\$2
DCR2	<p>Data Control Register R2</p> <p>Controls the ON/OFF switching of the R2 port output buffer.</p> <ul style="list-style-type: none"> When DCR23 to DCR20 = "0", the output buffers of R2₃ to R2₀ are OFF and R2₃ to R2₀ pins are set to high impedance. When DCR23 to DCR20 = "1", the output buffers of R2₃ to R2₀ are ON and the values of the corresponding PDRs are output. <p>Note: Applies to H4344 only.</p>	\$032	\$F
DCR8	<p>Data Control Register R8</p> <p>Controls the ON/OFF switching of the R8 port output buffer.</p> <ul style="list-style-type: none"> When DCR83 to DCR80 = "0", the output buffers of R8₃ to R8₀ are OFF, and R8₃ to R8₀ pins are set to high impedance. When DCR83 to DCR80 = "1", the output buffers of R8₃ to R8₀ are ON and the values of the corresponding PDRs are output. <p>Note: Applies to H4318/H4359/H4369 only.</p>	\$038	\$F

b. Table 7 describes the internal registers used in the H4889.

Table 7 Internal Registers Used in H4889

Register	Description	RAM Address	Setting
IE	Interrupt Enable Flag This flag controls reception of all interrupts by the CPU. <ul style="list-style-type: none"> When IE = "0", CPU reception of all interrupts is disabled. When IE = "1", CPU reception is enabled. 	0, \$000	1
RSP	Reset Stack Pointer Clearing RSP to "0" initializes the stack pointer.	1, \$000	0
IFTB	Timer B Interrupt Request Flag Reflects the existence of a timer B interrupt request. <ul style="list-style-type: none"> When IFTB = "0", no timer B interrupt is requested. When IFTB = "1", a timer B interrupt is requested. 	2, \$002	0
IMTB	Timer B Interrupt Mask This bit masks IFTB. <ul style="list-style-type: none"> When IMTB = "0", IFTB is enabled. When IMTB = "1", IFTB is masked. 	3, \$002	1
SSR	System Clock Selection Register Selects the system clock oscillation frequency, subsystem clock frequency division, and, in stop mode, the subsystem clock oscillation and system clock frequency division ratio. <ul style="list-style-type: none"> When SSR1 = "0", the system clock oscillation frequency is set to 0.4 to 1 MHz. When SSR1 = "1", the system clock oscillation frequency is set to 1.6 to 4.5 MHz. 	\$004	\$2
PMR3	Port Mode Register 3 Sets the functions of the R2 ₂ /SI/SO pin, R2 ₇ /SCK pin, and R2 ₀ /TOC pin. <ul style="list-style-type: none"> When PMR33 = "0", PMR32 = "0", PMR31 = "0" and PMR30 = "0", the R2₂/SI/SO pin functions as R2₂ I/O pin, R2₇/SCK functions as R2₁ I/O pin, and R2₀/TOC functions as R2₀ I/O pin. 	\$00B	\$0

Table 7 Internal Registers Used in H4889 (cont)

Register	Description	RAM Address	Setting
TMB1	<p>Timer Mode Register B1</p> <p>TMB13 selects the timer B function, TMB12 to TMB10 select the operating clock.</p> <ul style="list-style-type: none"> When TMB13 = "1", TMB12 = "0", TMB11 = "1", and TMB10 = "0", timer B functions as a reload timer, and the timer B clock is the system clock divided by 128. 	\$010	\$A
TMB2	<p>Timer Mode Register B2</p> <p>Sets the timer B output mode and selects the detection edge for EVNB pin input.</p> <ul style="list-style-type: none"> When TMB22 = "0", timer B output is set to toggle waveform. When TMB22 = "1", timer B output is set to PWM. When TMB21 = "0" and TMB20 = "0", no edge detection is performed on EVNB pin input. 	\$011	\$0
TWBL	<p>Timer Write Register BL</p> <p>Sets the lower digit of the TCB reload value.</p>	\$012	\$8
TWBU	<p>Timer Write Register BU</p> <p>Sets the upper digit of the TCB reload value.</p>	\$013	\$1
DCR8	<p>Data Control Register 8</p> <p>Controls the ON/OFF switching of the R8 port output buffer.</p> <ul style="list-style-type: none"> When DCR83 to DCR80 = "0", the output buffers of R8₃ to R8₀ are OFF, and the output pins are set to high impedance. When DCR83 to DCR80 = "1", the output buffers of R8₃ to R8₀ are ON and the values of the corresponding PDRs are output. 	\$03C	\$F

4. Description of RAM

Table 8 describes the RAM used in this example task.

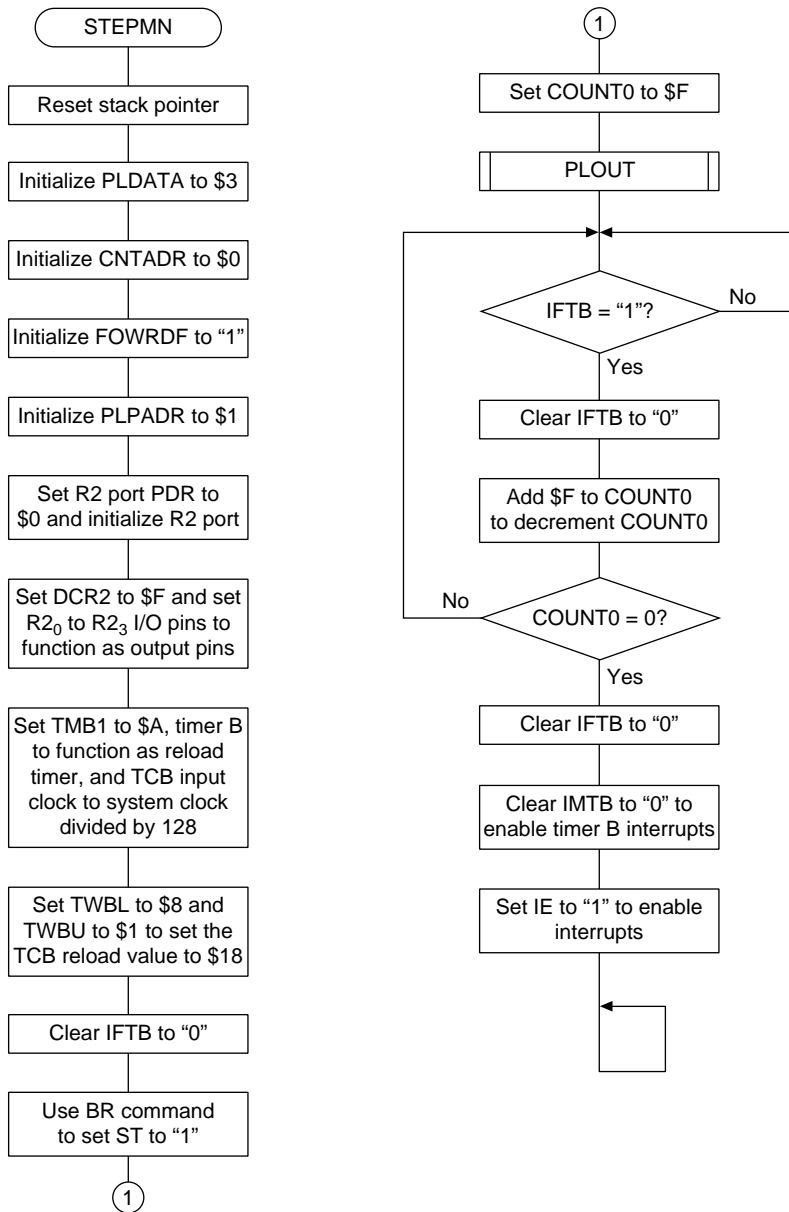
Table 8 **RAM**

Label	Function	RAM Address	Module
AESC	Stores the contents of the accumulator during timer B interrupt processing.	\$040	STEPCNT
BESC	Stores the contents of the B register during timer B interrupt processing.	\$041	STEPCNT
XESC	Stores the contents of the X register during timer B interrupt processing.	\$043	STEPCNT
YESC	Stores the contents of the Y register during timer B interrupt processing.	\$044	STEPCNT
PLDATA	Stores the data for the pulse output from the port.	\$050	STEPMN, POUT
CNTADR	Stores the contents of the accumulator used for specifying the address when executing a table branch command.	\$051	STEPMN, SLUP, CNST, SLDOWN, STOP, STEPCNT
PLPADR	Stores the contents of the accumulator used for specifying the address when executing a pattern command.	\$052	STEPMN, SLUP, CNST, SLDOWN, STOP
COUNT0	Stores bits 3 to 0 of the 12-bit counter made up of COUNT0, COUNT1, COUNT2.	\$053	STEPMN, SLUP, SLDOWN, DECR
COUNT1	Stores bits 7 to 4 of the 12-bit counter made up of COUNT0, COUNT1, COUNT2.	\$054	SLUP, SLDOWN, DECR
COUNT2	Stores bits 11 to 8 of the 12-bit counter made up of COUNT0, COUNT1, COUNT2.	\$055	SLUP, SLDOWN, DECR
FOWRDF	This flag is used to identify the direction (CW or CCW) of the stepping motor.	0, \$05F	STEPMN, STOP, POUT

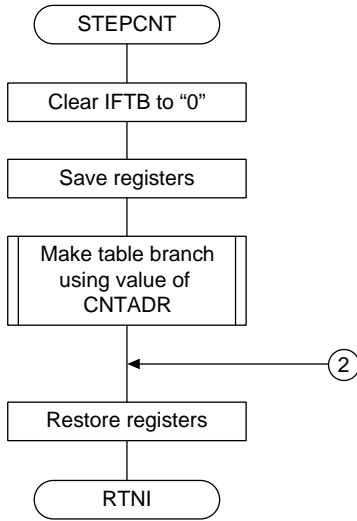
Flow charts

1. H4344

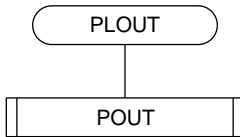
a. Main Routine



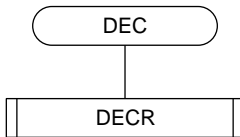
b. Timer B Interrupt Processing Routine



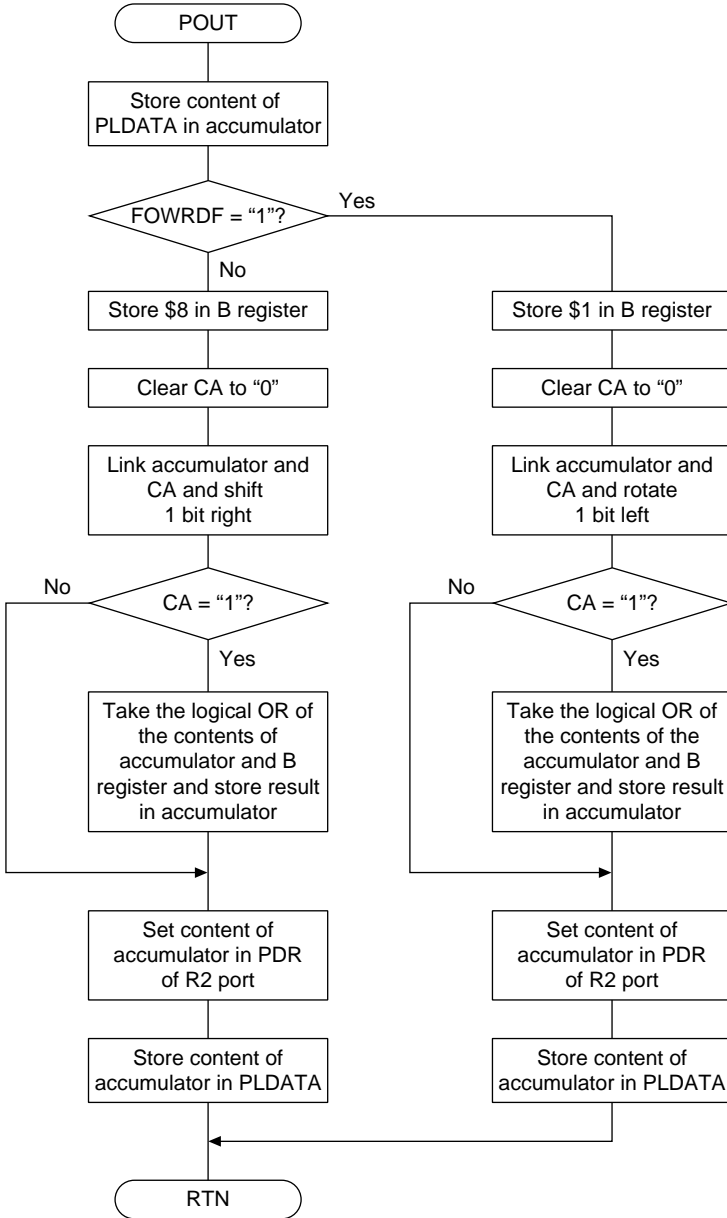
c. Pulse Output



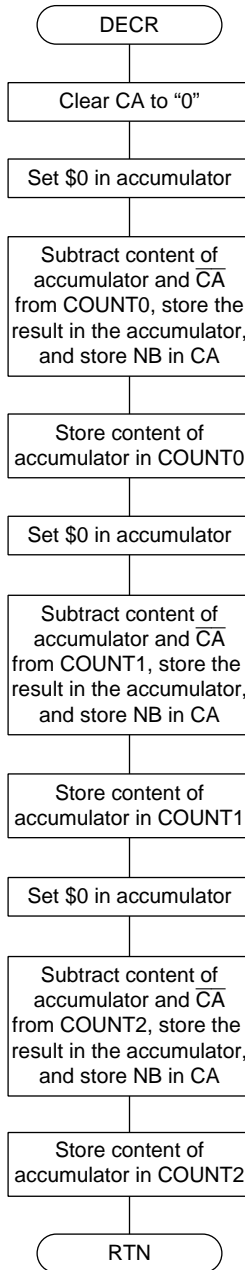
d. Decrement



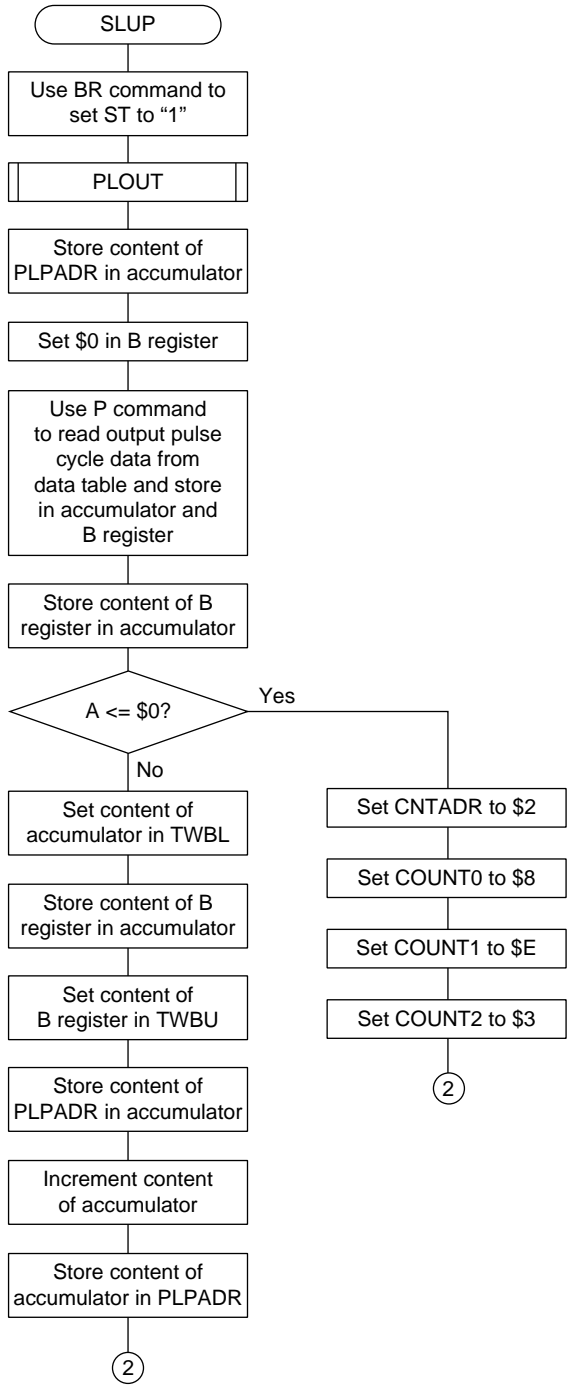
e. Pulse Output



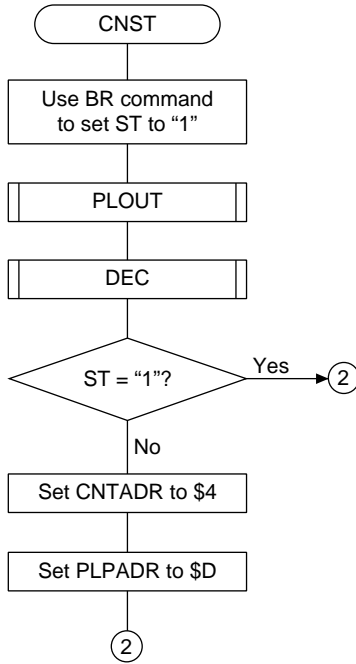
f. Decrement



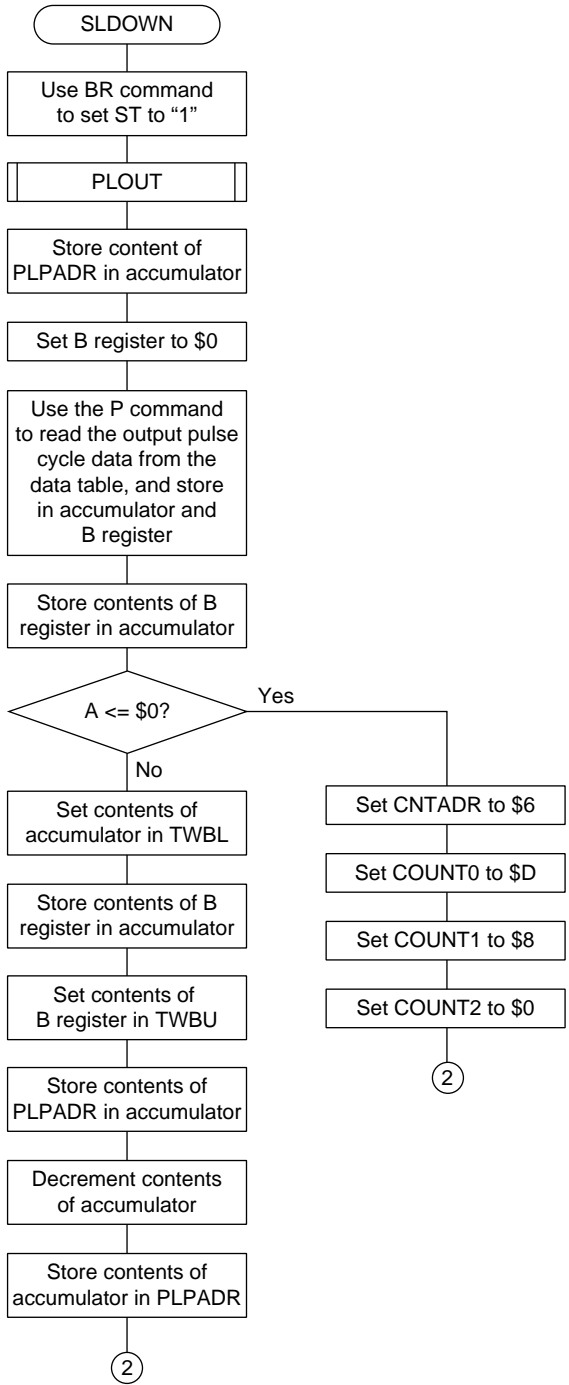
g. Slue Up Control



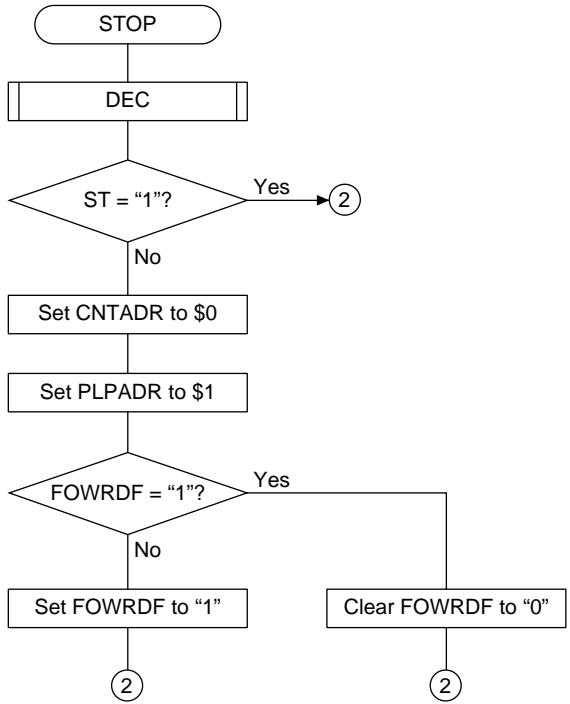
h. Constant Control



i. Slow Down Control

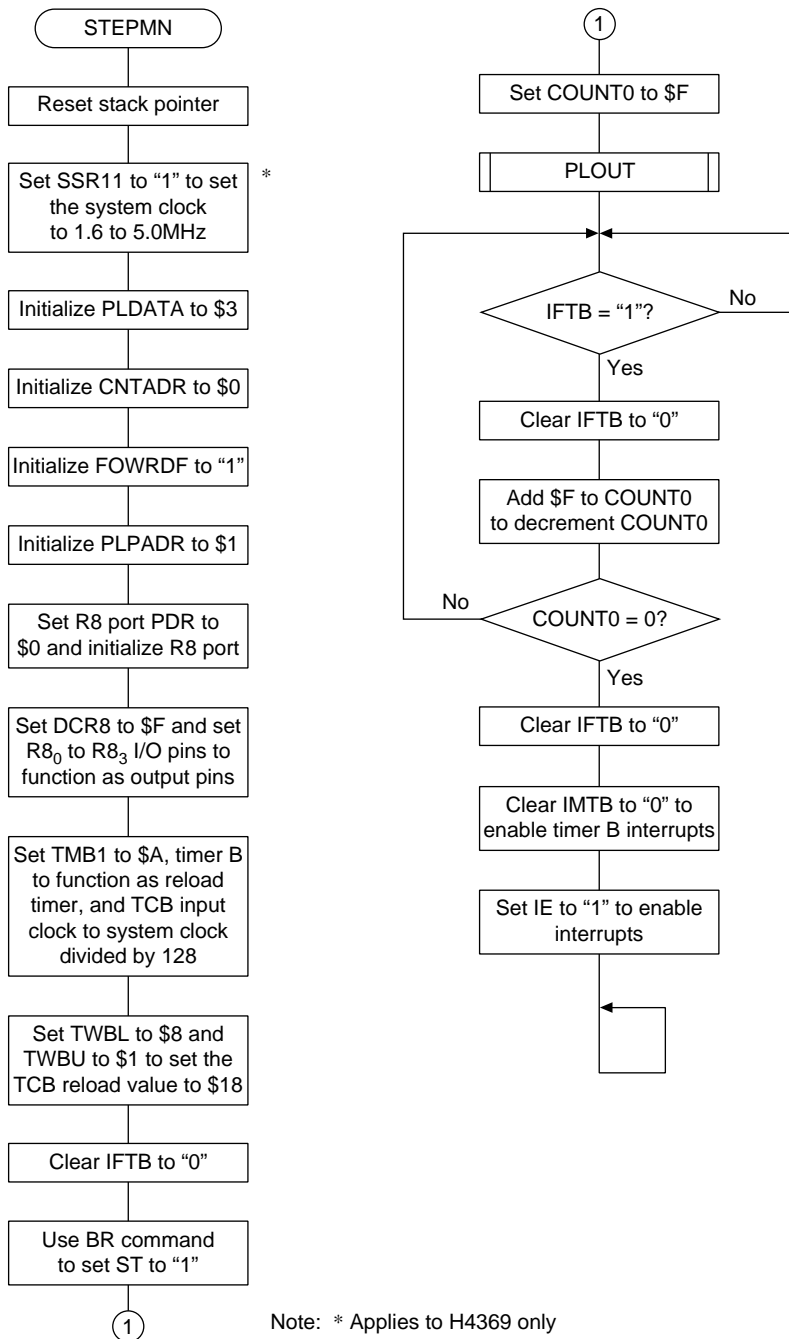


j. Stop Control

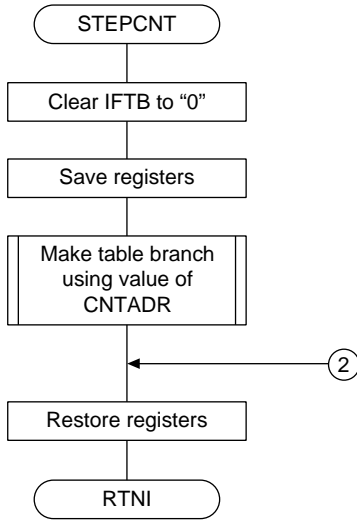


2. H4318/H4359/H4369

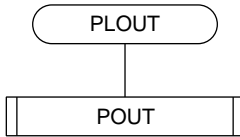
a. Main Routine



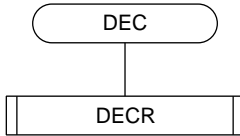
b. Timer B Interrupt Processing Routine



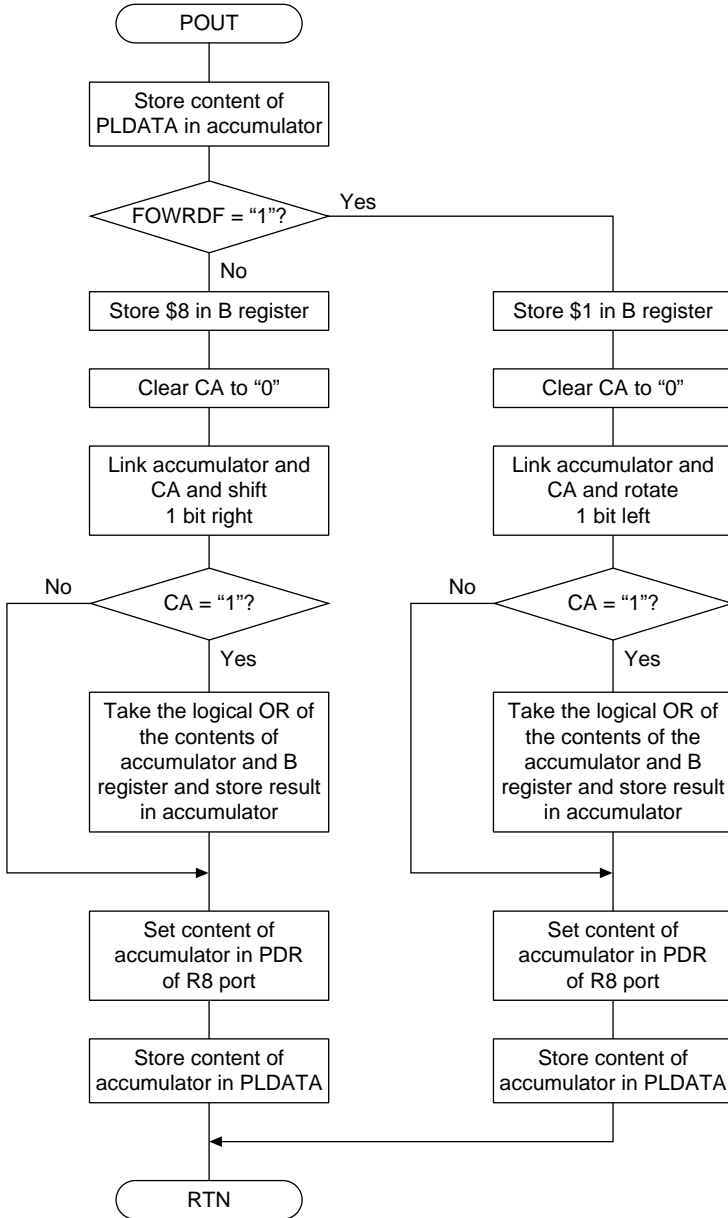
c. Pulse Output



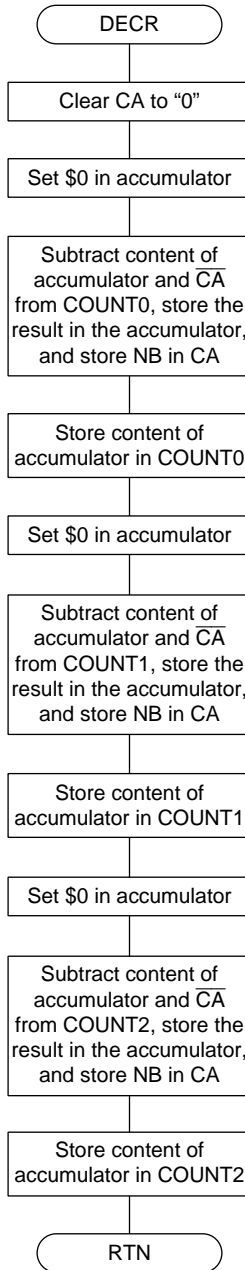
d. Decrement



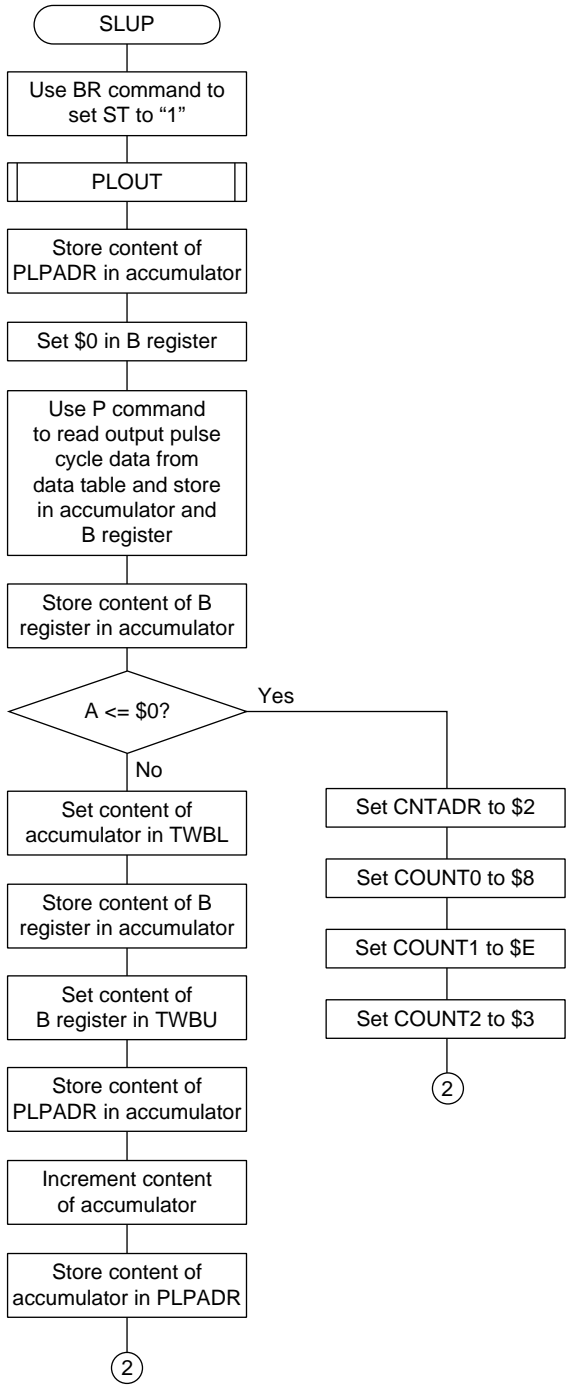
e. Pulse Output



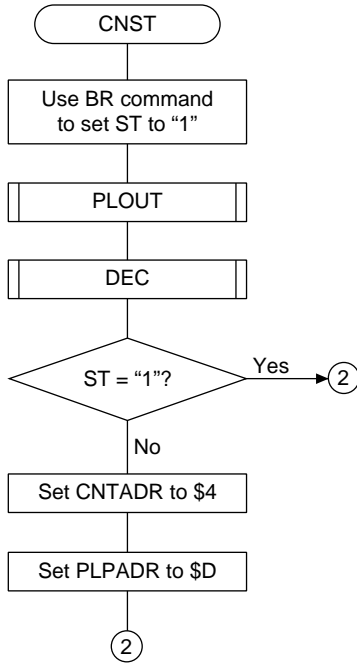
f. Decrement



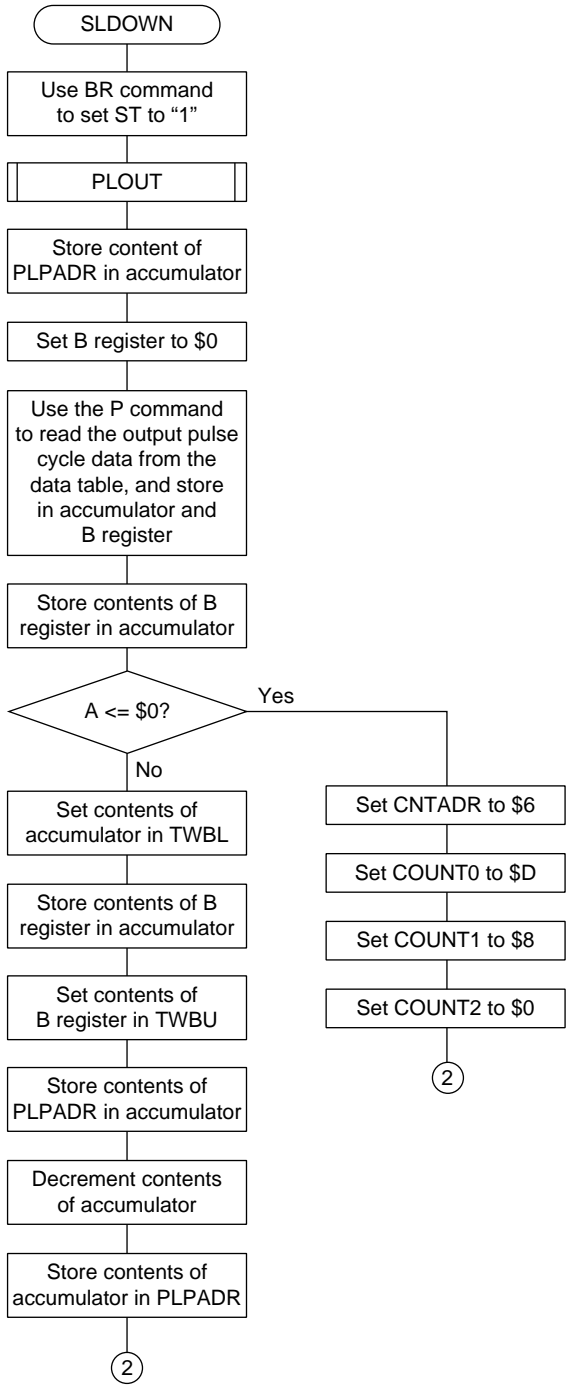
g. Slue Up Control



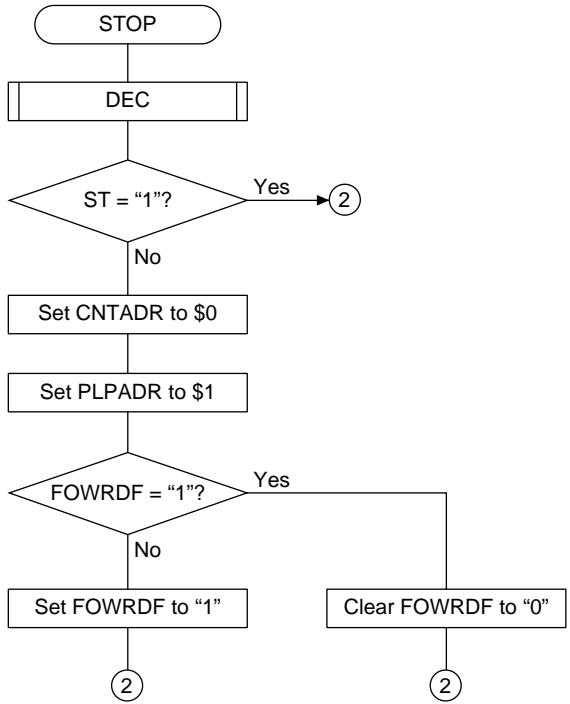
h. Constant Control



i. Slue Down Control

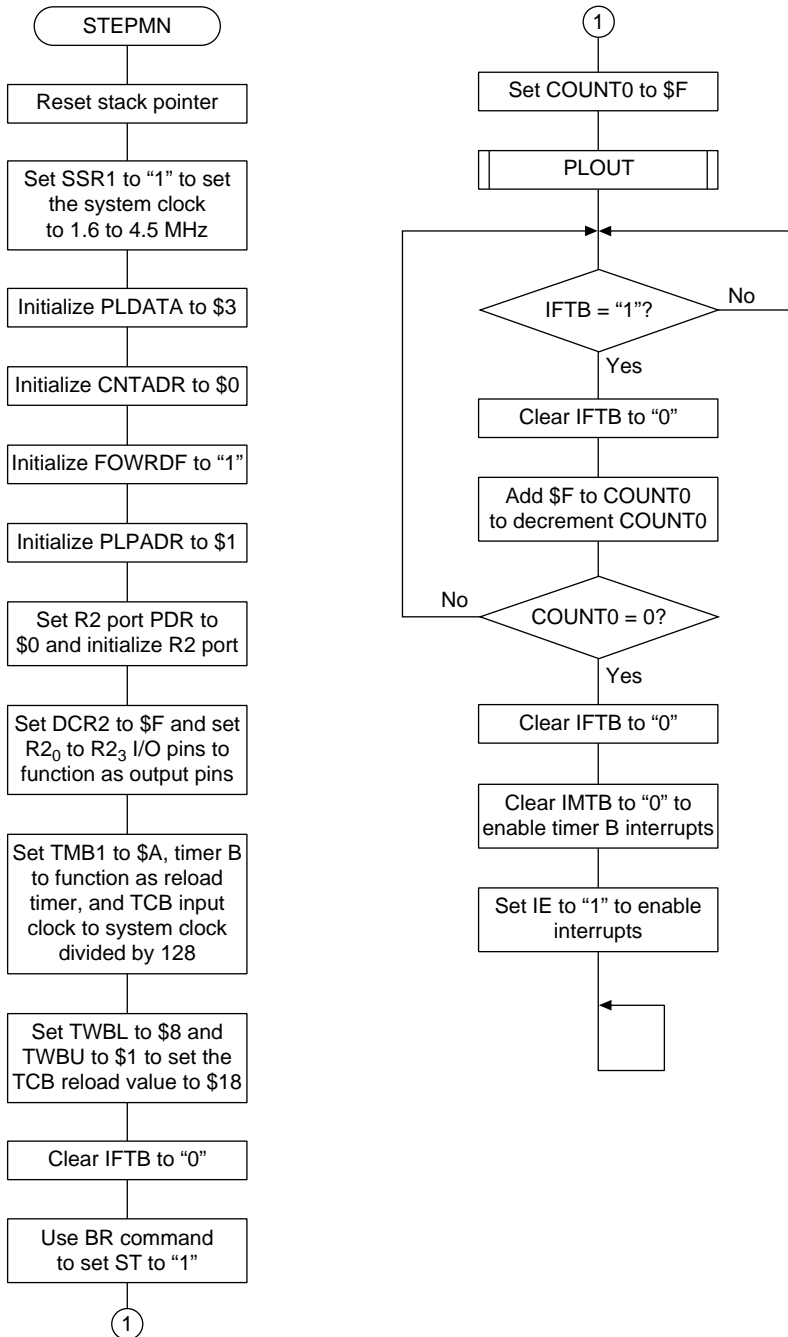


j. Stop Control

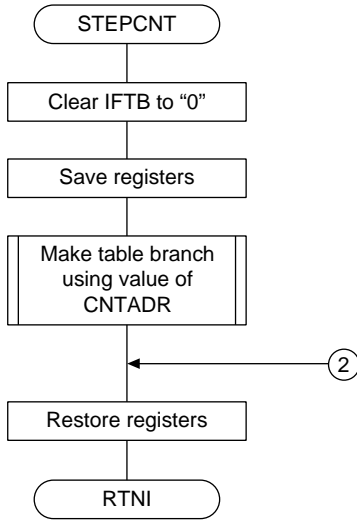


3. H4889

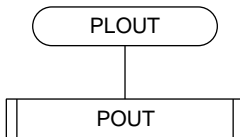
a. Main Routine



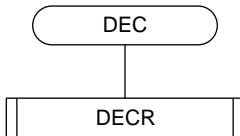
b. Timer B Interrupt Processing Routine



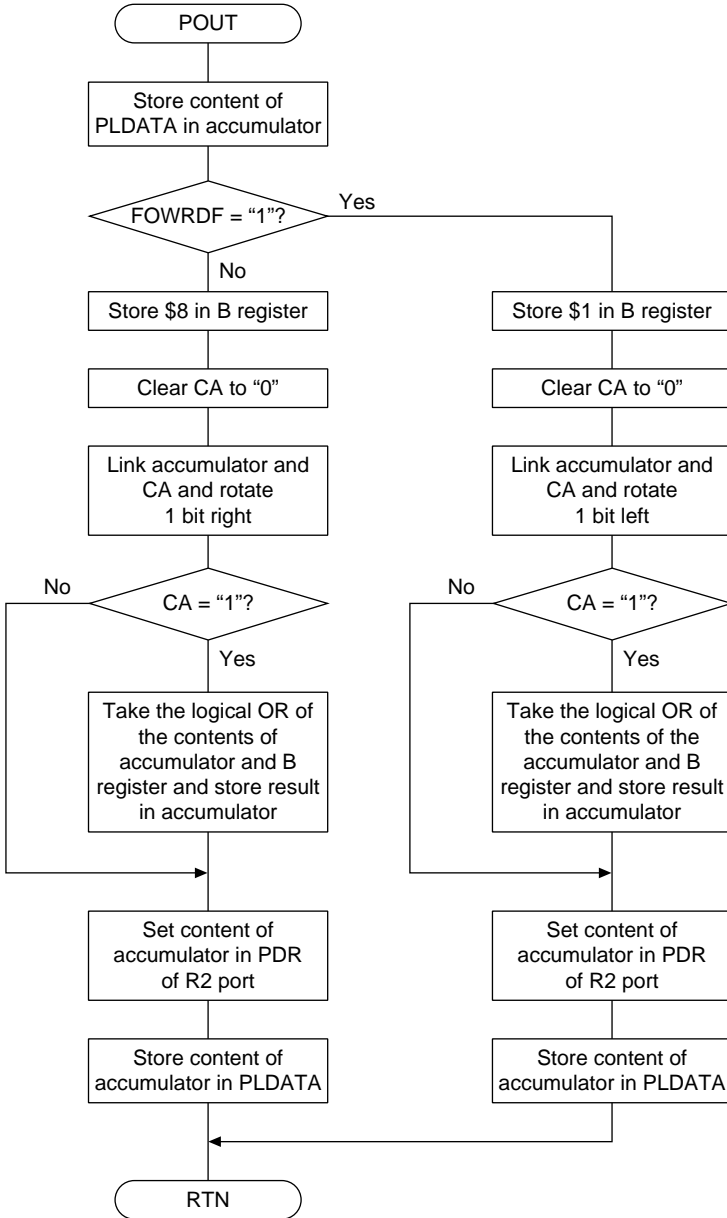
c. Pulse Output



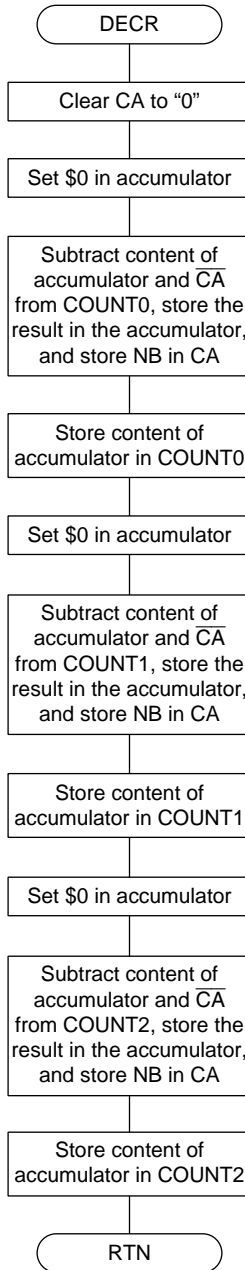
d. Decrement



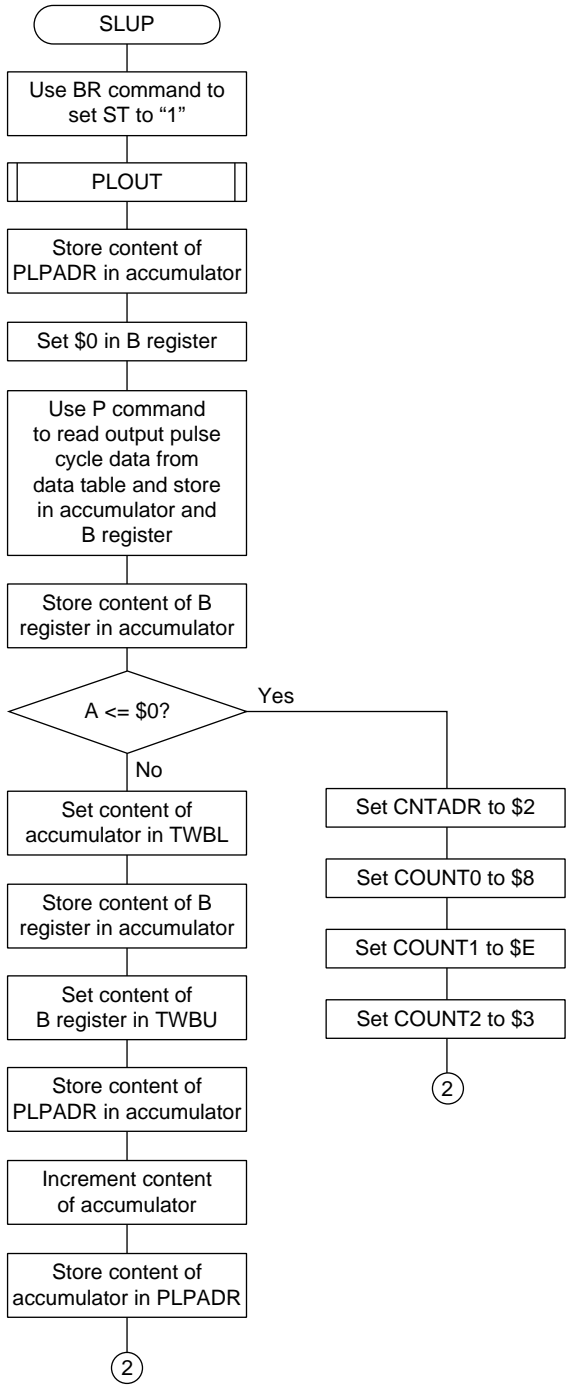
e. Pulse Output



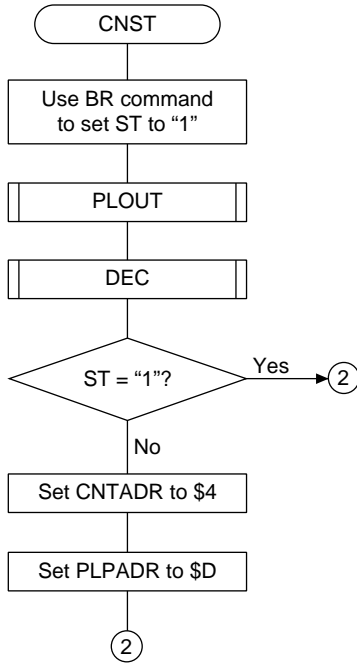
f. Decrement



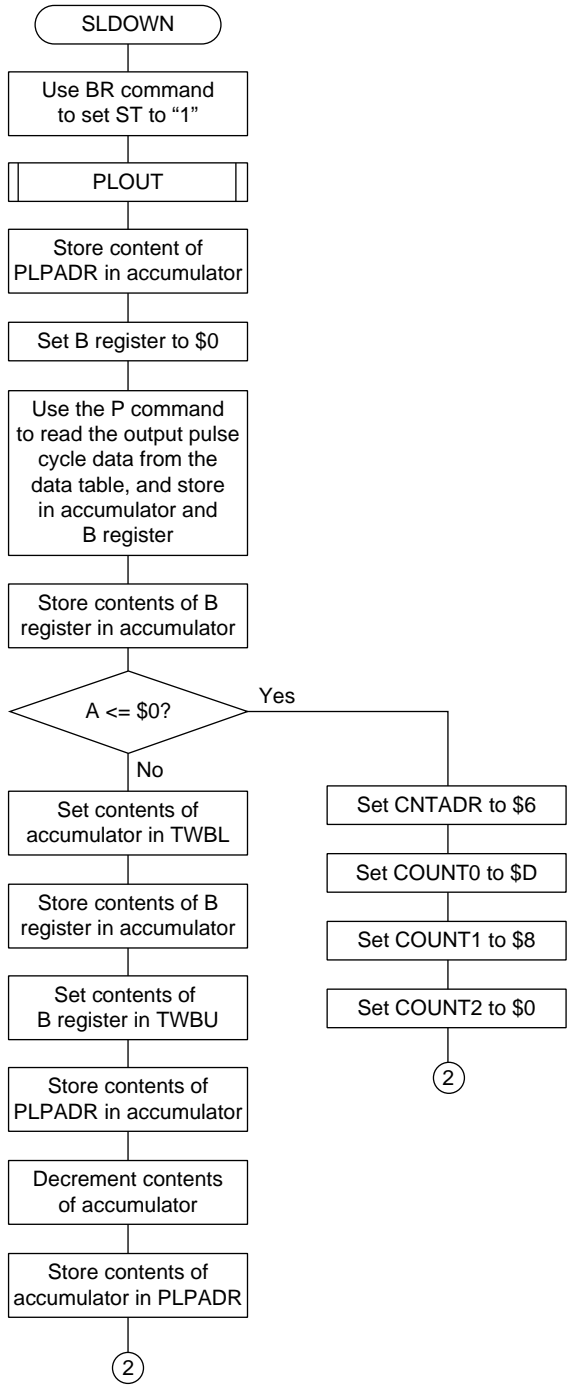
g. Slue Up Control



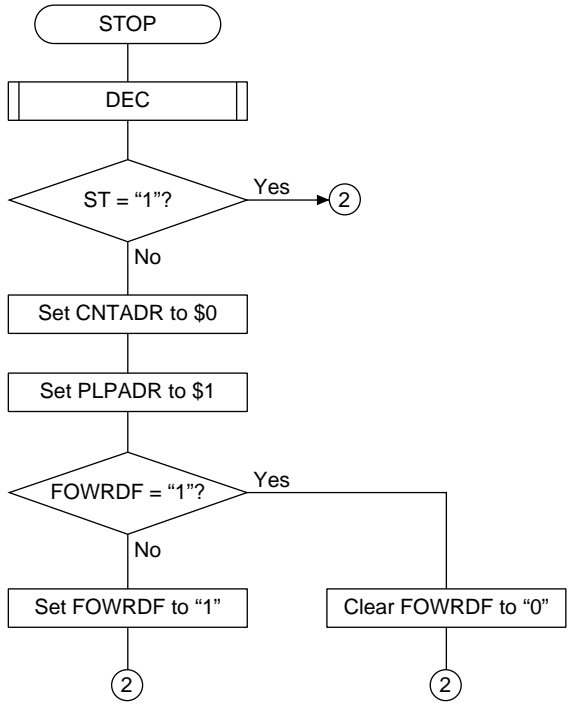
h. Constant Control



i. Slow Down Control



j. Stop Control



Program Listing

1. H4344

```
*****
*
*       H400 Series Application Note
*       - Application Chapter -
*
*       'Stepping Motor Control'
*
*       Function
*       : Timer B Reload Timer
*       : I/O Port
*
*       MCU : H4344
*
*       External Clock : 4MHz
*       Internal Clock : 1MHz
*
*****
*
*****
*       Symbol Definition
*****
*
IE       equ     0,$000    Interrupt Enable Flag
RSP      equ     1,$000    Reset Stack Pointer
IF0      equ     2,$000    INTO Interrupt Request Flag
IM0      equ     3,$000    INTO Interrupt Mask
*
IFTB     equ     0,$002    TIMER B Interrupt Request Flag
IMTB     equ     1,$002    TIMER B Interrupt Mask
IFTC     equ     2,$002    TIMER C Interrupt Request Flag
IMTC     equ     3,$002    TIMER C Interrupt Mask
*
IFAD     equ     0,$003    A/D Interrupt Request Flag
IMAD     equ     1,$003    A/D Interrupt Mask
IFS      equ     2,$003    SCI Interrupt Request Flag
IMS      equ     3,$003    SCI Interrupt Mask
*
PMRA     equ     $004      Port Mode Register A
SMR      equ     $005      Serial Mode Register
SRL      equ     $006      Serial Data Register L
SRU      equ     $007      Serial Data Register U
*
TMB1     equ     $009      Timer Mode Register B1
TRBL     equ     $00A      Timer Read Register BL
TWBL     equ     $00A      Timer Write register BL
TRBU     equ     $00B      Timer Read Register BU
TWBU     equ     $00B      Timer Write Register BU
```

```

MIS      equ      $00C      Miscellaneous Register
TMC      equ      $00D      Timer Mode Register C
TRCL     equ      $00E      Timer Read Register CL
TWCL     equ      $00E      Timer Write Register CL
TRCU     equ      $00F      Timer Read Register CU
TWCUC    equ      $00F      Timer Write Register CU
*
ACR      equ      $016      A/D Control Register
ADRL     equ      $017      A/D Data Register L
ADRU     equ      $018      A/D Data Register U
AMR1     equ      $019      A/D Mode Register 1
AMR2     equ      $01A      A/D Mode Register 2
*
WDON     equ      1,$020    Watchdog on Flag
ADSF     equ      2,$020    A/D Start Flag
*
IAOF     equ      2,$021    IAD off Flag
RAME     equ      3,$021    RAM Enable Flag
*
PMRB     equ      $024      Port Mode register B
PMRC     equ      $025      Port Mode Register C
TMB2     equ      $026      Timer Mode Register B2
DCD0     equ      $02C      Data Control Register D0
DCD1     equ      $02D      Data Control Register D1
*
DCR0     equ      $030      Data Control Register R0
DCR1     equ      $031      Data Control Register R1
DCR2     equ      $032      Data Control Register R2
DCR3     equ      $033      Data Control Register R3
*
*****
*          RAM Allocation
*****
*
AESC     equ      $040      A Escape RAM Area
BESC     equ      $041      B Escape RAM Area
WESC     equ      $042      W Escape RAM Area
XESC     equ      $043      X Escape RAM Area
YESC     equ      $044      Y Escape RAM Area
SXESC    equ      $045      SPX Escape RAM Area
SYESC    equ      $046      SPY Escape RAM Area
*
PLDATA   equ      $050      Pulse Data ($3 <-> $6 <-> $C <-> $9)
CNTADR   equ      $051      Control Process Address
PLPADR   equ      $052      Pulse Period Address
COUNT0  equ      $053      Counter 0
COUNT1  equ      $054      Counter 1
COUNT2  equ      $055      Counter 2
*
FOWRDF   equ      0,$05F    Forward Flag( 1:Forward, 0:Reverse )
*

```

* Vector Address

*

org \$0000

*

JMPL STEPMN Reset Interrupt
JMPL STEPMN INT0 Interrupt

*

org \$0008

*

JMPL STEPCNT Timer B Interrupt
JMPL STEPMN Timer C Interrupt
JMPL STEPMN A/D Interrupt
JMPL STEPMN SCI Interrupt

*

* STEPMN : Main Program

*

org \$1000

*

STEPMN REMD RSP Stack Pointer Reset

*

LMID \$3,PLDATA Initialize Pulse Data
LMID \$0,CNTADR Initialize Control Process Address
SEMD FOWRDF Set Forward Mode
LMID \$1,PLPADR Initialize Pulse Period Address

*

LAI \$0 Initialize R2 Port Data Register
LRA \$2
LMID \$F,DCR2 Initialize R2 Port Output Terminal Function

*

LMID \$A,TMB1 Initialize Timer B (128tcyc,Reload Timer ON)
LMID \$8,TWBL Initialize Period 29.696ms
LMID \$1,TWBU
REMD IFTB Clear Timer B Interrupt Request Flag

*

BR *+1 Set Status Flag
LMID \$F,COUNT0 Initialize Counter 0

STMN10 CAL PLOUT Subroutine Call 'PLOUT'

*

STMN11 TMD IFTB 29.696ms Pass ?
BRS STMN12 Yes. Branch to STMN12
BRS STMN11 No. Branch to STMN11

*

STMN12 REMD IFTB Clear IFTB
LAMD COUNT0 Load Counter 0
AI \$F Decrement Counter 0
LMAD COUNT0 Save Counter 0
BRS STMN10 16 times End ? No. Branch to STMN10

```

*
      REMD   IFTB   Clear Timer B Interrupt Request Flag
      REMD   IMTB   Timer B Interrupt Enable
      SEMD   IE     Interrupt Enable
*
STMN99  BRS     STMN99  Infinite Loop
*
*****
*       STEPCNT : Stepping Motor Control
*****
*
STEPCNT  REMD   IFTB   Clear Timer B Interrupt Request Flag
*
      LMAD   AESC   Store Accumulator
      LAB
      LMAD   BESC   Store B Register
      XSPX
      LASPX
      LMAD   XESC   Store X Register
      XSPX
      LAY
      LMAD   YESC   Store Y Register
*
      LAMD   CNTADR  Load Control Process Address
      LBI    $0
      TBR    $2     Table Branch (CNTADR=0:SLUP, 2:CNST, 4:SLDOWN, 6:STOP)
*
STCNT90  LAMD   YESC   Restore Y Register
      LYA
      LAMD   XESC   Restore X Register
      LXA
      LAMD   BESC   Restore B Register
      LBA
      LAMD   AESC   Restore Accumulator
*
      RTNI          Return from Interrupt
*
*****
*       SLUP : Slue up Control
*****
*
SLUP     BR      *+1   Set Status Flag
      CAL    PLOUT   Subroutine Jump to 'PLOUT'
      LAMD   PLPADR  Load Pulse Period Address
      LBI    $0
      P      $1     Pattern Generation 'Output Pulse Period'
      LAB
      ALEI   $0     A <= $0 ?
      BRS   SLUP10  Yes. Branch to SLUP10
      LMAD   TWBL   Set Pulse Period Data Lower
      LAB

```

```

LMAD TWBU Set Pulse Period Data Upper
LAMAD PLPADR Load Pulse Period Address
AI $1 Increment Pulse Period Address
LMAD PLPADR Save Pulse Period Address
BR *+1
BRS STCNT90 Branch to STCNT90
*
SLUP10 LMID $2,CNTADR Set Constant Control Mode
LMID $8,COUNT0 Initialize Counter0 to COUNT0
LMID $E,COUNT1 12-bit Counter = H'3E8 = D'1000
LMID $3,COUNT2
BRS STCNT90 Branch to STCNT90
*
*****
* CNST : Constant Control
*****
*
CNST BR *+1 Set Status Flag
CAL PLOUT Subroutine Jump to 'PLOUT'
*
CAL DEC Subroutine Jump to 'DEC'
BRS STCNT90 Counter = H'000 ? Yes. Branch to STCNT90
*
LMID $4,CNTADR Set Slue down Control Mode
LMID $D,PLPADR Set Pulse Period Address
BRS STCNT90 Branch to STCNT90
*
*****
* STDOWN : Slue down Control
*****
*
SLDOWN BR *+1 Set Status Flag
CAL PLOUT Subroutine Jump to 'PLOUT'
LAMAD PLPADR Load Pulse Period Address
LBI $0
P $1 Pattern Generation 'Output Pulse Period'
LAB
ALEI $0 A <= $0 ?
BRS SLDW10 Yes. Branch to SLDW10
LMAD TWBL Set Pulse Period Data Lower
LAB
LMAD TWBU Set Pulse Period Data Upper
LAMAD PLPADR Load Pulse Period Address
AI $F Decrement Pulse Period Address
LMAD PLPADR Save Pulse Period Address
BR *+1
BRS STCNT90 Branch to STCNT90
*
SLDW10 LMID $6,CNTADR Set Stop Control Mode
LMID $D,COUNT0 Initialize COUNT0 to COUNT2
LMID $8,COUNT1 12-bit Counter = H'08D = D'141

```

```

        LMID    $0,COUNT2
        BRS     STCNT90      Branch to STCNT90
*
*****
*
        STOP : Stop Control
*****
*
STOP     CAL     DEC          Subroutine Jump to 'DEC'
        BRS     STCNT90      ST = "1"? Yes. Branch to STCNT9
*
        LMID    $0,CNTADR   No. Set Slue up Control Mode
        LMID    $1,PLPADR   Set Pulse period Address
        TMD     FOWRDF      FOWRDF = "1" ?
        BRS     STOP10      Yes. Branch to STOP10
        SEMD    FOWRDF      Set FOWRDF
        BRS     STCNT90     Branch to STCNT90
STOP10   REMD    FOWRDF      Reset FOWRDF
        BRS     STCNT90     Branch to STCNT90
*
*****
*
        POUT : Output Pulse
*****
*
POUT     LAMD    PLDATA      Load Pulse Data
        TMD     FOWRDF      FOWRDF = 1 ?
        BRS     POT20      Yes. Branch to POT20
*
        LBI     $8          No.
        REC                      Reset CA
        ROTR                   Rotate Right A with Carry
        TC                      CA = 1 ?
        BRS     POT10      Yes. Branch to POT10
        BRS     POT11      No. Branch to POT11
POT10    OR                      A = A OR B
POT11    LRA     $2          Set R2 Port PDR
        LMAD    PLDATA      Save Pulse Data
        BRS     POT99      Branch to POT99
*
POT20    LBI     $1          Reset CA
        REC                      Reset CA
        ROTL                   Rotate Left A with Carry
        TC                      CA = 1 ?
        BRS     POT21      Yes. Branch to POT21
        BRS     POT22      No. Branch to POT22
POT21    OR                      A = A OR B
POT22    LRA     $2          Set R2 Port PDR
        LMAD    PLDATA      Save Pulse Data
*
POT99    RTN                      Return from Subroutine
*
*****

```

```

*      DECR : Decrement Counter
*****
*
DECR   REC          Reset Carry
      LAI           $0
      SMCD          COUNT0      A = COUNT0 - A - _CA
      LMAD          COUNT0      Save COUNT0
      LAI           $0
      SMCD          COUNT1      A = COUNT1 - A - _CA
      LMAD          COUNT1      Save COUNT1
      LAI           $0
      SMCD          COUNT2      A = COUNT2 - A - _CA
      LMAD          COUNT2      Save COUNT2
      RTN           Return from Subroutine

*
*****
*      Subroutine Table
*****
*
      org           $20

*
PLOUT  BRL          POUT        Branch to POUT
DEC    BRL          DECR        Branch to DECR

*
*****
*      Timer Period Data Table
*****
*
      org           $100

*
      dc           $100          Start
      dc           $111          30.592ms
      dc           $1AA          11.008ms
      dc           $1BB          8.832ms
      dc           $1CC          6.656ms
      dc           $1CC          6.656ms
      dc           $1CC          6.656ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $1DD          4.480ms
      dc           $100          End

*
*****
*      Pulse Motor Control Address
*****
*
      org           $200

```



```
*
      JMPL   SLUP      Jump to Slue up Control Routine
      JMPL   CNST      Jump to Constant Control Routine
      JMPL   SLDOWN    Jump to Slue down Control Routine
      JMPL   STOP      Jump to Stop Control Routine
*
      end
```

2. H4318/H4359

*
* H400 Series Application Note
* - Application Chapter -
*

* 'Stepping Motor Control'
*

* Function
* : Timer B Reload Timer
* : I/O Port
*

* MCU : H4318/H4359
*

* External Clock : 4MHz

* Internal Clock : 1MHz
*

*

* Symbol Definition

*
IE equ 0,\$000 Interrupt Enable Flag
RSP equ 1,\$000 Reset Stack Pointer
IF0 equ 2,\$000 INTO Interrupt Request Flag
IM0 equ 3,\$000 INTO Interrupt Mask
*
IF1 equ 0,\$001 INT1 Interrupt Request Flag
IM1 equ 1,\$001 INT1 Interrupt Mask
IFTA equ 2,\$001 TIMER A Interrupt Request Flag
IMTA equ 3,\$001 TIMER A Interrupt Mask
*
IFTB equ 0,\$002 TIMER B Interrupt Request Flag
IMTB equ 1,\$002 TIMER B Interrupt Mask
IFTC equ 2,\$002 TIMER C Interrupt Request Flag
IMTC equ 3,\$002 TIMER C Interrupt Mask
*
IFAD equ 0,\$003 A/D Interrupt Request Flag
IMAD equ 1,\$003 A/D Interrupt Mask
IFS equ 2,\$003 SCI Interrupt Request Flag
IMS equ 3,\$003 SCI Interrupt Mask
*
PMRA equ \$004 Port Mode Register A
SMR equ \$005 Serial Mode Register
SRL equ \$006 Serial Data Register L
SRU equ \$007 Serial Data Register U
TMA equ \$008 Timer Mode Register A
TMB1 equ \$009 Timer Mode Register B1
TRBL equ \$00A Timer Read Register BL

```

TWBL    equ    $00A    Timer Write register BL
TRBU    equ    $00B    Timer Read Register BU
TWBU    equ    $00B    Timer Write Register BU
MIS     equ    $00C    Miscellaneous Register
TMC     equ    $00D    Timer Mode Register C
TRCL    equ    $00E    Timer Read Register CL
TWCL    equ    $00E    Timer Write Register CL
TRCU    equ    $00F    Timer Read Register CU
TWCU    equ    $00F    Timer Write Register CU
ACR     equ    $016    A/D Control Register
ADRL    equ    $017    A/D Data Register L
ADRU    equ    $018    A/D Data Register U
AMR1    equ    $019    A/D Mode Register 1
AMR2    equ    $01A    A/D Mode Register 2
*
WDON    equ    1,$020   Watchdog on Flag
ADSF    equ    2,$020   A/D Start Flag
*
ICSF    equ    0,$021   Input Capture Status Flag
ICEF    equ    1,$021   Input Capture Error Flag
IAOF    equ    2,$021   IAD off Flag
RAME    equ    3,$021   RAM Enable Flag
*
PMRB    equ    $024    Port Mode register B
PMRC    equ    $025    Port Mode Register C
TMB2    equ    $026    Timer Mode Register B2
DCD0    equ    $02C    Data Control Register D0
DCD1    equ    $02D    Data Control Register D1
DCD2    equ    $02E    Data Control Register D2
DCR0    equ    $030    Data Control Register R0
DCR1    equ    $031    Data Control Register R1
DCR2    equ    $032    Data Control Register R2
DCR3    equ    $033    Data Control Register R3
DCR4    equ    $034    Data Control Register R4
DCR8    equ    $038    Data Control Register R8
*
*****
*          RAM Allocation
*****
*
AESC    equ    $040    A Escape RAM Area
BESC    equ    $041    B Escape RAM Area
WESC    equ    $042    W Escape RAM Area
XESC    equ    $043    X Escape RAM Area
YESC    equ    $044    Y Escape RAM Area
SXESC   equ    $045    SPX Escape RAM Area
SYESC   equ    $046    SPY Escape RAM Area
*
PLDATA  equ    $050    Pulse Data ($3 <-> $6 <-> $C <-> $9)
CNTADR  equ    $051    Control Process Address
PLPADR  equ    $052    Pulse Period Address

```

```

COUNT0 equ $053 Counter 0
COUNT1 equ $054 Counter 1
COUNT2 equ $055 Counter 2
*
FOWRDF equ 0,$05F Forward Flag( 1:Forward, 0:Reverce )
*

```

* Vector Address

*

```
org $0000
```

*

```

JMPL STEPMN Reset Interrupt
JMPL STEPMN INT0 Interrupt
JMPL STEPMN INT1 Interrupt
JMPL STEPMN Timer A Interrupt
JMPL STEPCNT Timer B Interrupt
JMPL STEPMN Timer C Interrupt
JMPL STEPMN A/D Interrupt
JMPL STEPMN SCI Interrupt

```

*

* STEPMN : Main Program

*

```
org $1000
```

*

```
STEPMN REMD RSP Stack Pointer Reset
```

*

```

LMID $3,PLDATA Initialize Pulse Data
LMID $0,CNTADR Initialize Control Process Address
SEMD FOWRDF Set Forward Mode
LMID $1,PLPADR Initialize Pulse Period Address

```

*

```

LAI $0 Initialize R8 Port Data Register
LRA $8
LMID $F,DCR8 Initialize R8 Port Output Terminal Function

```

*

```

LMID $A,TMB1 Initialize Timer B (128tcyc,Reload Timer ON)
LMID $8,TWBL Initialize Period 29.696ms
LMID $1,TWBU
REMD IFTB Clear Timer B Interrupt Request Flag

```

*

```

BR *+1 Set Status Flag
LMID $F,COUNT0 Initialize Counter 0
STMN10 CAL PLOUT Subroutine Call 'PLOUT'

```

*

```

STMN11 TMD IFTB 29.696ms Pass ?
BRS STMN12 Yes. Branch to STMN12
BRS STMN11 No. Branch to STMN11

```

*

```

STMN12  REMD   IFTB      Clear IFTB
        LAMD   COUNT0    Load Counter 0
        AI     $F        Decrement Counter 0
        LMAD   COUNT0    Save Counter 0
        BRS    STMN10    16 times End ? No. Branch to STMN10
*
        REMD   IFTB      Clear Timer B Interrupt Request Flag
        REMD   IMTB      Timer B Interrupt Enable
        SEMD   IE        Interrupt Enable
*
STMN99  BRS    STMN99    Infinite Loop
*
*****
*       STEPCNT : Stepping Motor Control
*****
*
STEPCNT  REMD   IFTB      Clear Timer B Interrupt Request Flag
*
        LMAD   AESC      Store Accumulator
        LAB
        LMAD   BESC      Store B Register
        XSPX
        LASPX
        LMAD   XESC      Store X Register
        XSPX
        LAY
        LMAD   YESC      Store Y Register
*
        LAMD   CNTADR    Load Control Process Address
        LBI    $0
        TBR    $2        Table Branch (CNTADR=0:SLUP, 2:CNST, 4:SLDOWN, 6:STOP)
*
STCNT90 LAMD   YESC      Restore Y Register
        LYA
        LAMD   XESC      Restore X Register
        LXA
        LAMD   BESC      Restore B Register
        LBA
        LAMD   AESC      Restore Accumulator
*
        RTNI           Return from Interrupt
*
*****
*       SLUP : Slue up Control
*****
*
SLUP     BR     *+1      Set Status Flag
        CAL    PLOUT     Subroutine Jump to 'PLOUT'
        LAMD   PLPADR    Load Pulse Period Address
        LBI    $0
        P      $1        Paturrn Generation 'Output Pulse Period'

```

```

LAB
ALEI      $0      A <= $0 ?
BRS      SLUP10   Yes. Branch to SLUP10
LMAD     TWBL     Set Pulse Period Data Lower
LAB
LMAD     TWBU     Set Pulse Period Data Upper
LAMD     PLPADR   Load Pulse Period Address
AI       $1      Increment Pulse Period Address
LMAD     PLPADR   Save Pulse Period Address
BR       *+1
BRS      STCNT90  Branch to STCNT90
*
SLUP10   LMID     $2,CNTADR  Set Constant Control Mode
          LMID     $8,COUNT0  Initialize Counter0 to COUNT0
          LMID     $E,COUNT1  12-bit Counter = H'3E8 = D'1000
          LMID     $3,COUNT2
          BRS      STCNT90  Branch to STCNT90
*
*****
*          CNST : Constant Control
*****
*
CNST     BR       *+1      Set Status Flag
          CAL      PLOUT    Subroutine Jump to 'PLOUT'
*
          CAL      DEC      Subroutine Jump to 'DEC'
          BRS      STCNT90  Counter = H'000 ? Yes. Branch to STCNT90
*
          LMID     $4,CNTADR  Set Slue down Control Mode
          LMID     $D,PLPADR  Set Pulse Period Address
          BRS      STCNT90  Branch to STCNT90
*
*****
*          STDOWN : Slue down Control
*****
*
SLDOWN   BR       *+1      Set Status Flag
          CAL      PLOUT    Subroutine Jump to 'PLOUT'
          LAMD     PLPADR   Load Pulse Period Address
          LBI      $0
          P        $1      Pattern Generation 'Output Pulse Period'
          LAB
          ALEI     $0      A <= $0 ?
          BRS     SLDW10   Yes. Branch to SLDW10
          LMAD     TWBL     Set Pulse Period Data Lower
          LAB
          LMAD     TWBU     Set Pulse Period Data Upper
          LAMD     PLPADR   Load Pulse Period Address
          AI       $F      Decrement Pulse Period Address
          LMAD     PLPADR   Save Pulse Period Address
          BR       *+1

```

```

      BRS      STCNT90      Branch to STCNT90
*
SLDW10  LMID      $6,CNTADR  Set Stop Control Mode
      LMID      $D,COUNT0    Initialize COUNT0 to COUNT2
      LMID      $8,COUNT1    12-bit Counter = H'08D = D'141
      LMID      $0,COUNT2
      BRS      STCNT90      Branch to STCNT90
*
*****
*      STOP : Stop Control
*****
*
STOP     CAL      DEC          Subroutine Jump to 'DEC'
      BRS      STCNT90      ST = "1"? Yes. Branch to STCNT9
*
      LMID      $0,CNTADR  No. Set Slue up Control Mode
      LMID      $1,PLPADR  Set Pulse period Address
      TMD      FOWRDF      FOWRDF = "1" ?
      BRS      STOP10      Yes. Branch to STOP10
      SEMD     FOWRDF      Set FOWRDF
      BRS      STCNT90      Branch to STCNT90
STOP10   REMD     FOWRDF      Reset FOWRDF
      BRS      STCNT90      Branch to STCNT90
*
*****
*      POUT : Output Pulse
*****
*
POUT     LAMD     PLDATA      Load Pulse Data
      TMD      FOWRDF      FOWRDF = 1 ?
      BRS      POT20      Yes. Branch to POT20
*
      LBI      $8          No.
      REC                      Reset CA
      ROTR                     Rotate Right A with Carry
      TC                      CA = 1 ?
      BRS      POT10      Yes. Branch to POT10
      BRS      POT11      No. Branch to POT11
POT10    OR                      A = A OR B
POT11    LRA      $8          Set R8 Port PDR
      LMAD     PLDATA      Save Pulse Data
      BRS      POT99      Branch to POT99
*
POT20    LBI      $1          Reset CA
      REC                      Rotate Left A with Carry
      ROTL                     CA = 1 ?
      BRS      POT21      Yes. Branch to POT21
      BRS      POT22      No. Branch to POT22
POT21    OR                      A = A OR B
POT22    LRA      $8          Set R8 Port PDR

```

```

        LMAD    PLDATA    Save Pulse Data
*
POT99   RTN          Return from Subroutine
*
*****
*       DECR : Decrement Counter
*****
*
DECR    REC          Reset Carry
        LAI     $0
        SMCD   COUNT0  A = COUNT0 - A - _CA
        LMAD   COUNT0  Save COUNT0
        LAI     $0
        SMCD   COUNT1  A = COUNT1 - A - _CA
        LMAD   COUNT1  Save COUNT1
        LAI     $0
        SMCD   COUNT2  A = COUNT2 - A - _CA
        LMAD   COUNT2  Save COUNT2
        RTN          Return from Subroutine
*
*****
*       Subroutine Table
*****
*
        org     $20
*
PLOUT   BRL    POUT    Branch to POUT
DEC     BRL    DECR    Branch to DECR
*
*****
*       Timer Period Data Table
*****
*
        org     $100
*
        dc     $100    Start
        dc     $111    30.592ms
        dc     $1AA    11.008ms
        dc     $1BB    8.832ms
        dc     $1CC    6.656ms
        dc     $1CC    6.656ms
        dc     $1CC    6.656ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $1DD    4.480ms
        dc     $100    End
*

```



```
*****
*           Pulse Motor Control Address
*****
*
*           org           $200
*
*           JMPL         SLUP           Jump to Slue up Control Routine
*           JMPL         CNST          Jump to Constant Control Routine
*           JMPL         SLDOWN        Jump to Slue down Control Routine
*           JMPL         STOP          Jump to Stop Control Routine
*
*           end
```

3. H4369

```
*****
*
*      H400 Series Application Note
*      - Application Chapter -
*
*      'Stepping Motor Control'
*
*      Function
*      : Timer B Reload Timer
*      : I/O Port
*
*      MCU : H4369
*
*      External Clock : 4MHz
*      Internal Clock : 1MHz
*      Sub Clock      : 32.768kHz
*
```

```
*****
*
```

```
*****
*      Symbol Definition
*****
```

```
*
IE      equ      0,$000      Interrupt Enable Flag
RSP     equ      1,$000      Reset Stack Pointer
IF0     equ      2,$000      INTO Interrupt Request Flag
IM0     equ      3,$000      INTO Interrupt Mask
*
IF1     equ      0,$001      INT1 Interrupt Request Flag
IM1     equ      1,$001      INT1 Interrupt Mask
IFTA    equ      2,$001      TIMER A Interrupt Request Flag
IMTA    equ      3,$001      TIMER A Interrupt Mask
*
IFTB    equ      0,$002      TIMER B Interrupt Request Flag
IMTB    equ      1,$002      TIMER B Interrupt Mask
IFTC    equ      2,$002      TIMER C Interrupt Request Flag
IMTC    equ      3,$002      TIMER C Interrupt Mask
*
IFAD    equ      0,$003      A/D Interrupt Request Flag
IMAD    equ      1,$003      A/D Interrupt Mask
IFS     equ      2,$003      SCI Interrupt Request Flag
IMS     equ      3,$003      SCI Interrupt Mask
*
PMRA    equ      $004        Port Mode Register A
SMR     equ      $005        Serial Mode Register
SRL     equ      $006        Serial Data Register L
SRU     equ      $007        Serial Data Register U
TMA     equ      $008        Timer Mode Register A
TMB1    equ      $009        Timer Mode Register B1
```

```

TRBL    equ    $00A    Timer Read Register BL
TWBL    equ    $00A    Timer Write register BL
TRBU    equ    $00B    Timer Read Register BU
TWBU    equ    $00B    Timer Write Register BU
MIS     equ    $00C    Miscellaneous Register
TMC     equ    $00D    Timer Mode Register C
TRCL    equ    $00E    Timer Read Register CL
TWCL    equ    $00E    Timer Write Register CL
TRCU    equ    $00F    Timer Read Register CU
TWCU    equ    $00F    Timer Write Register CU
*
ACR     equ    $016    A/D Control Register
ADRL    equ    $017    A/D Data Register L
ADRU    equ    $018    A/D Data Register U
AMR1    equ    $019    A/D Mode Register 1
AMR2    equ    $01A    A/D Mode Register 2
*
LSON    equ    0,$020    LSON Flag
WDON    equ    1,$020    Watchdog on Flag
ADSF    equ    2,$020    A/D Start Flag
DTON    equ    3,$020    DTON Flag
*
ICSF    equ    0,$021    Input Capture Status Flag
ICEF    equ    1,$021    Input Capture Error Flag
IAOF    equ    2,$021    IAD off Flag
RAME    equ    3,$021    RAM Enable Flag
*
PMRB    equ    $024    Port Mode register B
PMRC    equ    $025    Port Mode Register C
TMB2    equ    $026    Timer Mode Register B2
SSR1    equ    $027    System Clock Selection Register 1
SSR2    equ    $028    System Clock Selection Register 2
*
DCD0    equ    $02C    Data Control Register D0
DCD1    equ    $02D    Data Control Register D1
DCD2    equ    $02E    Data Control Register D2
DCD3    equ    $02F    Data Control Register D3
DCR0    equ    $030    Data Control Register R0
DCR1    equ    $031    Data Control Register R1
DCR2    equ    $032    Data Control Register R2
DCR3    equ    $033    Data Control Register R3
DCR4    equ    $034    Data Control Register R4
DCR5    equ    $035    Data Control Register R5
DCR6    equ    $036    Data Control Register R6
DCR7    equ    $037    Data Control Register R7
DCR8    equ    $038    Data Control Register R8
DCR9    equ    $039    Data Control Register R9
*

```

```

*****
*
RAM Allocation
*****

```

```

*
AESC      equ      $040      A Escape RAM Area
BESC      equ      $041      B Escape RAM Area
WESC      equ      $042      W Escape RAM Area
XESC      equ      $043      X Escape RAM Area
YESC      equ      $044      Y Escape RAM Area
SXESC     equ      $045      SPX Escape RAM Area
SYESC     equ      $046      SPY Escape RAM Area
*
PLDATA    equ      $050      Pulse Data ($3 <-> $6 <-> $C <-> $9)
CNTADR    equ      $051      Control Process Address
PLPADR    equ      $052      Pulse Period Address
COUNT0   equ      $053      Counter 0
COUNT1   equ      $054      Counter 1
COUNT2   equ      $055      Counter 2
*
FOWRDF    equ      0,$05F    Forward Flag( 1:Forward, 0:Reverse )
*
*****
*          Vector Address
*****
*
          org      $0000
*
          JMPL     STEPMN      Reset Interrupt
          JMPL     STEPMN      INT0 Interrupt
          JMPL     STEPMN      INT1 Interrupt
          JMPL     STEPMN      Timer A Interrupt
          JMPL     STEPCNT     Timer B Interrupt
          JMPL     STEPMN      Timer C Interrupt
          JMPL     STEPMN      A/D Interrupt
          JMPL     STEPMN      SCI Interrupt
*
*****
*          STEPMN : Main Program
*****
*
          org      $1000
*
STEPMN    REMD     RSP        Stack Pointer Reset
          LMID     $2,SSR1     Initialize System Clock
*
          LMID     $3,PLDATA    Initialize Pulse Data
          LMID     $0,CNTADR     Initialize Control Process Address
          SEMD     FOWRDF       Set Forward Mode
          LMID     $1,PLPADR     Initialize Pulse Period Address
*
          LAI      $0           Initialize R8 Port Data Register
          LRA      $8           Initialize R8 Port Output Terminal Function
          LMID     $F,DCR8      Initialize R8 Port Output Terminal Function
*

```

```

        LMID  $A,TMB1      Initialize Timer B (128tcyc,Reload Timer ON)
        LMID  $8,TWBL      Initialize Period 29.696ms
        LMID  $1,TWBU
        REMD  IFTB         Clear Timer B Interrupt Request Flag
*
        BR    *+1          Set Status Flag
        LMID  $F,COUNT0    Initialize Counter 0
STMN10  CAL    PLOUT      Subroutine Call 'PLOUT'
*
STMN11  TMD    IFTB       29.696ms Pass ?
        BRS  STMN12      Yes. Branch to STMN12
        BRS  STMN11      No. Branch to STMN11
*
STMN12  REMD  IFTB       Clear IFTB
        LAMD  COUNT0     Load Counter 0
        AI   $F          Decrement Counter 0
        LMAD  COUNT0     Save Counter 0
        BRS  STMN10      16 times End ? No. Branch to STMN10
*
        REMD  IFTB       Clear Timer B Interrupt Request Flag
        REMD  IMTB       Timer B Interrupt Enable
        SEMD  IE         Interrupt Enable
*
STMN99  BRS   STMN99     Infinite Loop
*
*****
*       STEPCNT : Stepping Motor Control
*****
*
STEPCNT  REMD  IFTB      Clear Timer B Interrupt Request Flag
*
        LMAD  AESC       Store Accumulator
        LAB
        LMAD  BESC       Store B Register
        XSPX
        LASPX
        LMAD  XESC       Store X Register
        XSPX
        LAY
        LMAD  YESC       Store Y Register
*
        LAMD  CNTADR     Load Control Process Address
        LBI   $0
        TBR   $2         Table Branch (CNTADR=0:SLUP, 2:CNST, 4:SLDOWN, 6:STOP)
*
STCNT90  LAMD  YESC     Restore Y Register
        LYA
        LAMD  XESC     Restore X Register
        LXA
        LAMD  BESC     Restore B Register
        LBA

```

```

LAMD  AESC      Restore Accumulator
*
RTNI           Return from Interrupt
*
*****
*   SLUP : Slue up Control
*****
*
SLUP  BR        *+1      Set Status Flag
      CAL       PLOUT    Subroutine Jump to 'PLOUT'
      LAMD      PLPADR   Load Pulse Period Address
      LBI       $0
      P         $1      Pattern Generation 'Output Pulse Period'
      LAB
      ALEI     $0       A <= $0 ?
      BRS      SLUP10   Yes. Branch to SLUP10
      LMAD     TWBL     Set Pulse Period Data Lower
      LAB
      LMAD     TWBU     Set Pulse Period Data Upper
      LAMD     PLPADR   Load Pulse Period Address
      AI       $1      Increment Pulse Period Address
      LMAD     PLPADR   Save Pulse Period Address
      BR       *+1
      BRS      STCNT90  Branch to STCNT90
*
SLUP10 LMID     $2,CNTADR Set Constant Control Mode
        LMID     $8,COUNT0 Initialize Counter0 to COUNT0
        LMID     $E,COUNT1 12-bit Counter = H'3E8 = D'1000
        LMID     $3,COUNT2
        BRS      STCNT90  Branch to STCNT90
*
*****
*   CNST : Constant Control
*****
*
CNST  BR        *+1      Set Status Flag
      CAL       PLOUT    Subroutine Jump to 'PLOUT'
*
      CAL       DEC      Subroutine Jump to 'DEC'
      BRS      STCNT90  Counter = H'000 ? Yes. Branch to STCNT90
*
      LMID     $4,CNTADR Set Slue down Control Mode
      LMID     $D,PLPADR Set Pulse Period Address
      BRS      STCNT90  Branch to STCNT90
*
*****
*   STDOWN : Slue down Control
*****
*
SLDOWN BR       *+1      Set Status Flag
      CAL       PLOUT    Subroutine Jump to 'PLOUT'

```

```

LAMD  PLPADR  Load Pulse Period Address
LBI   $0
P     $1      Pattern Generation 'Output Pulse Period'
LAB
ALEI  $0      A <= $0 ?
BRS   SLDW10  Yes. Branch to SLDW10
LMAD  TWBL    Set Pulse Period Data Lower
LAB
LMAD  TWBU    Set Pulse Period Data Upper
LAMD  PLPADR  Load Pulse Period Address
AI    $F      Decrement Pulse Period Address
LMAD  PLPADR  Save Pulse Period Address
BR    *+1
BRS   STCNT90 Branch to STCNT90
*
SLDW10 LMID  $6,CNTADR  Set Stop Control Mode
      LMID  $D,COUNT0  Initialize COUNT0 to COUNT2
      LMID  $8,COUNT1  12-bit Counter = H'08D = D'141
      LMID  $0,COUNT2
      BRS   STCNT90  Branch to STCNT90
*
*****
*      STOP : Stop Control
*****
*
STOP   CAL    DEC      Subroutine Jump to 'DEC'
      BRS   STCNT90  ST = "1"? Yes. Branch to STCNT9
*
      LMID  $0,CNTADR  No. Set Slue up Control Mode
      LMID  $1,PLPADR  Set Pulse period Address
      TMD  FOWRDF     FOWRDF = "1" ?
      BRS   STOP10    Yes. Branch to STOP10
      SEMD FOWRDF     Set FOWRDF
      BRS   STCNT90   Branch to STCNT90
STOP10 REMD  FOWRDF     Reset FOWRDF
      BRS   STCNT90   Branch to STCNT90
*
*****
*      POUT : Output Pulse
*****
*
POUT   LAMD  PLDATA    Load Pulse Data
      TMD  FOWRDF     FOWRDF = 1 ?
      BRS   POT20    Yes. Branch to POT20
*
      LBI   $8      No.
      REC          Reset CA
      ROTR         Rotate Right A with Carry
      TC          CA = 1 ?
      BRS   POT10   Yes. Branch to POT10
      BRS   POT11   No. Branch to POT11

```

```

POT10   OR           A = A OR B
POT11   LRA          $8       Set R8 Port PDR
        LMAD         PLDATA    Save Pulse Data
        BRS          POT99     Branch to POT99
*
POT20   LBI          $1
        REC           Reset CA
        ROTL         Rotate Left A with Carry
        TC           CA = 1 ?
        BRS          POT21     Yes. Branch to POT21
        BRS          POT22     No. Branch to POT22
POT21   OR           A = A OR B
POT22   LRA          $8       Set R8 Port PDR
        LMAD         PLDATA    Save Pulse Data
*
POT99   RTN          Return from Subroutine
*

```

```

*****
*      DECR : Decrement Counter
*****
*

```

```

DECR    REC           Reset Carry
        LAI          $0
        SMCD         COUNT0    A = COUNT0 - A - _CA
        LMAD         COUNT0    Save COUNT0
        LAI          $0
        SMCD         COUNT1    A = COUNT1 - A - _CA
        LMAD         COUNT1    Save COUNT1
        LAI          $0
        SMCD         COUNT2    A = COUNT2 - A - _CA
        LMAD         COUNT2    Save COUNT2
        RTN          Return from Subroutine
*

```

```

*****
*      Subroutine Table
*****
*

```

```

        org          $20
*

```

```

PLOUT   BRL          POUT     Branch to POUT
DEC     BRL          DECR     Branch to DECR
*

```

```

*****
*      Timer Period Data Table
*****
*

```

```

        org          $100
*
        dc          $100      Start
        dc          $111      30.592ms
        dc          $1AA      11.008ms
*

```




```
dc      $1BB      8.832ms
dc      $1CC      6.656ms
dc      $1CC      6.656ms
dc      $1CC      6.656ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $1DD      4.480ms
dc      $100      End
```

```
*
*****
```

```
*      Pulse Motor Control Address
```

```
*****
```

```
*
      org      $200
```

```
*
      JMPL     SLUP      Jump to Slue up Control Routine
      JMPL     CNST      Jump to Constant Control Routine
      JMPL     SLDOWN    Jump to Slue down Control Routine
      JMPL     STOP      Jump to Stop Control Routine
```

```
*
      end
```

4. H4889

```
*****
*
*      H400 Series Application Note
*      - Application Chapter -
*
*      'Stepping Motor Control'
*
*      Function
*      : Timer B Reload Timer
*      : I/O Port
*
*      MCU : H4889
*
*      External Clock : 4MHz
*      Internal Clock : 1MHz
*      Sub Clock      : 32.768kHz
*
*****
```

```
*****
*
*****
```

* Symbol Definition

```
*****
```

```
*
IE      equ      0,$000      Interrupt Enable Flag
RSP     equ      1,$000      Reset Stack Pointer
IFWU    equ      2,$000      _WU0-_WU3 Interrupt Request Flag
IMWU    equ      3,$000      _WU0-_WU3 Interrupt Mask
*
IF0     equ      0,$001      _INT0 Interrupt Request Flag
IM0     equ      1,$001      _INT0 Interrupt Mask
IF1     equ      2,$001      _INT1 Interrupt request Flag
IM1     equ      3,$001      _INT1 Interrupt Mask
*
IFTA    equ      0,$002      Timer A Interrupt Request Flag
IMTA    equ      1,$002      Timer A Interrupt Mask
IFTB    equ      2,$002      Timer B Interrupt Request Flag
IMTB    equ      3,$002      Timer B Interrupt Mask
*
IFTC    equ      0,$003      Timer C Interrupt Request Flag
IMTC    equ      1,$003      Timer C Interrupt Mask
IFAD    equ      2,$003      A/D Converter Interrupt Request Flag
IMAD    equ      3,$003      A/D Converter Interrupt Mask
*
SSR     equ      $004        System Clock Selection Register
MIS     equ      $005        Miscellaneous Register
ESR     equ      $006        Edge Detection Selection Register
*
PMR0    equ      $008        Port Mode Register 0
PMR1    equ      $009        Port Mode Register 1
```

PMR2	equ	\$00A	Port Mode Register 2
PMR3	equ	\$00B	Port Mode Register 3
PMR4	equ	\$00C	Port Mode Register 4
MSR1	equ	\$00D	Module Standby Register 1
MSR2	equ	\$00E	Module Standby Register 2
TMA	equ	\$00F	Timer Mode Register A
TMB1	equ	\$010	Timer Mode Register B1
TMB2	equ	\$011	Timer Mode Register B2
TRBL	equ	\$012	Timer Read Register BL
TWBL	equ	\$012	Timer Write Register BL
TRBU	equ	\$013	Timer Read Register BU
TWBU	equ	\$013	Timer Write Register BU
TMC1	equ	\$014	Timer Mode Register C1
TMC2	equ	\$015	Timer Mode Register C2
TRCL	equ	\$016	Timer Read Register CL
TWCL	equ	\$016	Timer Write Register CL
TRCU	equ	\$017	Timer Read Register CU
TWCU	equ	\$017	Timer Write Register CU
TMD1	equ	\$018	Timer Mode Register D1
TMD2	equ	\$019	Timer Mode Register D2
TRDL	equ	\$01A	Timer Read Register DL
TWDL	equ	\$01A	Timer Write Register DL
TRDU	equ	\$01B	Timer read Register DU
TWDU	equ	\$01B	Timer Write register DU
*			
LSON	equ	0,\$020	Low Speed on Flag
WDON	equ	1,\$020	Watchdog on Flag
ADSF	equ	2,\$020	A/D Start Flag
DTON	equ	3,\$020	DTON Flag
*			
ICSF	equ	0,\$021	Input Capture Status Flag
ICEF	equ	1,\$021	Input Capture Error Flag
GEF	equ	3,\$021	Gear Enable Flag
*			
IFTD	equ	2,\$022	Timer D Interrupt Request Flag
IMTD	equ	3,\$022	Timer D Interrupt Mask
*			
IFS	equ	2,\$023	Serial Interrupt Request Flag
IMS	equ	3,\$023	Serial Interrupt Mask
*			
SMR1	equ	\$024	Serial Mode Register 1
SMR2	equ	\$025	Serial Mode Register 2
SRL	equ	\$026	Serial Data Register L
SRU	equ	\$027	Serial Data Register U
AMR	equ	\$028	A/D Mode Register
*			
ADRL	equ	\$02A	A/D Data Register L
ADRU	equ	\$02B	A/D Data Register U
LCR	equ	\$02C	LCD Control Register
LMR	equ	\$02D	LCD Mode Register
BMR	equ	\$02E	Buzzer Mode Register

```

*
DCD0    equ    $030    Data Control Register D0
DCD1    equ    $031    Data Control Register D1
DCD2    equ    $032    Data Control Register D2
*
DCR0    equ    $034    Data Control Register R0
DCR1    equ    $035    Data Control Register R1
DCR2    equ    $036    Data Control Register R2
DCR3    equ    $037    Data Control Register R3
DCR4    equ    $038    Data Control Register R4
DCR5    equ    $039    Data Control Register R5
DCR6    equ    $03A    Data Control Register R6
DCR7    equ    $03B    Data Control Register R7
DCR8    equ    $03C    Data Control Register R8
*
V        equ    $03F    Bank Register
*
*****
*          RAM Allocation
*****
*
AESC    equ    $040    A Escape RAM Area
BESC    equ    $041    B Escape RAM Area
WESC    equ    $042    W Escape RAM Area
XESC    equ    $043    X Escape RAM Area
YESC    equ    $044    Y Escape RAM Area
SXESC   equ    $045    SPX Escape RAM Area
SYESC   equ    $046    SPY Escape RAM Area
*
PLDATA  equ    $090    Pulse Data ($3 <-> $6 <-> $C <-> $9)
CNTADR  equ    $091    Control Process Address
PLPADR  equ    $092    Pulse Period Address
COUNT0 equ    $093    Counter 0
COUNT1 equ    $094    Counter 1
COUNT2 equ    $095    Counter 2
*
FOWRDF  equ    0,$09F  Forward Flag( 1:Forward, 0:Reverse )
*
*****
*          Vector Address
*****
*
*          org    $0000
*
JMPL    STEPMN    Reset Interrupt
JMPL    STEPMN    _WU0-WU3 Interrupt
JMPL    STEPMN    _INT0 Interrupt
JMPL    STEPMN    _INT1 Interrupt
JMPL    STEPMN    Timer A Interrupt
JMPL    STEPCNT  Timer B/D Interrupt
JMPL    STEPMN    Timer C Interrupt

```

*

* STEPMN : Main Program

*

org \$1000

*

STPMN REMD RSP Stack Pointer Reset
 LMID \$2,SSR Initialize System Clock

*

 LMID \$3,PLDATA Initialize Pulse Data
 LMID \$0,CNTADR Initialize Control Process Address
 SEMD FOWRDF Set Forward Mode
 LMID \$1,PLPADR Initialize Pulse Period Address

*

 LAI \$0 Initialize R2 Port Data Register
 LRA \$2
 LMID \$F,DCR2 Initialize R2 Port Output Terminal Function

*

 LMID \$A,TMB1 Initialize Timer B (128tcyc,Reload Timer ON)
 LMID \$8,TWBL Initialize Period 29.696ms
 LMID \$1,TWBU
 REMD IFTB Clear Timer B Interrupt Request Flag

*

 BR *+1 Set Status Flag
 LMID \$F,COUNT0 Initialize Counter 0
 STMN10 CAL PLOUT Subroutine Call 'PLOUT'

*

 STMN11 TMD IFTB 29.696ms Pass ?
 BRS STMN12 Yes. Branch to STMN12
 BRS STMN11 No. Branch to STMN11

*

 STMN12 REMD IFTB Clear IFTB
 LAMD COUNT0 Load Counter 0
 AI \$F Decrement Counter 0
 LMAD COUNT0 Save Counter 0
 BRS STMN10 16 times End ? No. Branch to STMN10

*

 REMD IFTB Clear Timer B Interrupt Request Flag
 REMD IMTB Timer B Interrupt Enable
 SEMD IE Interrupt Enable

*

 STMN99 BRS STMN99 Infinite Loop

*

* STEPCNT : Stepping Motor Control

*

 STPCNT REMD IFTB Clear Timer B Interrupt Request Flag

*

```

LMAD  AESC      Store Accumulator
LAB
LMAD  BESC      Store B Register
XSPX
LASPX
LMAD  XESC      Store X Register
XSPX
LAY
LMAD  YESC      Store Y Register
*
LMAD  CNTADR    Load Control Process Address
LBI   $0
TBR   $2        Table Branch (CNTADR=0:SLUP, 2:CNST, 4:SLDOWN, 6:STOP)
*
STCNT90  LAMD  YESC      Restore Y Register
LYA
LAMD  XESC      Restore X Register
LXA
LAMD  BESC      Restore B Register
LBA
LAMD  AESC      Restore Accumulator
*
RTNI                    Return from Interrupt
*
*****
*      SLUP : Slue up Control
*****
*
SLUP     BR      *+1      Set Status Flag
CAL      PLOUT    Subroutine Jump to 'PLOUT'
LAMD     PLPADR   Load Pulse Period Address
LBI      $0
P        $1        Pattern Generation 'Output Pulse Period'
LAB
ALEI     $0        A <= $0 ?
BRS      SLUP10   Yes. Branch to SLUP10
LMAD     TWBL     Set Pulse Period Data Lower
LAB
LMAD     TWBU     Set Pulse Period Data Upper
LAMD     PLPADR   Load Pulse Period Address
AI       $1        Increment Pulse Period Address
LMAD     PLPADR   Save Pulse Period Address
BR       *+1
BRS      STCNT90  Branch to STCNT90
*
SLUP10   LMID     $2,CNTADR Set Constant Control Mode
LMID     $8,COUNT0 Initialize Counter0 to COUNT0
LMID     $E,COUNT1 12-bit Counter = H'3E8 = D'1000
LMID     $3,COUNT2
BRS      STCNT90  Branch to STCNT90
*

```

* CNST : Constant Control

```

*
CNST   BR      *+1      Set Status Flag
       CAL     PLOUT    Subroutine Jump to 'PLOUT'
*
       CAL     DEC      Subroutine Jump to 'DEC'
       BRS    STCNT90   Counter = H'000 ? Yes. Branch to STCNT90
*
       LMID   $4,CNTADR Set Slue down Control Mode
       LMID   $D,PLPADR Set Pulse Period Address
       BRS    STCNT90   Branch to STCNT90

```

*

* STDOWN : Slue down Control

```

*
SLDOWN BR      *+1      Set Status Flag
       CAL     PLOUT    Subroutine Jump to 'PLOUT'
       LAMD   PLPADR    Load Pulse Period Address
       LBI    $0
       P      $1        Pattern Generation 'Output Pulse Period'
       LAB
       ALEI   $0        A <= $0 ?
       BRS   SLDW10     Yes. Branch to SLDW10
       LMAD   TWBL      Set Pulse Period Data Lower
       LAB
       LMAD   TWBU      Set Pulse Period Data Upper
       LAMD   PLPADR    Load Pulse Period Address
       AI     $F        Decrement Pulse Period Address
       LMAD   PLPADR    Save Pulse Period Address
       BR     *+1
       BRS   STCNT90   Branch to STCNT90

```

*

```

SLDW10 LMID   $6,CNTADR Set Stop Control Mode
       LMID   $D,COUNT0 Initialize COUNT0 to COUNT2
       LMID   $8,COUNT1 12-bit Counter = H'08D = D'141
       LMID   $0,COUNT2
       BRS   STCNT90   Branch to STCNT90

```

*

* STOP : Stop Control

```

*
STOP   CAL     DEC      Subroutine Jump to 'DEC'
       BRS    STCNT90   ST = "1"? Yes. Branch to STCNT9
*
       LMID   $0,CNTADR No. Set Slue up Control Mode
       LMID   $1,PLPADR Set Pulse period Address
       TMD   FOWRDF     FOWRDF = "1" ?

```

```

        BRS      STOP10      Yes. Branch to STOP10
        SEMD     FOWRDF      Set FOWRDF
        BRS      STCNT90     Branch to STCNT90
STOP10  REMD     FOWRDF      Reset FOWRDF
        BRS      STCNT90     Branch to STCNT90
*
*****
*          POUT : Output Pulse
*****
*
POUT    LAMD     PLDATA      Load Pulse Data
        TMD      FOWRDF      FOWRDF = 1 ?
        BRS      POT20      Yes. Branch to POT20
*
        LBI      $8          No.
        REC                      Reset CA
        ROTR                     Rotate Right A with Carry
        TC                        CA = 1 ?
        BRS      POT10      Yes. Branch to POT10
        BRS      POT11      No. Branch to POT11
POT10   OR                          A = A OR B
POT11   LRA      $2          Set R2 Port PDR
        LMAD     PLDATA      Save Pulse Data
        BRS      POT99      Branch to POT99
*
POT20   LBI      $1          Reset CA
        REC                      Rotate Left A with Carry
        ROTL                     CA = 1 ?
        BRS      POT21      Yes. Branch to POT21
        BRS      POT22      No. Branch to POT22
POT21   OR                          A = A OR B
POT22   LRA      $2          Set R2 Port PDR
        LMAD     PLDATA      Save Pulse Data
*
POT99   RTN                      Return from Subroutine
*
*****
*          DECR : Decrement Counter
*****
*
DECR    REC                      Reset Carry
        LAI      $0
        SMCD     COUNT0      A = COUNT0 - A - _CA
        LMAD     COUNT0      Save COUNT0
        LAI      $0
        SMCD     COUNT1      A = COUNT1 - A - _CA
        LMAD     COUNT1      Save COUNT1
        LAI      $0
        SMCD     COUNT2      A = COUNT2 - A - _CA
        LMAD     COUNT2      Save COUNT2

```



```

*
*****
*
      Subroutine Table
*****
*
      org      $20
*
PLOUT  BRL      POUT      Branch to POUT
DEC    BRL      DECR      Branch to DECR
*
*****
*
      Timer Period Data Table
*****
*
      org      $100
*
      dc      $100      Start
      dc      $111      30.592ms
      dc      $1AA      11.008ms
      dc      $1BB      8.832ms
      dc      $1CC      6.656ms
      dc      $1CC      6.656ms
      dc      $1CC      6.656ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $1DD      4.480ms
      dc      $100      End
*
*****
*
      Pulse Motor Control Address
*****
*
      org      $200
*
      JMPL    SLUP      Jump to Slue up Control Routine
      JMPL    CNST      Jump to Constant Control Routine
      JMPL    SLDOWN    Jump to Slue down Control Routine
      JMPL    STOP      Jump to Stop Control Routine
*
      end

```

2.3 Key Scan and 7-Segment LED Display

Key Scan and 7-Segment LED Display	MCU: H4318/H4359/H4369	Functions Used: R1, R2, R3 Ports, D Port, and Timer A
---	---	--

Specifications

- As shown in figure 1, the H4318/H4359/H4369 Series are used to construct a key matrix key-scanning function and 7-segment LED display.
- Numbers 0 to F are assigned to the 16 keys and the number (0 to F of the pressed key) is displayed on LED0, which is one of four 7-segment LEDs (LED0 to LED3).
- Two keys cannot be pressed simultaneously (the result is invalid).
- Key chattering is suppressed in software.
- Figure 2 shows the key configuration and number allocation. Figure 3 shows an example 7-segment LED display.
- Figure 4 shows the connection of H4318/H4359/H4369 and keys and 7-segment LED.

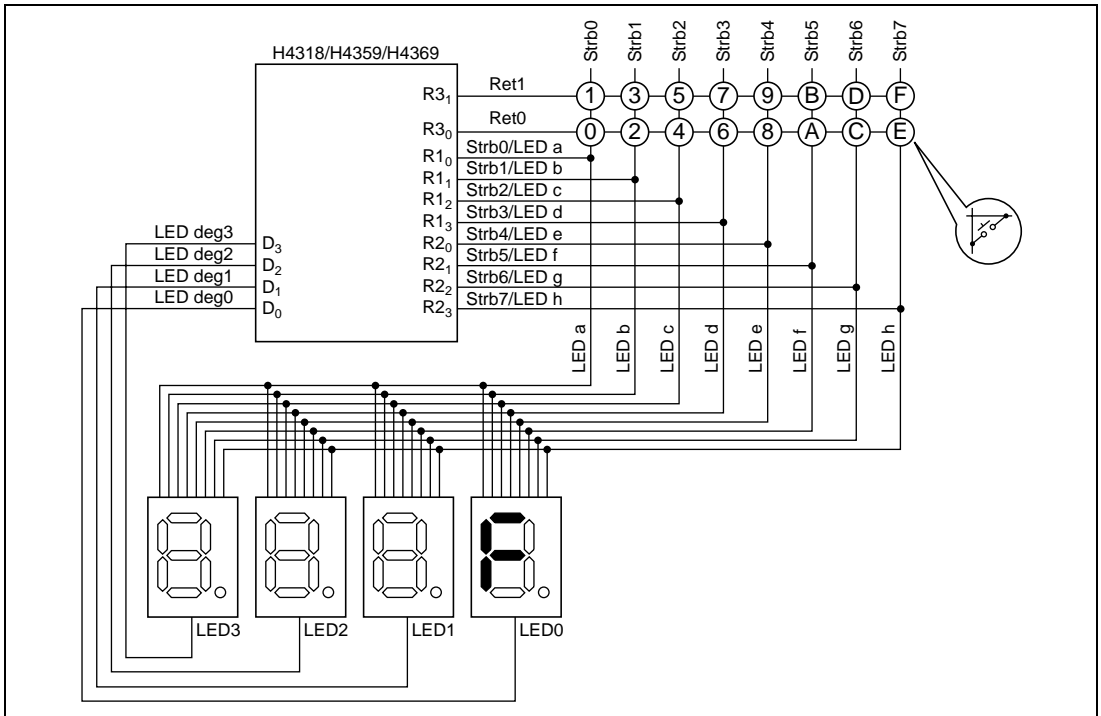


Figure 1 Key Scan and 7-Segment LED Display

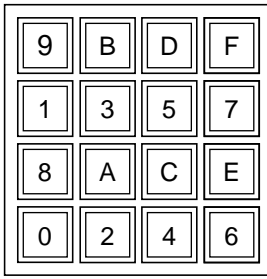


Figure 2 Key Configuration and Assigned Numbers

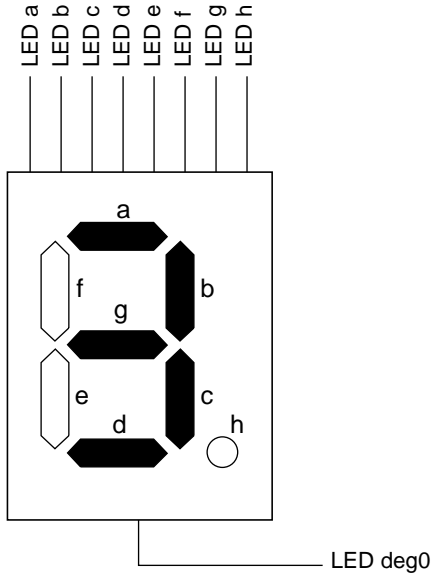


Figure 3 Example 7-Segment LED Display

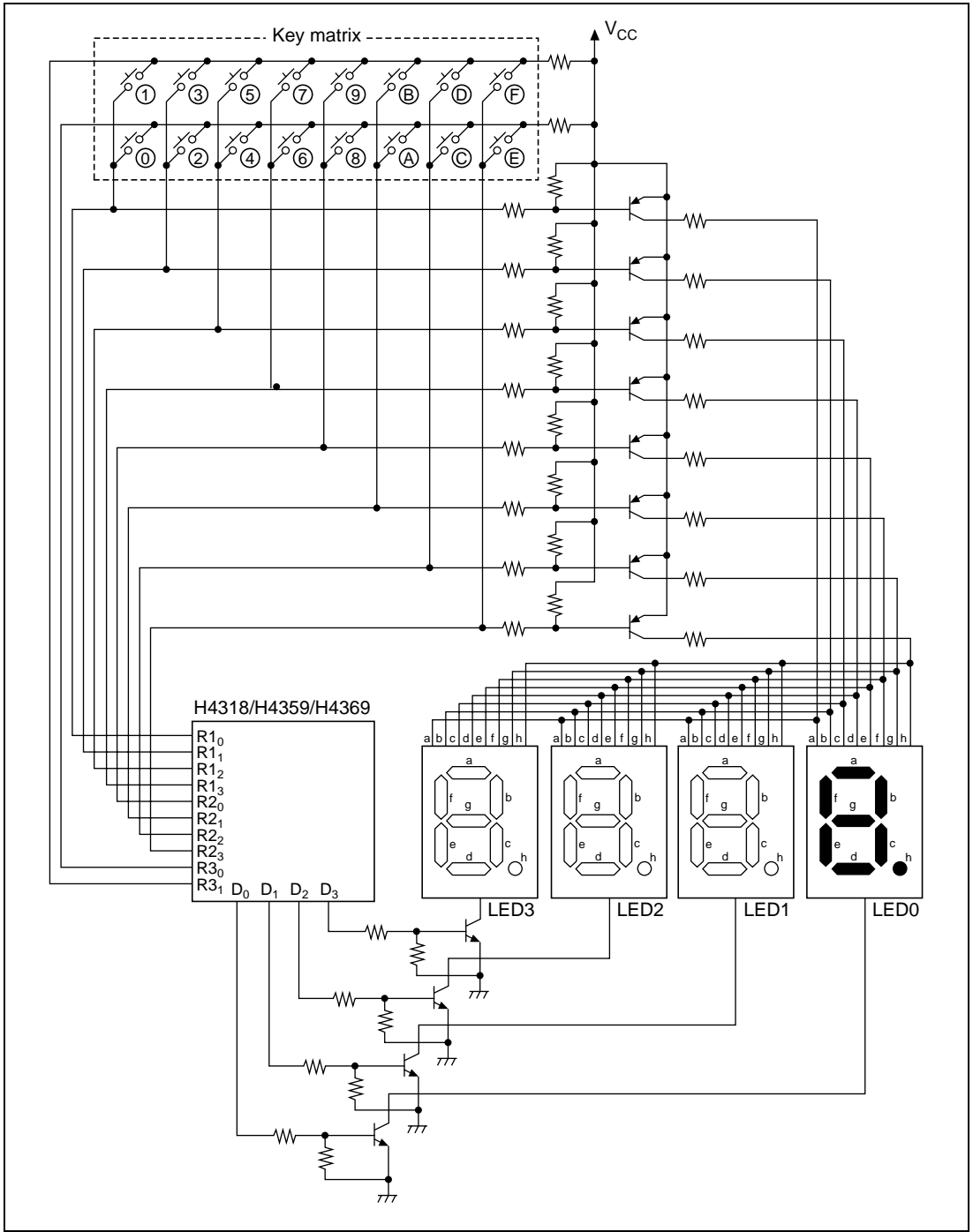


Figure 4 Connection of H4318/H4359/H4369 and keys and 7-Segment LED

Concepts

1. Key Scan

Figure 5 is a timing chart of the key scanning operation.

- A “Low” signal is output from P1₀ pin, and a strobe signal output to the STRb0 row of the key matrix.
- The key data for the Ret0 row of the key matrix is read from R3₀ and R3₁ pins when the strobe signal is output.
- Key depression is detected from the data read from the pins.
- The strobe signal is shifted and steps a to c repeated.

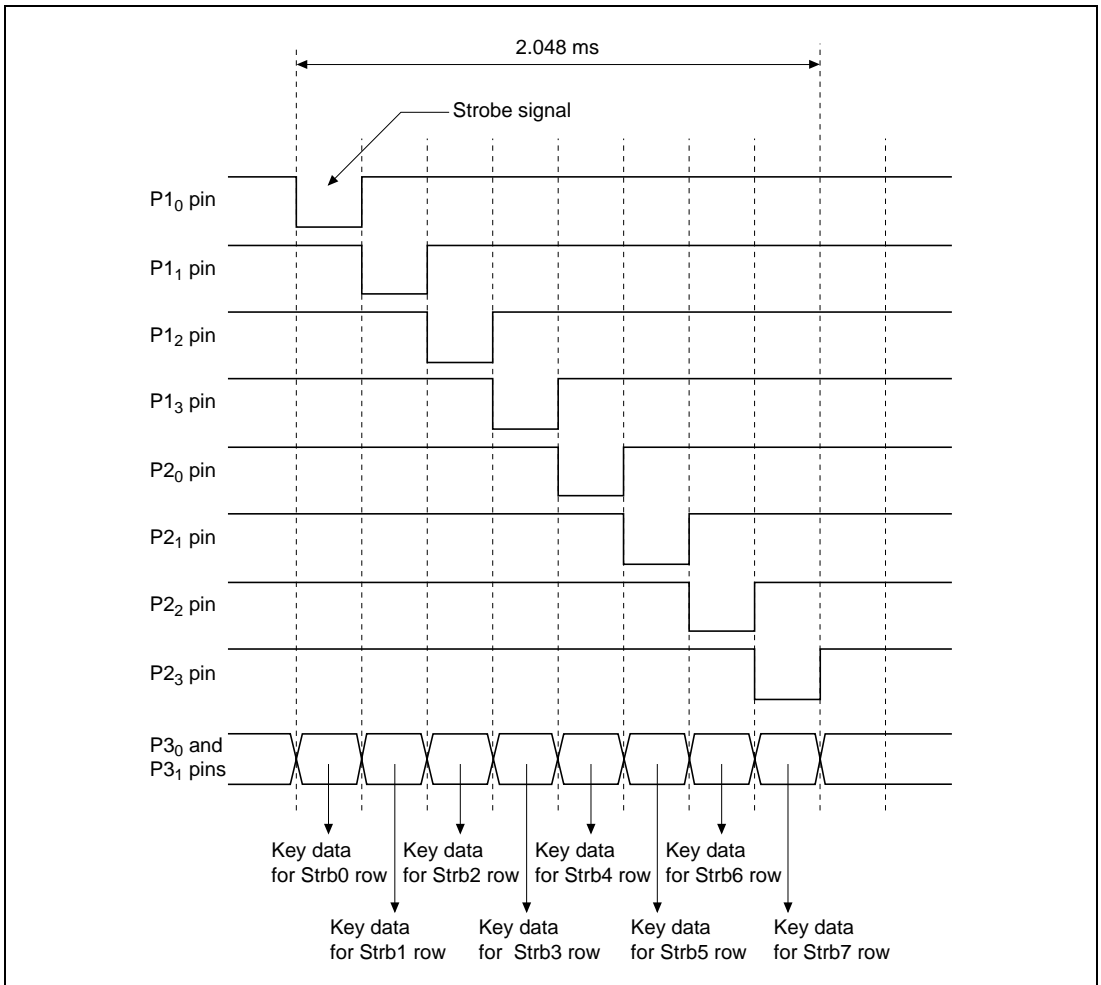


Figure 5 Timing Chart for Key Scanning Operation

2. Chattering Suppression

Figure 6 is a timing chart for chattering suppression.

- Key data is sampled at intervals of 10.24 ms.
- The data is checked to see if the same data is obtained 3 times in succession.
- If the key data is not the same for all 3 times, key depression is ignored.
- If the key data is the same for all 3 times, the key is assumed to be depressed and the key data is taken to be valid.

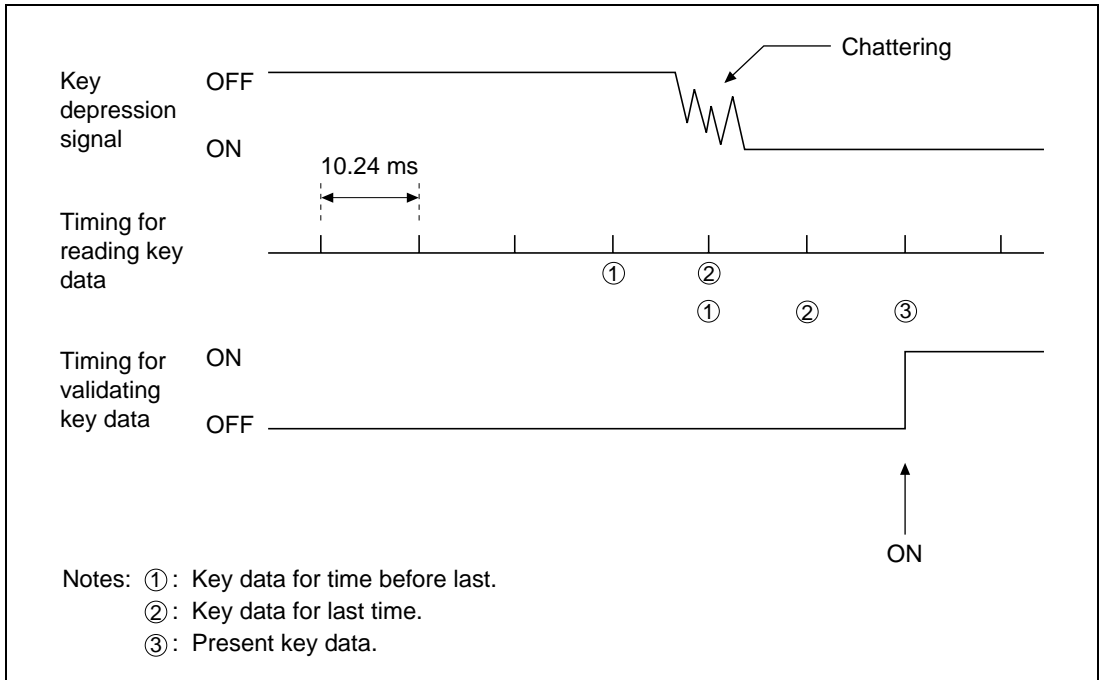


Figure 6 Timing Chart for Chattering Suppression

2. LED Display

Table 1 shows the relationship between 7-segment LED display, port output and segment data.

Table 1 Relationship Between LED Display, Port Output, and Segment Data


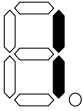
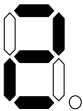
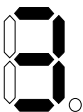
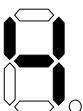
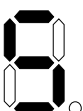
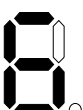

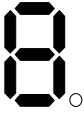


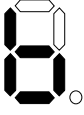

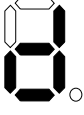
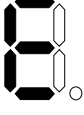
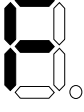
LED Display	R1 and R2 Port Output								Segment Data	
	R1 ₀	R1 ₁	R1 ₂	R1 ₃	R2 ₀	R2 ₁	R2 ₂	R2 ₃	SEG0L	SEG0U
	0	0	0	0	0	0	1	1	\$0	\$C
	1	0	0	1	1	1	1	1	\$9	\$F
	0	0	1	0	0	1	0	1	\$4	\$A
	0	0	0	0	1	1	0	1	\$0	\$B
	1	0	0	1	1	0	0	1	\$9	\$9
	0	1	0	0	1	0	0	1	\$2	\$9
	0	1	0	0	0	0	0	1	\$2	\$8
	0	0	0	1	1	0	1	1	\$8	\$D

Table 1 Relationship Between LED Display, Port Output, and Segment Data (cont)

LED Display	R1 and R2 Port Output								Segment Data	
	R1 ₀	R1 ₁	R1 ₂	R1 ₃	R2 ₀	R2 ₁	R2 ₂	R2 ₃	SEG0L	SEG0U
	0	0	0	0	0	0	0	1	\$0	\$8
	0	0	0	0	1	0	0	1	\$0	\$9
	0	0	0	1	0	0	0	1	\$8	\$8
	1	1	0	0	0	0	0	1	\$3	\$8
	0	1	1	0	0	0	1	1	\$6	\$C
	1	0	0	0	0	1	0	1	\$1	\$A
	0	1	1	0	0	0	0	1	\$6	\$8
	0	1	1	1	0	0	0	1	\$E	\$8

Description of Functions

1. This section describes the functions of the H4318/H4359/H4369 used in key scanning and 7-segment LED display. Figure 7 is a block diagram of the functions used in this example task.

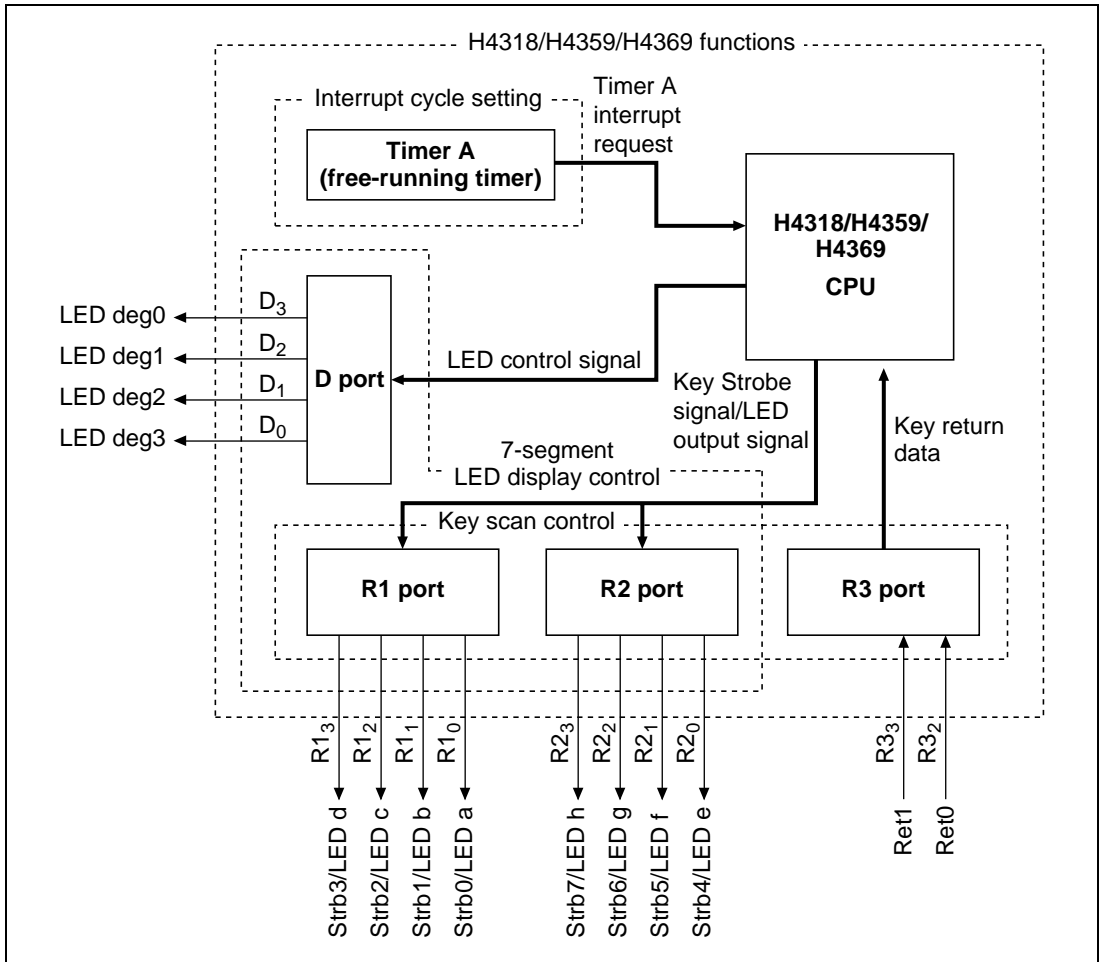


Figure 7 Block Diagram of H4318/H4359/H4369 Functions Used in Key Scanning and 7-Segment LED Display

2. Descriptions of Functions of Timer A, R1/R2/R3 Ports, and D Port.

a. Figure 8 is a block diagram of the timer A functions.

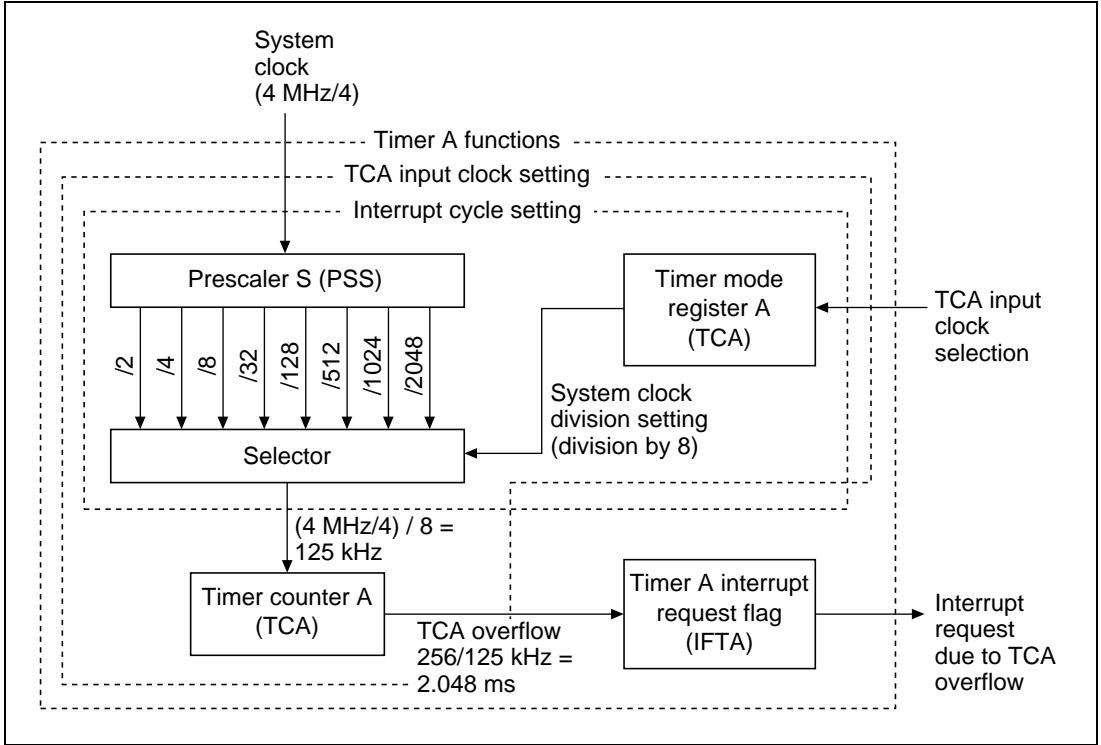


Figure 8 Block Diagram of Timer A Functions

- b. Timer A is an 8-bit free-running timer. However, in the H4369, it can also be used as a time based real-time clock using the system clock oscillator (32.768 kHz). Table 2 describes the timer A functions.

Table 2 Timer A Functions

Timer Mode Register A (TMA)

Function TMA is a 4-bit write-only register. It selects the division ratio of the prescaler S, which is the clock source for timer A. TMA is initialized to \$0 when reset and in stop mode. In the H4318/H4359 TMA bit 3 (TMA3) cannot be used. In the H4369, TMA3 selects the prescaler (PSS or PSW), which is the clock source of timer A.

Timer Counter A (TCA)

Function TCA is an 8-bit up-counter, which is incremented by the input internal clock. The TCA input clock is selected by TMA. TCA cannot be read or written to. When TCA overflows, the timer A interrupt request flag (IFTA) is set to "1". TCA is initialized to \$00 when reset and in stop mode.

Prescaler S (PSS)

Function PSS is an 11-bit counter to which the system clock is input when in active mode and standby mode, and the subsystem clock is input when in subactive mode*. PSS is initialized to \$000 at a reset, and the system clock count starts when the reset is canceled. PSS operation is halted when reset, in stop mode, and in watch mode*. However, it runs in other operating modes. The PSS output is shared by the internal peripheral modules, the division ratio being set independently for each of the internal peripheral modules.

Timer A Interrupt Request Flag (IFTA)

Function IFTA reflects the existence of the timer A interrupt request. When timer A overflows, IFTA is set to "1". IFTA can only be read/written to (only "0" can be written) using bit operation commands. Note that IFTA is not automatically cleared even when the interrupt is received, and must be cleared by writing "0" using software. IFTA is cleared at a reset and in stop mode.

Timer A Interrupt Mask (IMTA)

Function IMTA is the bit that masks IFTA. When IFTA is set to "1" and, additionally, IMTA is "0", a timer A interrupt request is sent to the CPU (when IE = "1"). If IFTA is set to "1" but IMTA is "1", no interrupt request is sent to the CPU and the timer A interrupt is held. IMTA can only be read or written to using bit operation commands. It is set to "1" at a reset and in stop mode.

Note: * Applies to H4369 only.

- c. Ports R1, R2, and R3 are 4-bit I/O ports, accessed in units of 4 bits. Each of ports R1 to R3 are accessed in 4-bit units using the output commands (LRA and LRB) to control the output level High/Low. The output data is stored in the port data registers (PDR) of the respective pins. The input commands (LAR and LBR) are used for 4-bit access to read the pin levels.
- d. Table 3 describes the functions of the R1, R2, and R3 ports.

Table 3 Functions of R1, R2, and R3 Ports

Data Control Register R1 (DCR1)

Function DCR1 switches the I/O pin function of the R1 port. When any bit of DCR1 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR1 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.

Data Control Register R2 (DCR2)

Function DCR2 switches the I/O pin function of the R2 port. When any bit of DCR2 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR2 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.

Data Control Register R3 (DCR3)

Function DCR3 switches the I/O pin function of the R3 port. When any bit of DCR3 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCR3 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.

Port Data Register (PDR)

Function The I/O pins of the R ports have built-in PDRs to store the output data. When the LRA and LRB commands are executed, the contents of the accumulator (A) and B register (B) are transferred to the PDR of the specified R port. When the corresponding DCR of the R port is "1", the output buffer of the appropriate pin is set ON and the value in the PDR is output via that pin. The PDR is initialized to \$F at a reset.

A/D Mode Register 1 (AMR1)

Function AMR1 is a 4-bit write-only register. Bits AMR13 to AMR10 switch the functions of the ports dual-function pins.

- e. The D ports are 1-bit input output ports, accessed in 1-bit units. Pins D_0 to D_3 are accessed in 1-bit units using the output commands (SED, SEDD, RED, and REDD) to control the High/Low output level. The output data is stored in the PDR of the respective pin. Pins D_0 to D_3 are also accessed in 1-bit units using the input commands (TD and TDD) to test the pin level.
- f. Table 4 describes the functions of the D ports.

Table 4 D Port Functions

Data Control Register D0 (DCD0)

Function DCD0 switches the I/O pin function of pins D_0 to D_3 . When any bit of DCD0 is cleared to "0", the output buffer (CMOS) of the corresponding pin is turned OFF and the output is set to high impedance. When the respective bit of DCD0 is set to "1", the output buffer of the corresponding pin is set ON and the corresponding PDR value is output.

Port Data Register (PDR)

Function The I/O pins D_0 to D_8 have built-in PDRs to store the output data. When the SED or SEDD commands are executed for pins D_0 to D_8 , the corresponding PDR is set to "1". When the RED or REDD commands are executed, the corresponding PDR is cleared to "0". When a corresponding bit to DCD0 to DCD2 is "1", the output buffer of that pin is turned ON and the value in the PDR is output via that pin. The PDR is set to "1" at a reset in stop mode.

Port Mode Register A (PMRA)

Function PMRA is a 4-bit write-only register. PMRA3 switches the function of the D_3 /BUZZ pin.

Port Mode Register B (PMRB)

Function PMRB is a 4-bit write-only register. PMRB0 switches the functions of the D_0/\overline{INT}_0 pin, PMRB1 switches D_1/\overline{INT}_1 , and PMRB2 switches D_2 /EVNB.

3. Table 5 describes the allocation of functions in this example task.

Table 5 Allocation of Functions

Function	Function Allocation
System clock	The system clock is obtained by dividing the clock output from the system clock oscillator by 4. It is used for operating the CPU and internal peripheral modules. In this example task, a 4 MHz system clock oscillator is used, so the clock supplied to the CPU and internal peripheral modules is 1 MHz. The clock used by timer B and timer C is obtained by dividing the 1 MHz clock at PSS.
PSS	Generates the clock input to timer A by dividing the system clock. The clock input to timer A is obtained by dividing the system clock by 8.
TCA	This 8-bit up-counter counts on the input internal clock ($(4 \text{ MHz}/4) / 8 = 125 \text{ kHz}$). IFTA is set to "1" when TCA overflows.
TMA	Selects the system clock divided by 8 as the TCA input clock.
IFTA	Reflects the existence of timer A interrupt requests.
IMTA	Enables/disables timer A interrupt requests.
DCD0	Sets D_0 to D_3 to function as output pins.
DCR1	Sets $R1_0$ to $R1_3$ of the R1 port to function as output pins.
DCR2	Sets $R2_0$ to $R2_3$ of the R2 port to function as output pins.
DCR3	Sets $R3_0$ and $R3_1$ of the R3 port to function as output pins.
PDR	Stores the data output from the respective pins.
AMR1	Sets the $R3_0/AN_0$ to $R3_3/AN_3$ pins to function as $R3_0$ to $R3_3$ I/O pins.
PMRA	Sets the $D_3/BUZZ$ pin to function as a D_3 I/O pin.
PMRB	Sets the D_0/\overline{INT}_0 pin to function as D_0 I/O pin, D_1/\overline{INT}_1 pin to function as D_1 I/O pin, and $D_2/EVNB$ pin to function as D_2 I/O pin.
Pins $R1_0$ to $R1_3$	Output pins for Strb0/LED a to Strb3/LED d signals.
Pins $R2_0$ to $R2_3$	Output pins for Strb4/LED e to Strb7/LED h signals.
Pins $R3_0$ and $R3_1$	Input pins for Ret0 and Ret1 signals.
Pins D_0 to D_3	Output pins for LED deg1 to LED deg3 signals.

Description of Operation

1. Figure 9 shows the operating principles of key scanning and the 7-segment LED display.

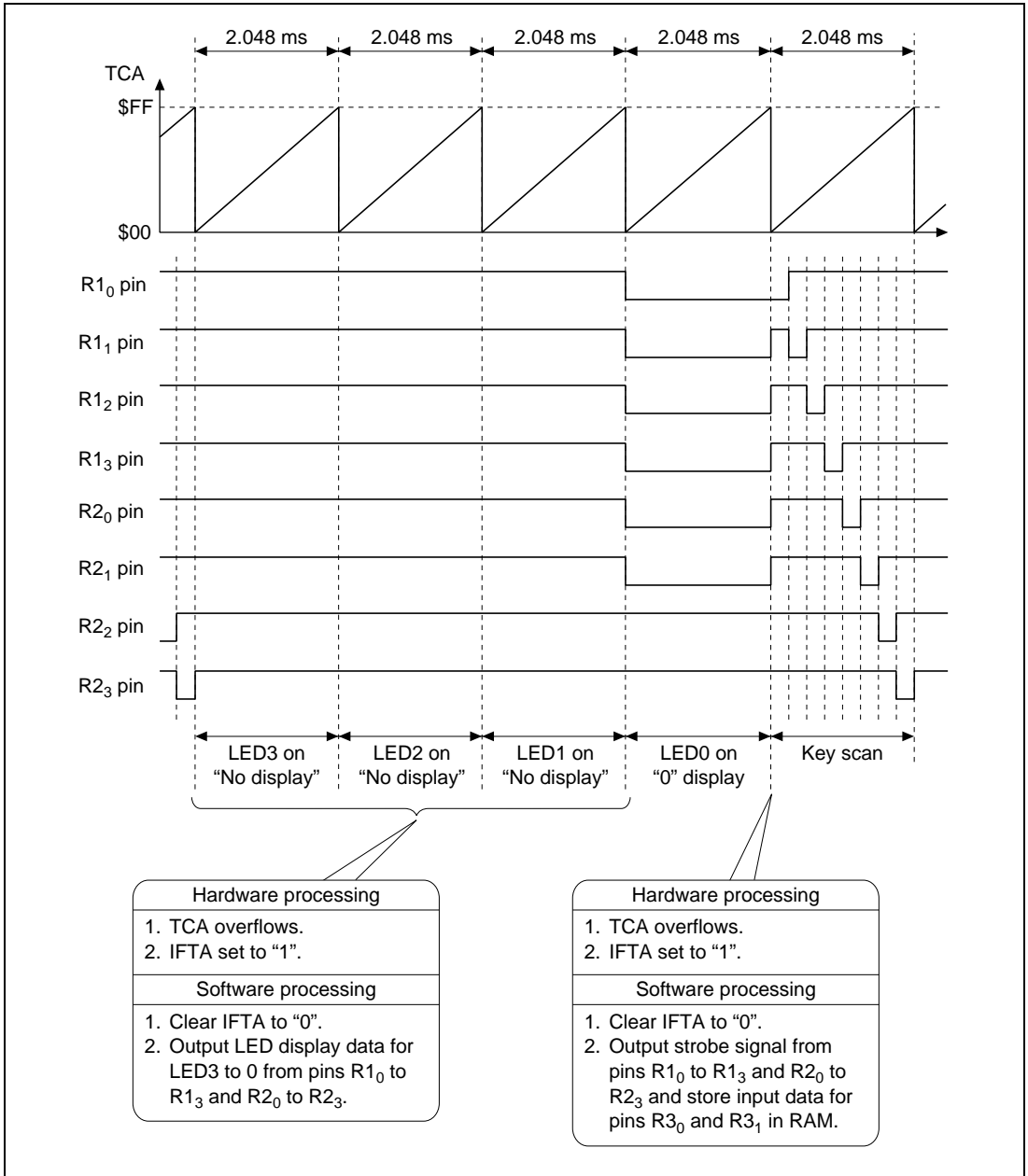


Figure 9 Operating Principles of Key Scanning and 7-Segment LED Display

Description of Software

1. Description of Modules

Table 6 shows the modules used in this example task.

Table 6 **Modules**

Module	Label	Functions
Main routine	LDKYMN	This routine makes the initial stack pointer, RAM, I/O port, and timer A settings, enables interrupts, and calls the KEYDEC and LEDDSP subroutines.
Key decoder	KEYDEC	Converts to key data on completion of key scanning, judges if the key data is the same three times in succession, and suppresses chattering.
LED display	LEDDSP	When the key data is the same three times in succession and is therefore taken to be valid, this routine converts the key data to LED display data and displays the number of the depressed key on the 7-segment LED.
Timer A interrupt processing routine	LDKYINT	Saves the registers, calls the LED and KEY subroutines, and restores registers.
LED control	LED	Controls the lighting of LED0 to LED3.
Key scan	KEY	Performs key scanning by outputting a strobe signal and storing the data input to pins R3 ₀ and R3 ₁ in RAM.

2. Description of Arguments

No arguments are used in this example task.

3. Description of Internal Registers

Table 7 describes the internal registers used in this example task.

Table 7 Internal Registers Used in Example Task

Register	Description	RAM Address	Setting
IE	<p>Interrupt Enable Flag</p> <p>Controls the CPU can receive any interrupts.</p> <ul style="list-style-type: none"> When IE = "0", CPU reception of all interrupts is disabled. When IE = "1", CPU reception is enabled. 	0, \$000	1
RSP	<p>Reset Stack Pointer</p> <p>The stack pointer is initialized by clearing RSP to "0".</p>	1, \$000	0
IFTA	<p>Timer A Interrupt Request Flag</p> <p>Reflects the existence of a timer A interrupt request.</p> <ul style="list-style-type: none"> When IFTA = "0", there is no timer A interrupt request. When IFTA = "1", there is a timer A interrupt request. 	2, \$001	0
IMTA	<p>Timer A Interrupt Mask</p> <p>This bit masks IFTA.</p> <ul style="list-style-type: none"> When IMTA = "0", IFTA is enabled. When IMTA = "1", IFTA is masked. 	3, \$001	0
PMRA	<p>Port Mode Register A</p> <p>Switches the function of the D₃/BUZZ pin.</p> <ul style="list-style-type: none"> When PMRA = "0", the D₃/BUZZ pin functions as the D₃ I/O pin. When PMRA = "1", the D₃/BUZZ pin functions as the BUZZ output pin. 	\$004	\$0
TMA	<p>Timer Mode Register A</p> <p>Selects the timer A clock source and the input clock cycle.</p> <ul style="list-style-type: none"> When TMA3 = "0", the timer A clock source is the PSS. However, this applies only to the H4369. In the H4318/H4359, TMA3 cannot be used. When TMA2 = "1" and TMA1 = "0", and TMA0 = "1", the timer A input clock cycle is set to 8 μs. 	\$008	\$5

Table 7 Internal Registers Used in Example Task (cont)

Register	Description	RAM Address	Setting
AMR1	<p>A/D mode register (AMR1)</p> <p>Switches the function of the R3 port's dual-function pins.</p> <ul style="list-style-type: none"> • When AMR13 = "0", the R3₃/AN₃ pin functions as the R3₃ I/O pin. • When AMR13 = "1", the R3₃/AN₃ pin functions as the AN₃ input pin. • When AMR12 = "0", the R3₂/AN₂ pin functions as the R3₂ I/O pin. • When AMR12 = "1", the R3₂/AN₂ pin functions as the AN₂ input pin. • When AMR11 = "0", the R3₁/AN₁ pin functions as the R3₁ I/O pin. • When AMR11 = "1", the R3₁/AN₁ pin functions as the AN₁ input pin. • When AMR10 = "0", the R3₀/AN₀ pin functions as the R3₀ I/O pin. • When AMR10 = "1", the R3₀/AN₀ pin functions as the AN₀ input pin. 	\$019	\$0
PMRB	<p>Port Mode Register B (PMRB)</p> <p>Switches the function of the D port's dual-function pins.</p> <ul style="list-style-type: none"> • When PMRB2 = "0", the D₂/EVNB pin functions as the D₂ I/O pin. • When PMRB2 = "1", the D₂/EVNB pin functions as the EVNB input pin. • When PMRB1 = "0", the D₁/$\overline{\text{INT}}_1$ pin functions as the D₁ I/O pin. • When PMRB1 = "1", the D₁/$\overline{\text{INT}}_1$ pin functions as the $\overline{\text{INT}}_1$ input pin. • When PMRB0 = "0", the D₀/$\overline{\text{INT}}_0$ pin functions as the D₀ I/O pin. • When PMRB0 = "1", the D₀/$\overline{\text{INT}}_0$ pin functions as the $\overline{\text{INT}}_0$ input pin. 	\$024	\$0

Table 7 Internal Registers Used in Example Task (cont)

Register	Description	RAM Address	Setting
SSR1	System Clock Selection Register 1 Selects the system clock oscillation frequency, subsystem clock frequency division, and, in stop mode, the subsystem clock oscillation. <ul style="list-style-type: none"> When SSR11 = "0", the system clock oscillation frequency is set to 0.4 to 1 MHz. When SSR11 = "1", the system clock oscillation frequency is set to 1.6 to 5 MHz. Note: Applicable only to H4369.	\$027	\$2
DCD0	Data Control Register D0 Controls the ON/OFF state of the D port output buffer. <ul style="list-style-type: none"> When DCD03 to DCD00 = "0", the output buffers of the D₃ to D₀ pins are OFF and output set to high impedance. When DCD03 to DCD00 = "1", the output buffers of the D₃ to D₀ pins are ON and the values of the corresponding PDRs are output. 	\$02C	\$F
DCR1	Data Control Register R1 Controls the ON/OFF state of the R1 port output buffer. <ul style="list-style-type: none"> When DCR13 to DCR10 = "0", the output buffers of the R1₃ to R1₀ pins are OFF and output set to high impedance. When DCR13 to DCR10 = "1", the output buffers of the R1₃ to R1₀ pins are ON and the values of the corresponding PDRs are output. 	\$030	\$F
DCR2	Data Control Register R2 DCR2 switches the output buffer of the R2 port ON/OFF. <ul style="list-style-type: none"> When DCR23 to DCR20 = "0", the output buffers of pins R2₃ to R2₀ are OFF and the pins are in the high impedance state. When DCR23 to DCR20 = "1", The output buffers of pins R2₃ to R2₀ are ON and the values in the corresponding PDRs are output. 	\$031	\$F

Table 7 Internal Registers Used in Example Task (cont)

Register	Description	RAM Address	Setting
DCR3	Data Control Register R3 DCR3 switches the output buffer of the R3 port ON/OFF. <ul style="list-style-type: none"> When DCR33 to DCR30 = "0", the output buffers of pins R3₃ to R3₀ are OFF and the pins are in the high impedance state. When DCR33 to DCR30 = "1", The output buffers of pins R3₃ to R3₀ are ON and the values in the corresponding PDRs are output. 	\$032	\$0

4. Description of RAM

Table 8 describes the RAM used in this example task.

Table 8 RAM

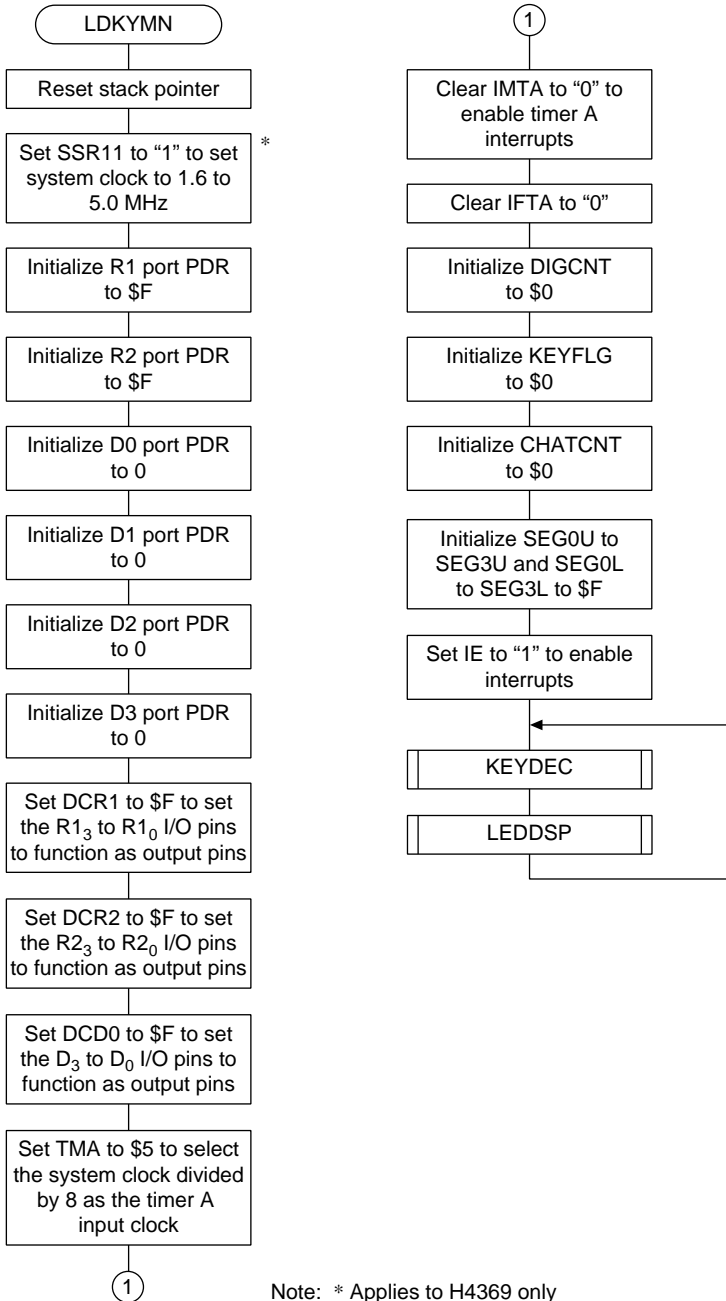
Label	Description	RAM Address	Module
AESC	Stores content of accumulator when processing timer A interrupt.	\$040	LDKYINT
BESC	Stores content of B register when processing timer A interrupt.	\$041	LDKYINT
XESC	Stores content of X register when processing timer A interrupt.	\$043	LDKYINT
YESC	Stores content of Y register when processing timer A interrupt.	\$044	LDKYINT
DIGCNT	Counter to control output to 7-segment LED.	\$054	LDKYMN, LED, KEY
SEG0L	Stores lower 4 bits of display data output to LED0.	\$050	LDKYMN, LEDDSP, LED
SEG1L	Stores lower 4 bits of display data output to LED1.	\$051	LDKYMN, LEDDSP, LED
SEG2L	Stores lower 4 bits of display data output to LED2.	\$052	LDKYMN, LEDDSP, LED
SEG3L	Stores lower 4 bits of display data output to LED3.	\$053	LDKYMN, LEDDSP, LED
SEG0U	Stores upper 4 bits of display data output to LED0.	\$060	LDKYMN, LEDDSP, LED

Table 8 RAM (cont)

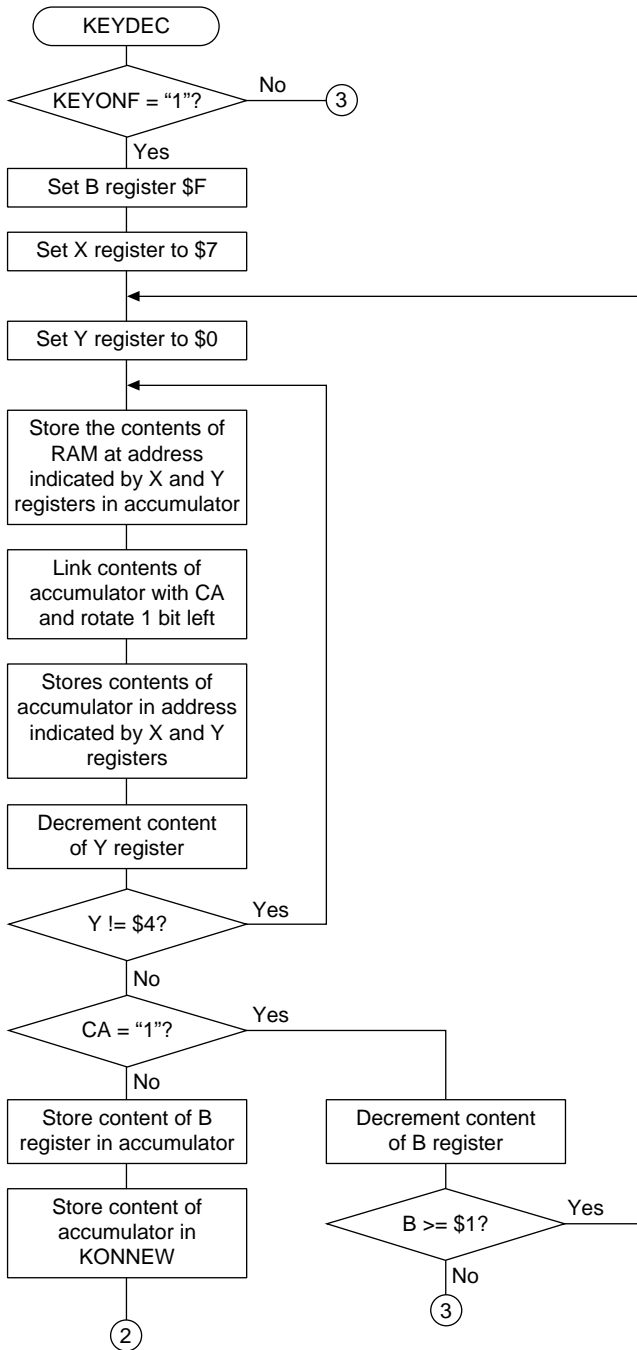
Label	Description	RAM Address	Module
SEG1U	Stores upper 4 bits of display data output to LED1.	\$061	LDKYMN, LEDDSP, LED
SEG2U	Stores upper 4 bits of display data output to LED2.	\$062	LDKYMN, LEDDSP, LED
SEG3U	Stores upper 4 bits of display data output to LED3.	\$063	LDKYMN, LEDDSP, LED
KEYFLG	Stores KEYONF and KDECONF.	\$080	—
KEYONF	Flag showing end of key scanning.	0, \$080	LDKYMN, KEYDEC, KEY
KDECONF	Flag confirming key data.	1, \$080	LDKYMN, KEYDEC, LEDDSP
KONNEW	Stores new key data	\$07F	KEYDEC, LEDDSP
KONOLD	Stores old key data	\$07E	KEYDEC
CHATCNT	Counter to suppress chattering	\$07D	LDKYMN, KEYDEC
STRBU	Stores upper 4 bits of output strobe signal	\$079	KEY
STRBL	Stores lower 4 bits of output strobe signal	\$078	KEY

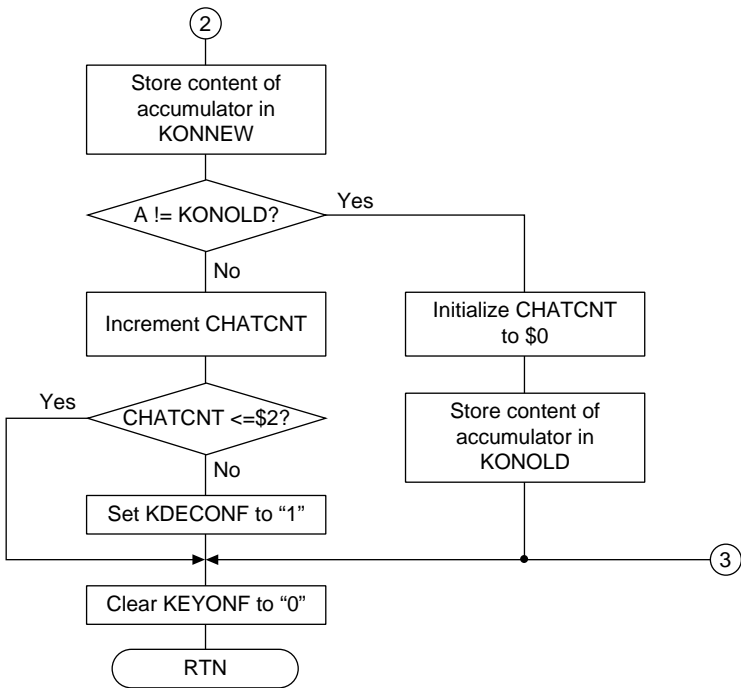
Flowcharts

1. Main Routine

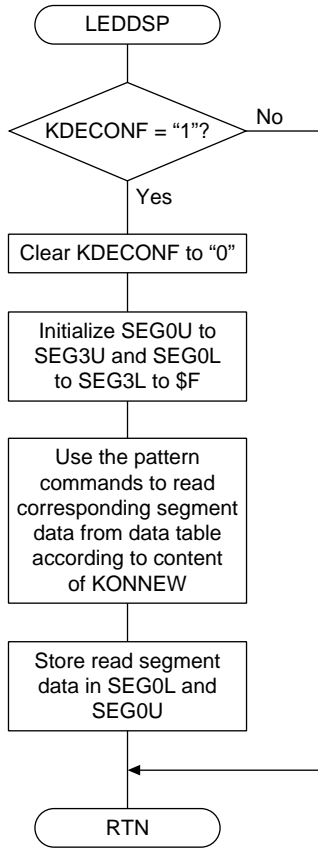


2. Key Decoder

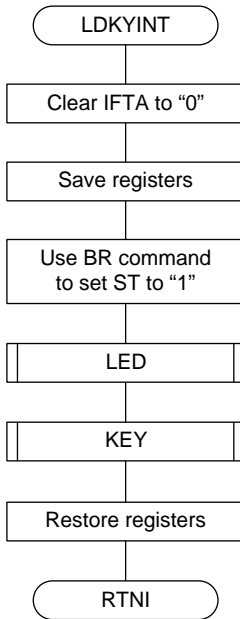




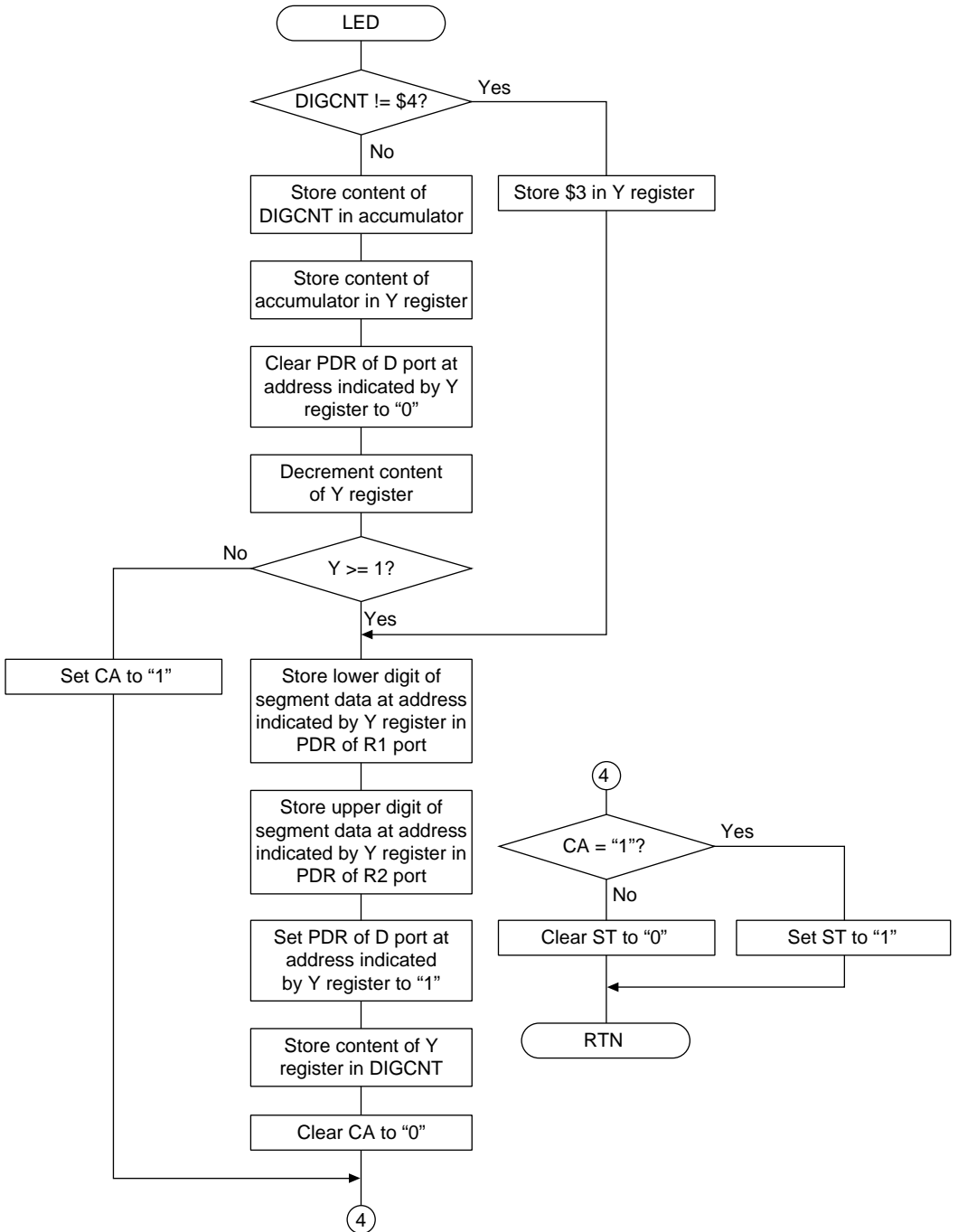
3. LED Display



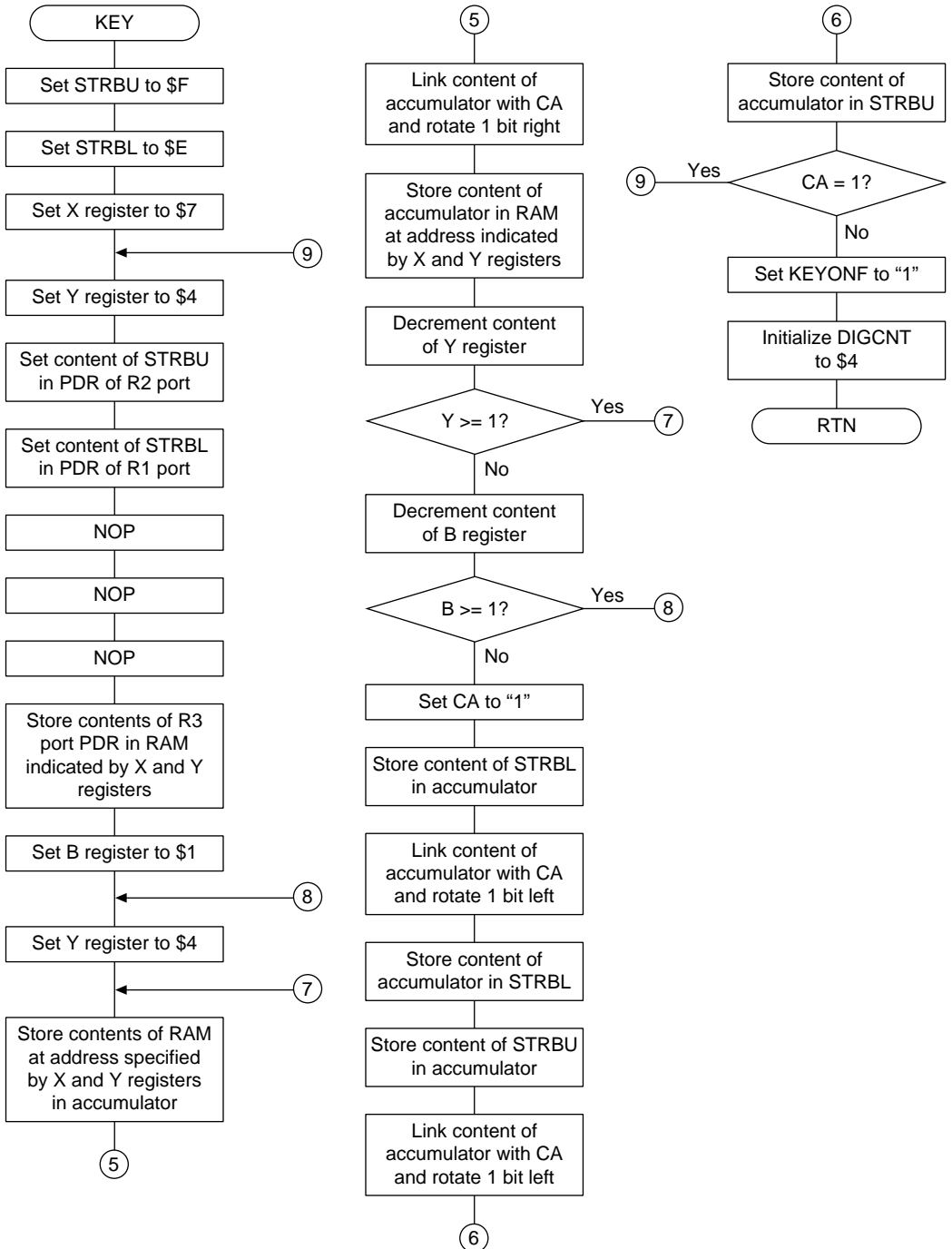
4. Timer A Interrupt Processing Routine



5. LED Control



6. Key Scan



Program Listing

1. H4318/H4359

```
*****
*
*      H400 Series Application Note
*      - Application Chapter -
*
*      'Keyscan & 8-segment LED Display'
*
*      Function
*      : Timer A Free Running Timer
*      : I/O Port (D0-D3, R1-R3 Port)
*
*      MCU : H4318/H4359
*
*      External Clock : 4MHz
*      Internal Clock : 1MHz
*
```

```
*****
*
```

```
*****
*      Symbol Definition
*****
```

```
*
```

IE	equ	0,\$000	Interrupt Request Flag
RSP	equ	1,\$000	Reset Stack Pointer
IF0	equ	2,\$000	_INT0 Interrupt Request Flag
IM0	equ	3,\$000	_INT0 Interrupt Mask
*			
IF1	equ	0,\$001	_INT1 Interrupt Request Flag
IM1	equ	1,\$001	_INT1 Interrupt Mask
IFTA	equ	2,\$001	Timer A Interrupt Request Flag
IMTA	equ	3,\$001	Timer A Interrupt Mask
*			
IFTB	equ	0,\$002	Timer B Interrupt Request Flag
IMTB	equ	1,\$002	Timer B Interrupt Mask
IFTC	equ	2,\$002	Timer C Interrupt Request Flag
IMTC	equ	3,\$002	Timer C Interrupt Mask
*			
IFAD	equ	0,\$003	A/D Converter Interrupt Request Flag
IMAD	equ	1,\$003	A/D Converter Interrupt Mask
IFS	equ	2,\$003	Serial Interrupt Request Flag
IMS	equ	3,\$003	Serial Interrupt Mask
*			
PMRA	equ	\$004	Port Mode Register A
SMR	equ	\$005	Serial Mode Register
SRL	equ	\$006	Serial Data Register L
SRU	equ	\$007	Serial Data Register U
TMA	equ	\$008	Timer Mode Register A

```

TMB1    equ    $009    Timer Mode Register B1
TRBL    equ    $00A    Timer Read Register BL
TWBL    equ    $00A    Timer Write Register BL
TRBU    equ    $00B    Timer Read Register BU
TWBU    equ    $00B    Timer Write Register BU
MIS     equ    $00C    Miscellaneous register
TMC     equ    $00D    Timer Mode Register C
TRCL    equ    $00E    Timer Read Register CL
TWCL    equ    $00E    Timer Write Register CL
TRCU    equ    $00F    Timer Read Register CU
TWCU    equ    $00F    Timer Write Register CU
ACR     equ    $016    A/D Control Register
ADRL    equ    $017    A/D Data Register L
ADRU    equ    $018    A/D Data Register U
AMR1    equ    $019    A/D Mode Register 1
AMR2    equ    $01A    A/D Mode Register 2
*
WDON    equ    1,$020    Watchdog on Flag
ADSF    equ    2,$020    A/D Start Flag
*
ICSF    equ    0,$021    Input Capture Status Flag
ICEF    equ    1,$021    Input Capture Error Flag
IAOF    equ    2,$021    I_AD off Flag
RAME    equ    3,$021    RAM Enable Flag
*
PMRB    equ    $024    Port Mode Register B
PMRC    equ    $025    Port Mode Register C
TMB2    equ    $026    Timer Mode Register B2
DCD0    equ    $02C    Data Control Register D0
DCD1    equ    $02D    Data Control Register D1
DCD2    equ    $02E    Data Control Register D2
DCR0    equ    $030    Data Control Register R0
DCR1    equ    $031    Data Control Register R1
DCR2    equ    $032    Data Control register R2
DCR3    equ    $033    Data Control Register R3
DCR4    equ    $034    Data Control Register R4
DCR8    equ    $038    Data Control Register R8
*
*****
*          Ram Allocation
*****
*
AESC    equ    $040    A Escape RAM Area
BESC    equ    $041    B Escape RAM Area
WESC    equ    $042    W Escape RAM Area
XESC    equ    $043    X Escape RAM Area
YESC    equ    $044    Y Escape RAM Area
SXESC   equ    $045    SPX Escape RAM Area
SYESC   equ    $046    SPY Escape RAM Area
*
DIGCNT  equ    $054    LED Digit Counter

```

```

*
SEG0U equ $060 LED Display Data 0 Upper
SEG1U equ $061 LED Display Data 1 Upper
SEG2U equ $062 LED Display Data 2 Upper
SEG3U equ $063 LED Display Data 3 Upper
*
SEG0L equ $050 LED Display Data 0 Lower
SEG1L equ $051 LED Display Data 1 Lower
SEG2L equ $052 LED Display Data 2 Lower
SEG3L equ $053 LED Display Data 3 Lower
*
KEYFLG equ $080 Key Flag Area
KEYONF equ 0,KEYFLG Key on Flag
KDECONF equ 1,KEYFLG Key Decode on Flag
*
KONNEW equ $07F Key New Data
KONOLD equ $07E Key Old Data
CHATCNT equ $07D Chattering Counter
KEYYADR equ $07A
STRBU equ $079 Key Strobe Data UpperPPER
STRBL equ $078 Key Strobe Data Lower

```

```

*****

```

```

* Vector Address

```

```

*****

```

```

* org $0000

```

```

*
JMPL LDKYMN Reset Interrupt
JMPL LDKYMN _INT0 Interrupt
JMPL LDKYMN _INT1 Interrupt
JMPL LDKYINT Timer A Interrupt
JMPL LDKYMN Timer B Interrupt
JMPL LDKYMN Timer C Interrupt
JMPL LDKYMN A/D Converter Interrupt
JMPL LDKYMN SCI Interrupt

```

```

*****

```

```

* LDKYMN : Main Program

```

```

*****

```

```

* org $1000

```

```

* LDKYMN REMD RSP Reset Stack Pointer

```

```

*
LAI $F
LRA $1 Initialize R1 Port PDR
LRA $2 Initialize R2 Port PDR
REDD $0 Initialize D0 Port PDR
REDD $1 Initialize D1 Port PDR
REDD $2 Initialize D2 Port PDR

```

```

REDD    $3          Initialize D3 Port PDR
LMID    $F,DCR1     Initialize R1 Port Terminal Function
LMID    $F,DCR2     Initialize R2 Port Terminal Function
LMID    $F,DCD0     Initialize D0-D3 Port Terminal Function
*
LMID    $5,TMA      Initialize Timer A Input Clock Period
REMD    IMTA        Timer A Interrupt Enable
REMD    IFTA        Clear IFTA
*
LMID    $0,DIGCNT   Initialize LED Digit Counter
LMID    $0,KEYFLG   Initialize Key on Flag & Key Decode on Flag
LMID    $0,CHATCNT  Initialize Chattering Counter
*
LXI     $6          Initialize LED Display Data
XSPX
LXI     $5
LYI     $3
LAI     $F
LKMN10  LMAX
        LMADYX
        BRS    LKMN10
*
SEMD    IE          Interrupt Enable
*
LKMN90  CALL    KEYDEC  Subroutine Jump to KEYDEC
        CALL    LEDDSP  Subroutine Jump to LEDDSP
        BRS    LKMN90  Branch to LKMN90
*
*****
*      KEYDEC : Key Decoder
*****
*
KEYDEC  TMD    KEYONF   KEYONF = "1" ? Keyscan End ?
        BRS    KD10     Yes. Branch to KD10
        BRS    KD90     NO. Branch to KD90
*
KD10    LBI     $F
        LXI     $7
KD12    LYI     $0
KD15    LAM
        ROTL    Rotate Left with Carry
        LMAIY   Save Key Data. Increment Y Register
        YNEI    $4      Y+1 != 0
        BRS    KD15     Yes. Branch to KD15
        TC      No. CA = 1 ?
        BRS    KD16     Yes. Branch to KD16
        LAB
        LMAD    KONNEW  Save Key on New Data
        BRS    KD20
KD16    DB      Decrement B Register. B >= 1 ?
        BRS    KD12     Yes. Branch to KD12

```



```

      BRS      KD90      No. Branch to KD90
*
KD20  LMAD      KONNEW    Load Key on New Data
      ANEMD     KONOLD    Key on New Data != Key on Old Data ?
      BRS      KD21      Yes. Branch to KD21
      LAMD     CHATCNT    Load Chattering Counter
      AI       $1        Increment Chattering Counter
      LMAD     CHATCNT    Save Chattering Counter
      ALEI     $2        A <= $2 ?
      BRS      KD90      Yes. Branch to KD90
      SEMD     KDECONF    Set Key Decode on Flag
      BRS      KD90      Branch to KD90
KD21  LMID     $0,CHATCNT Initialize Chattering Counter
      LMAD     KONOLD    Save Key on Old Data
*
KD90  REMD     KEYONF    Clear Key on Flag
      RTN
*
*****
*      LEDDSP : LED Display
*****
*
LEDDSP TMD      KDECONF    KDECONF = 1 ?
      BRS      LDSP10    Yes. Branch to LDSP10
      BRS      LDSP90    No. Branch to LDSP90
*
LDSP10 REMD     KDECONF    Clear Key Decode on Flag
*
      LXI     $6          Initialize LED Display Data
      XSPX
      LXI     $5
      LYI     $3
      LAI     $F
LDSP20 LMAX
      LMADYX                End ?
      BRS      LDSP20    No. Branch to LDSP20
*
      LAMD     KONNEW    Load Key Data
      LBI     $0
      P       $F          Pattern Generation
      LMAD     SEG0L     Save LED Display Data Lower
      LAB
      LMAD     SEG0U     Save LED Display Data Upper
*
LDSP90 RTN
*
*****
*      LDKYINT : Timer A Interrupt Routine
*****
*
LDKYINT REMD     IFTA      Clear Timer A Interrupt Request Flag

```

```

*
    LMAD    AESC      Store Accumulator
    LAB
    LMAD    BESC      Store B Register
    XSPX
    LASPX
    LMAD    XESC      Store X Register
    XSPX
    LAY
    LMAD    YESC      Store Y Register
*
    BR      *+1       Set Status Flag
    CALL    LED        Subroutine Jump to 'LED'
    CALL    KEY        Subroutine Jump to 'KEY'
*
    LAMD    YESC      Restore Y Register
    LYA
    LAMD    XESC      Restore X Register
    LXA
    LAMD    BESC      Restore B Register
    LBA
    LAMD    AESC      Restore Accumulator
*
    RTNI                    Return from Interrupt
*
*****
*      LED : LED Control
*****
*
LED    INEMD  $4,DIGCNT  DIGCNT = 4 ?
      BRS    LED00      No. Branch to LED00
      LYI    $3         Yes. Initialize DIGCNT
      BRS    LED10      Branch to LED10
LED00  LAMD   DIGCNT    Load DIGCNT
      LYA
      RED                    Turn off Now Digit
      DY                    D >= 1 ?
      BRS    LED10      Yes. Branch to LED10
      SEC                    No. Set CA
      BRS    LED20      Branch to LED20
LED10  LXI    $5         Load LED Display Data
      LAM
      LRA    $1         Output Display Data Lower to R1 Port
      LXI    $6
      LAM
      LRA    $2         Output Display Data Upper to R2 Port
      SED                    Turn on Next Digit
      LAY
      LMAD   DIGCNT    Save DIGCNT
      REC                    Reset CA
LED20  TC      Test CA

```

```

*
      RTN                      Return from Subroutine
*
*****
*      KEY : Key Scan
*****
*
KEY    LMID    $F,STRBU    Initialize Strobe Data Upper
      LMID    $E,STRBL    Initialize Strobe Data Lower
      LXI    $7
*
KEY00  LYI    $4
      LAMD  STRBU    Load Strobe Data Upper
      LRA   $2      Output Strobe Data Upper to R2 Port
      LAMD  STRBL    Load Strobe Data Lower
      LRA   $1      Output Strobe Data Lower to R1 Port
      NOP
      NOP          Wait
      NOP          Wait
      LAR   $3      Input Key Return Data
      LMA
*
      LBI    $1
KEY10  LYI    $4
KEY20  LAM
      ROTR          Rotate Right with Carry
      LMADY         Save Key Return Data. Y >= 1 ?
      BRS    KEY20   Yes. Branch to KEY20
      DB
      BRS    KEY10   Yes. Branch to KEY10
*
      SEC          Set CA
      LAMD  STRBL    Load Strobe Data
      ROTL          Rotate Left with Carry
      LMAD  STRBL    Save Strobe Data
      LAMD  STRBU    Load Strobe Data
      ROTL          Rotate Left with Carry
      LMAD  STRBU    Save Strobe Data
      TC          CA = 1 ?
      BRS    KEY00   Yes. Branch to KEY20
*
      SEMD  KEYONF   Set KEYONF
*
KEY90  LMID    $4,DIGCNT  Initialize DIGCNT
*
      RTN
*
*****
*      LED Display Data Table
*****
*

```

```

org      $F00

*
dc      $1C0      LED Display Data "0"
dc      $1F9      LED Display Data "1"
dc      $1A4      LED Display Data "2"
dc      $1B0      LED Display Data "3"
dc      $199      LED Display Data "4"
dc      $192      LED Display Data "5"
dc      $182      LED Display Data "6"
dc      $1D8      LED Display Data "7"
dc      $180      LED Display Data "8"
dc      $190      LED Display Data "9"
dc      $188      LED Display Data "A"
dc      $183      LED Display Data "B"
dc      $1C6      LED Display Data "C"
dc      $1A1      LED Display Data "D"
dc      $186      LED Display Data "E"
dc      $18E      LED Display Data "F"

*

end

```

2. H4369

```
*****
*
*      H400 Series Application Note
*      - Application Chapter -
*
*      'Keyscan & 8-segment LED Display'
*
*      Function
*      : Timer A Free Running Timer
*      : I/O Port (D0-D3, R1-R3 Port)
*
*      MCU : H4369
*
*      External Clock : 4MHz
*      Internal Clock : 1MHz
*      Sub Clock      : 32.768kHz
*
*****
*
*****
*      Symbol Definition
*****
*
IE      equ      0,$000      Interrupt Request Flag
RSP     equ      1,$000      Reset Stack Pointer
IF0     equ      2,$000      _INT0 Interrupt Request Flag
IM0     equ      3,$000      _INT0 Interrupt Mask
*
IF1     equ      0,$001      _INT1 Interrupt Request Flag
IM1     equ      1,$001      _INT1 Interrupt Mask
IFTA    equ      2,$001      Timer A Interrupt Request Flag
IMTA    equ      3,$001      Timer A Interrupt Mask
*
IFTB    equ      0,$002      Timer B Interrupt Request Flag
IMTB    equ      1,$002      Timer B Interrupt Mask
IFTC    equ      2,$002      Timer C Interrupt Request Flag
IMTC    equ      3,$002      Timer C Interrupt Mask
*
IFAD    equ      0,$003      A/D Converter Interrupt Request Flag
IMAD    equ      1,$003      A/D Converter Interrupt Mask
IFS     equ      2,$003      Serial Interrupt Request Flag
IMS     equ      3,$003      Serial Interrupt Mask
*
PMRA    equ      $004        Port Mode Register A
SMR     equ      $005        Serial Mode Register
SRL     equ      $006        Serial Data Register L
SRU     equ      $007        Serial Data Register U
TMA     equ      $008        Timer Mode Register A
TMB1    equ      $009        Timer Mode Register B1
```

TRBL	equ	\$00A	Timer Read Register BL
TWBL	equ	\$00A	Timer Write Register BL
TRBU	equ	\$00B	Timer Read Register BU
TWBU	equ	\$00B	Timer Write Register BU
MIS	equ	\$00C	Miscellaneous register
TMC	equ	\$00D	Timer Mode Register C
TRCL	equ	\$00E	Timer Read Register CL
TWCL	equ	\$00E	Timer Write Register CL
TRCU	equ	\$00F	Timer Read Register CU
TWCU	equ	\$00F	Timer Write Register CU
ACR	equ	\$016	A/D Control Register
ADRL	equ	\$017	A/D Data Register L
ADRU	equ	\$018	A/D Data Register U
AMR1	equ	\$019	A/D Mode Register 1
AMR2	equ	\$01A	A/D Mode Register 2
*			
LSON	equ	0,\$020	LSON Flag
WDON	equ	1,\$020	Watchdog on Flag
ADSF	equ	2,\$020	A/D Start Flag
DTON	equ	3,\$020	DTON Flag
*			
ICSF	equ	0,\$021	Input Capture Status Flag
ICEF	equ	1,\$021	Input Capture Error Flag
IAOF	equ	2,\$021	I_AD off Flag
RAME	equ	3,\$021	RAM Enable Flag
*			
PMRB	equ	\$024	Port Mode Register B
PMRC	equ	\$025	Port Mode Register C
TMB2	equ	\$026	Timer Mode Register B2
SSR1	equ	\$027	System Clock Selection Register 1
SSR2	equ	\$028	System Clock Selection register 2
*			
DCD0	equ	\$02C	Data Control Register D0
DCD1	equ	\$02D	Data Control Register D1
DCD2	equ	\$02E	Data Control Register D2
DCD3	equ	\$02F	Data Control Register D3
*			
DCR0	equ	\$030	Data Control Register R0
DCR1	equ	\$031	Data Control Register R1
DCR2	equ	\$032	Data Control register R2
DCR3	equ	\$033	Data Control Register R3
DCR4	equ	\$034	Data Control Register R4
DCR5	equ	\$035	Data Control Register R5
DCR6	equ	\$036	Data Control Register R6
DCR7	equ	\$037	Data Control Register R7
DCR8	equ	\$038	Data Control Register R8
DCR9	equ	\$039	Data Control Register R9
*			

* Ram Allocation

```

*
AESC      equ      $040      A Escape RAM Area
BESC      equ      $041      B Escape RAM Area
WESC      equ      $042      W Escape RAM Area
XESC      equ      $043      X Escape RAM Area
YESC      equ      $044      Y Escape RAM Area
SXESC     equ      $045      SPX Escape RAM Area
SYESC     equ      $046      SPY Escape RAM Area
*
DIGCNT    equ      $054      LED Digit Counter
*
SEG0U     equ      $060      LED Display Data 0 Upper
SEG1U     equ      $061      LED Display Data 1 Upper
SEG2U     equ      $062      LED Display Data 2 Upper
SEG3U     equ      $063      LED Display Data 3 Upper
*
SEG0L     equ      $050      LED Display Data 0 Lower
SEG1L     equ      $051      LED Display Data 1 Lower
SEG2L     equ      $052      LED Display Data 2 Lower
SEG3L     equ      $053      LED Display Data 3 Lower
*
KEYFLG    equ      $080      Key Flag Area
KEYONF    equ      0,KEYFLG  Key on Flag
KDECONF   equ      1,KEYFLG  Key Decode on Flag
*
KONNEW    equ      $07F      Key New Data
KONOLD    equ      $07E      Key Old Data
CHATCNT   equ      $07D      Chattering Counter
KEYYADR   equ      $07A
STRBU     equ      $079      Key Strobe Data UpperPPER
STRBL     equ      $078      Key Strobe Data Lower
*

```

```
*****
```

```
*          Vector Address
```

```
*****
```

```
*
          org      $0000
*

```

```

          JMPL     LDKYMN      Reset Interrupt
          JMPL     LDKYMN      _INT0 Interrupt
          JMPL     LDKYMN      _INT1 Interrupt
          JMPL     LDKYINT     Timer A Interrupt
          JMPL     LDKYMN      Timer B Interrupt
          JMPL     LDKYMN      Timer C Interrupt
          JMPL     LDKYMN      A/D Converter Interrupt
          JMPL     LDKYMN      SCI Interrupt
*

```

```
*****
```

```
*          LDKYMN : Main Program
```

```
*****
```

```
*
```

```

    org      $1000
*
LDKYMN    REMD    RSP      Reset Stack Pointer
          LMID    $2,SSR1   Initialize System Clock
*
          LAI     $F
          LRA     $1        Initialize R1 Port PDR
          LRA     $2        Initialize R2 Port PDR
          REDD    $0        Initialize D0 Port PDR
          REDD    $1        Initialize D1 Port PDR
          REDD    $2        Initialize D2 Port PDR
          REDD    $3        Initialize D3 Port PDR
          LMID    $F,DCR1   Initialize R1 Port Terminal Function
          LMID    $F,DCR2   Initialize R2 Port Terminal Function
          LMID    $F,DCD0   Initialize D0-D3 Port Terminal Function
*
          LMID    $5,TMA    Initialize Timer A Input Clock Period
          REMD    IMTA      Timer A Interrupt Enable
          REMD    IFTA      Clear IFTA
*
          LMID    $0,DIGCNT Initialize LED Digit Counter
          LMID    $0,KEYFLG Initialize Key on Flag & Key Decode on Flag
          LMID    $0,CHATCNT Initialize Chattering Counter
*
          LXI     $6        Initialize LED Display Data
          XSPX
          LXI     $5
          LYI     $3
          LAI     $F
LKMN10    LMAX
          LMADYX
          BRS     LKMN10
*
          SEMD    IE        Interrupt Enable
*
LKMN90    CALL    KEYDEC    Subroutine Jump to KEYDEC
          CALL    LEDDSP    Subroutine Jump to LEDDSP
          BRS     LKMN90    Branch to LKMN90
*
*****
*          KEYDEC : Key Decoder
*****
*
KEYDEC    TMD     KEYONF    KEYONF = "1" ? Keyscan End ?
          BRS     KD10      Yes. Branch to KD10
          BRS     KD90      NO. Branch to KD90
*
KD10     LBI     $F
          LXI     $7
KD12     LYI     $0
KD15     LAM                      Load Key Data

```


	ROTL		Rotate Left with Carry
	LMAIY		Save Key Data. Increment Y Register
	YNEI	\$4	Y+1 != 0
	BRS	KD15	Yes. Branch to KD15
	TC		No. CA = 1 ?
	BRS	KD16	Yes. Branch to KD16
	LAB		
	LMAD	KONNEW	Save Key on New Data
	BRS	KD20	
KD16	DB		Decrement B Register. B >= 1 ?
	BRS	KD12	Yes. Branch to KD12
	BRS	KD90	No. Branch to KD90
	*		
KD20	LMAD	KONNEW	Load Key on New Data
	ANEMD	KONOLD	Key on New Data != Key on Old Data ?
	BRS	KD21	Yes. Branch to KD21
	LAMD	CHATCNT	Load Chattering Counter
	AI	\$1	Increment Chattering Counter
	LMAD	CHATCNT	Save Chattering Counter
	ALEI	\$2	A <= \$2 ?
	BRS	KD90	Yes. Branch to KD90
	SEMD	KDECONF	Set Key Decode on Flag
	BRS	KD90	Branch to KD90
KD21	LMID	\$0,CHATCNT	Initialize Chattering Counter
	LMAD	KONOLD	Save Key on Old Data
	*		
KD90	REMD	KEYONF	Clear Key on Flag
	RTN		Return
	*		

	*	LEDDSP : LED Display	

	*		
LEDDSP	TMD	KDECONF	KDECONF = 1 ?
	BRS	LDSP10	Yes. Branch to LDSP10
	BRS	LDSP90	No. Branch to LDSP90
	*		
LDSP10	REMD	KDECONF	Clear Key Decode on Flag
	*		
	LXI	\$6	Initialize LED Display Data
	XSPX		
	LXI	\$5	
	LYI	\$3	
	LAI	\$F	
LDSP20	LMAX		
	LMADYX		End ?
	BRS	LDSP20	No. Branch to LDSP20
	*		
	LAMD	KONNEW	Load Key Data
	LBI	\$0	
	P	\$F	Pattern Generation

```

LMAD SEG0L Save LED Display Data Lower
LAB
LMAD SEG0U Save LED Display Data Upper
*
LDSP90 RTN Return from Subroutine
*
*****
* LDKYINT : Timer A Interrupt Routine
*****
*
LDKYINT REMD IFTA Clear Timer A Interrupt Request Flag
*
LMAD AESC Store Accumulator
LAB
LMAD BESC Store B Register
XSPX
LASPX
LMAD XESC Store X Register
XSPX
LAY
LMAD YESC Store Y Register
*
BR *+1 Set Status Flag
CALL LED Subroutine Jump to 'LED'
CALL KEY Subroutine Jump to 'KEY'
*
LAMD YESC Restore Y Register
LYA
LAMD XESC Restore X Register
LXA
LAMD BESC Restore B Register
LBA
LAMD AESC Restore Accumulator
*
RTNI Return from Interrupt
*
*****
* LED : LED Control
*****
*
LED INEMD $4,DIGCNT DIGCNT = 4 ?
BRS LED00 No. Branch to LED00
LYI $3 Yes. Initialize DIGCNT
BRS LED10 Branch to LED10
LED00 LAMD DIGCNT Load DIGCNT
LYA
RED Turn off Now Digit
DY D >= 1 ?
BRS LED10 Yes. Branch to LED10
SEC No. Set CA
BRS LED20 Branch to LED20

```

```

LED10  LXI    $5      Load LED Display Data
        LAM
        LRA    $1      Output Display Data Lower to R1 Port
        LXI    $6
        LAM
        LRA    $2      Output Display Data Upper to R2 Port
        SED      Turn on Next Digit
        LAY
        LMAD   DIGCNT  Save DIGCNT
        REC      Reset CA
LED20  TC      Test CA
*
        RTN      Return from Subroutine
*
*****
*      KEY : Key Scan
*****
*
KEY    LMID   $F,STRBU  Initialize Strobe Data Upper
        LMID   $E,STRBL  Initialize Strobe Data Lower
        LXI    $7
*
KEY00  LYI    $4
        LAMD   STRBU     Load Strobe Data Upper
        LRA    $2      Output Strobe Data Upper to R2 Port
        LAMD   STRBL     Load Strobe Data Lower
        LRA    $1      Output Strobe Data Lower to R1 Port
        NOP      Wait
        NOP      Wait
        NOP      Wait
        LAR    $3      Input Key Return Data
        LMA      Save Key Return Data
*
        LBI    $1
KEY10  LYI    $4
KEY20  LAM      Load Key Return Data
        ROTR     Rotate Right with Carry
        LMADY     Save Key Return Data. Y >= 1 ?
        BRS    KEY20   Yes. Branch to KEY20
        DB      Decrement B Register. B >= 1 ?
        BRS    KEY10   Yes. Branch to KEY10
*
        SEC      Set CA
        LAMD   STRBL     Load Strobe Data
        ROTL     Rotate Left with Carry
        LMAD   STRBL     Save Strobe Data
        LAMD   STRBU     Load Strobe Data
        ROTL     Rotate Left with Carry
        LMAD   STRBU     Save Strobe Data
        TC      CA = 1 ?
        BRS    KEY00   Yes. Branch to KEY20

```

```

*
      SEMD      KEYONF      Set KEYONF
*
KEY90  LMID      $4,DIGCNT  Initialize DIGCNT
*
      RTN
*
*****
*      LED Display Data Table
*****
*
      org      $F00
*
      dc      $1C0      LED Display Data "0"
      dc      $1F9      LED Display Data "1"
      dc      $1A4      LED Display Data "2"
      dc      $1B0      LED Display Data "3"
      dc      $199      LED Display Data "4"
      dc      $192      LED Display Data "5"
      dc      $182      LED Display Data "6"
      dc      $1D8      LED Display Data "7"
      dc      $180      LED Display Data "8"
      dc      $190      LED Display Data "9"
      dc      $188      LED Display Data "A"
      dc      $183      LED Display Data "B"
      dc      $1C6      LED Display Data "C"
      dc      $1A1      LED Display Data "D"
      dc      $186      LED Display Data "E"
      dc      $18E      LED Display Data "F"
*
      end

```