

## Preliminary Information

Fixed Code Encoder  
A SureLok™ Security Product**FEATURES**

- Low Cost Encoder
- 28-bit fixed code transmission  
— 268 million code combinations
- Electrically programmable via E<sup>2</sup>PROM
- Low power indicator bit
- Supports up to seven switches/functions
- Inputs internally debounced/pulled down
- Dual selectable transmission baud rates
- Code Word Blanking
- EIAJ standard PDIPs and SOICs

**DESCRIPTION**

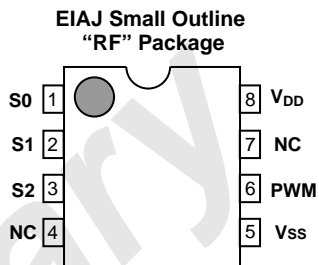
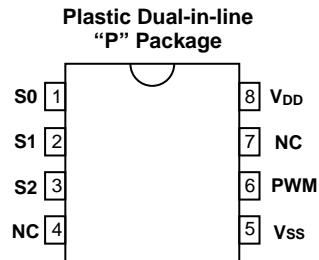
The XL135 is a fixed code encoder intended for secure remote control systems. It is ideal for remote control applications using infrared (IR), microwave or radio frequency (RF) transmitters.

The 28-bit fixed code length prevents unauthorized access through code scanning. The full feature device provides low power detect, to warn the receiver that the transmitter battery is low; two selectable transmission rates to work with a variety of wireless transmission circuits; and code word blanking for FCC power rating considerations.

Designing transmitters based on the XL135 is simple, requiring no peripheral components, only push-button switches and the transmission circuitry.

**Typical applications**

- Vehicle RKE
- Burglar alarm systems
- Garage door openers
- Gate openers
- Home automation
- Remote fan controllers
- Home security

**PIN CONFIGURATION**

D0042 ILL A01.1

**PIN NAMES**

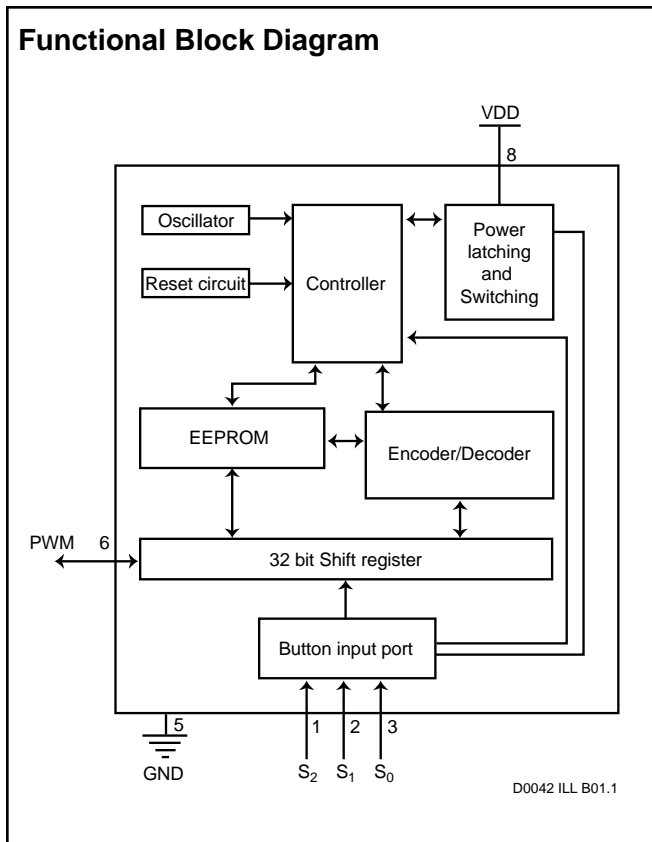
S0-S2	Switch Inputs
NC	No Connection
V <sub>DD</sub>	Supply Voltage
PWM	Pulse Width Modulated Output
V <sub>SS</sub>	Ground

**Overview**

Remote control via RF or IR is popular for the control of vehicle alarms, automatic garage doors and many other applications. Conventional remote control systems have a major security shortcoming in that the number of possible code combinations is relatively small. This can lead to unauthorized access by scanning through all the possible code combinations within a short period of time.

To solve this problem, the XL135 uses a 28 bit fixed code, providing in excess of 268 million combinations, and thus prevents scanning (a complete scan would require around one year).

Significant savings in manufacturing cost can be realized through the E<sup>2</sup>PROM programability offered by the XL135, as opposed to traditional methods of setting codes such as DIP switches and soldering traces.



The XL135 is made possible by special hardware and design techniques along with full custom integrated circuit implementation on state of the art silicon processes.

### Control input ( $S_0$ to $S_2$ ) activation

$S_2$	$S_1$	$S_0$	Function	$S_2$	$S_1$	$S_0$	Function
0	0	0	Reset state	1	0	0	Function 4
0	0	1	Function 1	1	0	1	Function 5
0	1	0	Function 2	1	1	0	Function 6
0	1	1	Function 3	1	1	1	Function 7

D0042 PGM T01.1

When any input ( $S_0$  to  $S_2$ ) is activated, the encoder enters a debounce period. After the debounce period, the inputs are sampled, and the function code is determined. A transmission commences, and is repeated until all buttons have been released.

If more buttons are pressed after the initial transmission has commenced, the encoder immediately resumes its power-on state, passes through the debounce period, and commences the new function code transmission. If buttons are released after the initial transmission has commenced, the transmission is not influenced. The encoder continues to repeat the same transmission until the last button is released.

As a practical example of transmitter operation, consider the case of a user that requires function 3 on a two button transmitter. The two transmitter buttons have to be pressed simultaneously. The user presses the first button first ( $S_2S_1S_0 = 001$ ), and the transmitter commences with a function 1 transmission. When the second button is pressed ( $S_2S_1S_0 = 011$ ), the device immediately re-enters the debounce period, without completing the current transmission, and function 3 is transmitted. Transmission will continue as long as the user is holding down at least one of the buttons.

In all cases, if all the buttons are released while a code word is being transmitted, the code word will be completed before the transmission is terminated.

### Transmission rates

Two transmission rates are available. If the fast rate is selected, alternate code transmissions are blanked, resulting in a 50% reduction in duty cycle. Under U.S.A. FCC regulations, the peak transmitter output can then be doubled, hence allowing for greater transmission ranges with the same average power.

### Low Power Indicator

A low power indicator bit is transmitted by the XL135 to inform the decoder that the transmitter battery is low and requires changing. The  $V_{BAT}$  status bit is zero (0) when above the battery threshold voltage and a one (1) when below it.

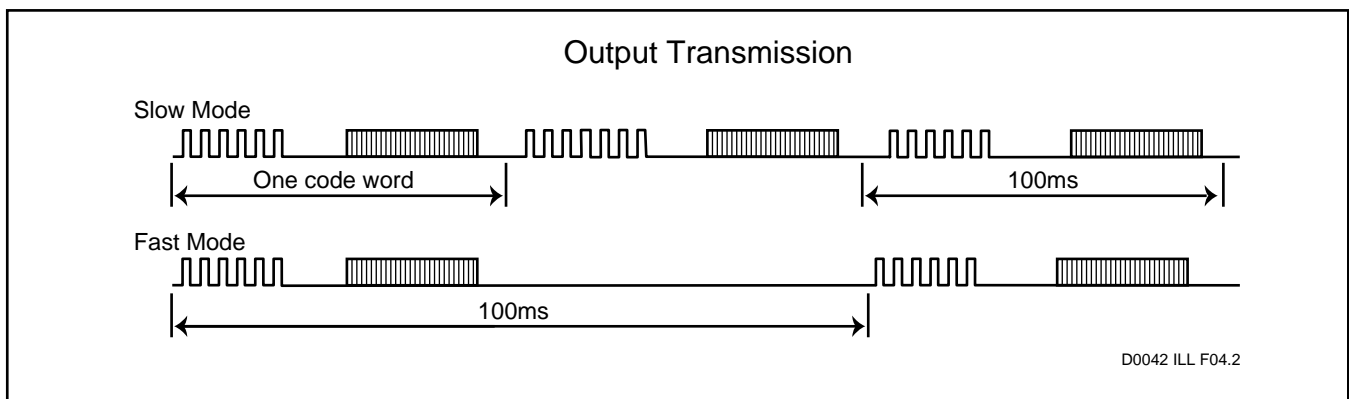
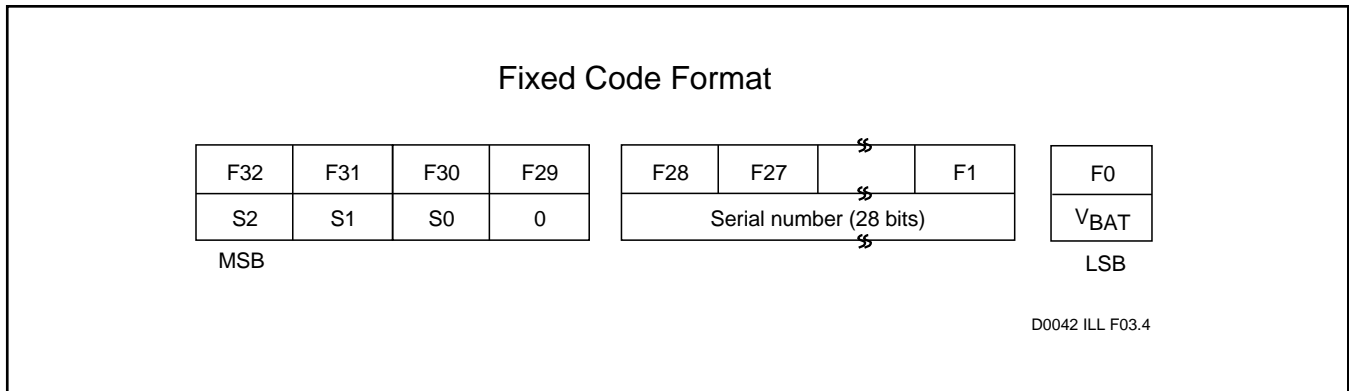
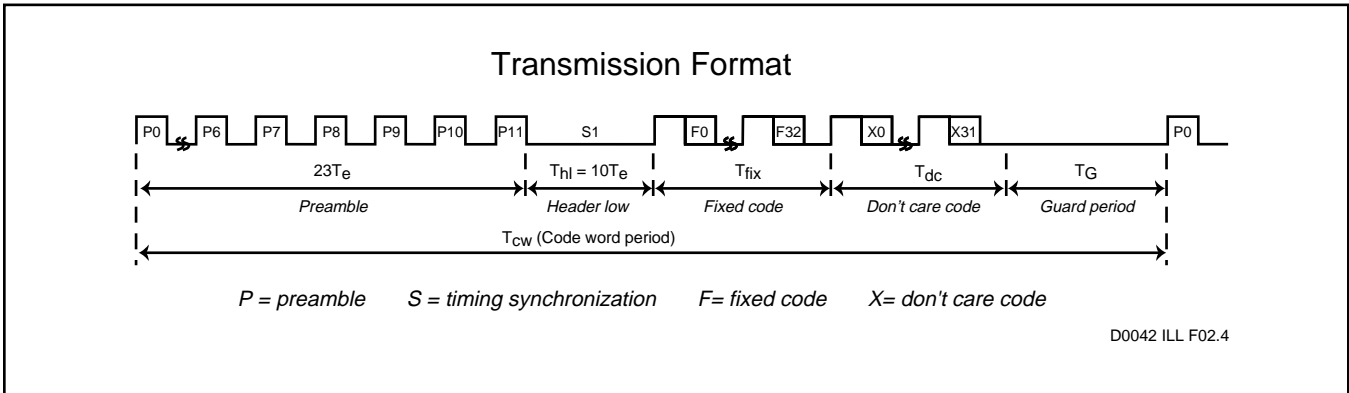
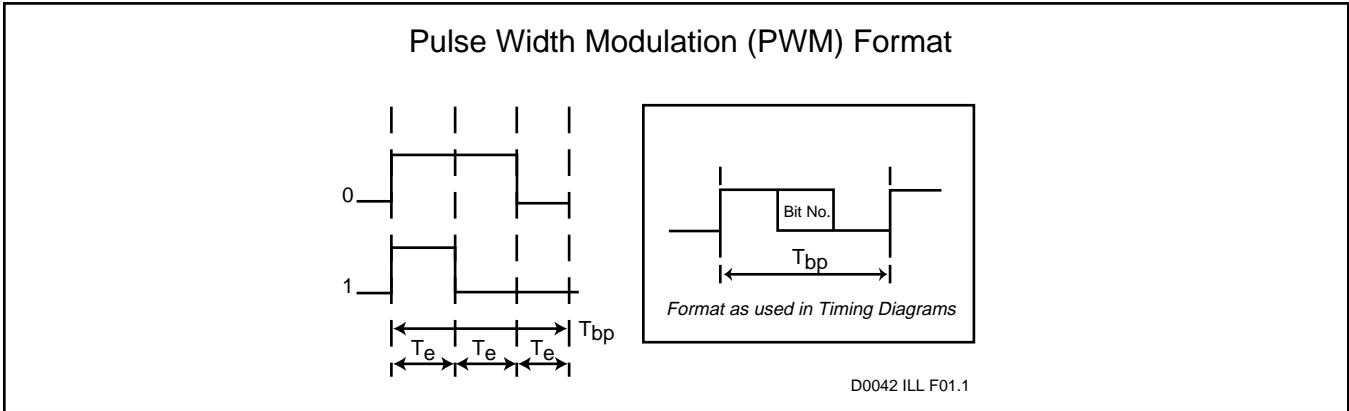
### Implementation

The application circuits clearly indicate the simplicity of implementations using the XL135. No DIP switches, cutting of tracks or soldering is needed. In addition, the small device footprint and no external components facilitate small PC board size and low component count. Only the XL135, transmitter circuitry and push button switches are required realizing significant savings in material and labor.

A PC based programming system is available to program each XL135 with a unique 28-bit fixed code and set the transmission baud rate. A single probe connector is typically used to program an encoder and its matching decoders.

EXEL also supplies evaluation kits to assess the operational aspects of the devices.

**Timing Diagrams**



**ABSOLUTE MAXIMUM RATINGS**

Supply voltage.....-0.3V to 6.5V  
 Voltage on any input ..... -0.3V to V<sub>DD</sub> + 0.3V  
 Voltage on any output ..... -0.3V to V<sub>DD</sub> + 0.3V  
 Storage temperature ..... -55°C to 125°C  
 Lead soldering temperature ..... 300°C  
 Electrostatic discharge rating ..... 3000V

NOTE: These are STRESS ratings only. Appropriate conditions for operating these devices are given elsewhere in this specification. Stresses beyond those listed here may permanently damage the part. Prolonged exposure to maximum ratings may adversely affect device reliability.

**Recommended Operating Conditions**

Symbol	Description	Limits	Units
V <sub>DD</sub>	Supply voltage	2.0 to 6.0	V
T <sub>OPR</sub>	Operating temperature	-40 to 85	°C

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**ELECTRICAL CHARACTERISTICS**

**DC ELECTRICAL CHARACTERISTICS**

TA = -40°C to 85°C, V<sub>DD</sub> = 2.0V to 6.0V

Symbol	Parameter	Test Condition	Minimum	Typical	Maximum	Units
I <sub>DD</sub>	Operating supply current	V <sub>CC</sub> = 5.0V		2.0	4.0	mA
I <sub>res</sub>	Standby current (reset condition)	V <sub>CC</sub> = 3.0V		1.0	3.0	mA
				50	1000	nA
V <sub>IH</sub>	Minimum input voltage for high		0.7 V <sub>DD</sub>			V
V <sub>IL</sub>	Maximum input voltage for low				0.3 V <sub>DD</sub>	V
V <sub>OH</sub>	Minimum output voltage for high		V <sub>CC</sub> - 0.3			V
V <sub>OL</sub>	Maximum output voltage for low				0.3	V
V <sub>BAT</sub>	Battery Low threshold voltage			2.4		V
R <sub>s</sub>	Control input pulldown resistance			60		kΩ
R <sub>PWM</sub>	PWM port pulldown resistance			120		kΩ
	E <sup>2</sup> PROM retention (power off, end of life)		10			years

D0042 PGM T03.3

**AC ELECTRICAL CHARACTERISTICS, PWM OUTPUT**

 TA = -40°C to 85°C, V<sub>DD</sub> = 2.0V to 6.0V

Symbol	Parameter	Min	Typical	Max	Units
T <sub>e</sub>	Slow elemental period	340		500	μs
	Fast elemental period	170		250	μs
	Slow PWM data rate		780		bps
	Fast PWM data rate		1560		bps
T <sub>xx</sub>	Power on to transmit		30		ms
T <sub>DB</sub>	Debounce time		9		ms

D0042 PGM T06.2

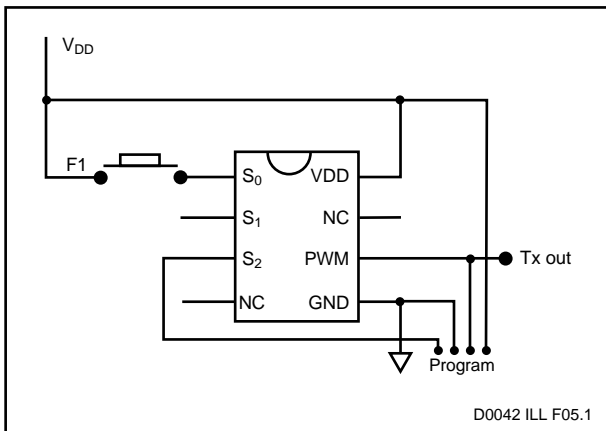
Symbol	Parameter	Slow	Fast	Units
T <sub>bp</sub>	Bit period	3	3	T <sub>e</sub>
T <sub>hl</sub>	Preamble	23	23	T <sub>e</sub>
	Header low	10	10	T <sub>e</sub>
T <sub>fix</sub>	Fixed code	99	99	T <sub>e</sub>
T <sub>dc</sub>	Don't care code	96	96	T <sub>e</sub>
T <sub>G</sub>	Guard period	6	240	T <sub>e</sub>
T <sub>ow</sub>	Code Word period	234	468	T <sub>e</sub>
	Duty cycle minimum <sup>2</sup>	33	16	%
	maximum <sup>2</sup>	61	30	%

D0042 PGM T04.3

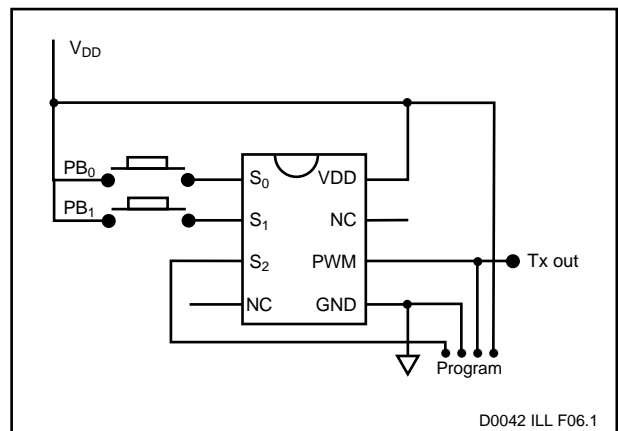
**Notes:**

- Decoders must automatically compensate for data rate variations due to variation in encoder timing parameters.
- Duty cycles are calculated by assuming 12 elements high during the preamble, and either 65 (bits all 1) or 130 (bits all 0) elements high during the transmitted code. For American FCC calculations, the highest duty cycle is  $142 \div 234$  (slow mode), or  $142 \div 468$  (fast mode).

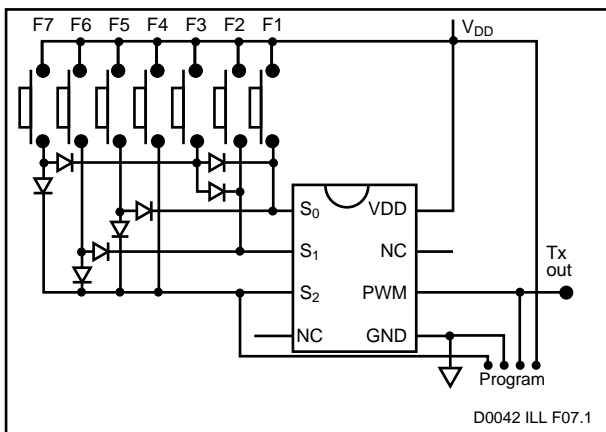
**Application Circuits**



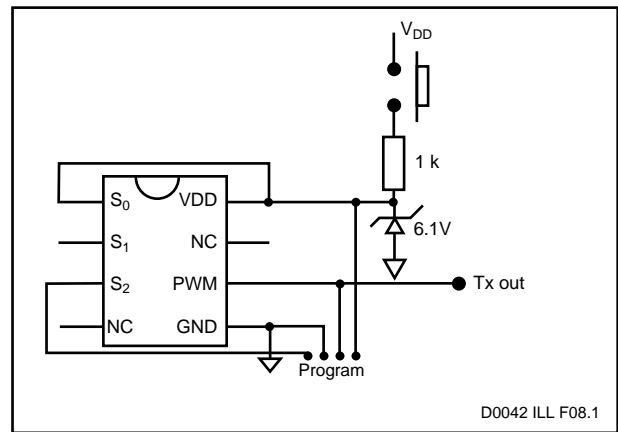
1 button remote control transmitter



3 function remote control transmitter



7 button remote control transmitter

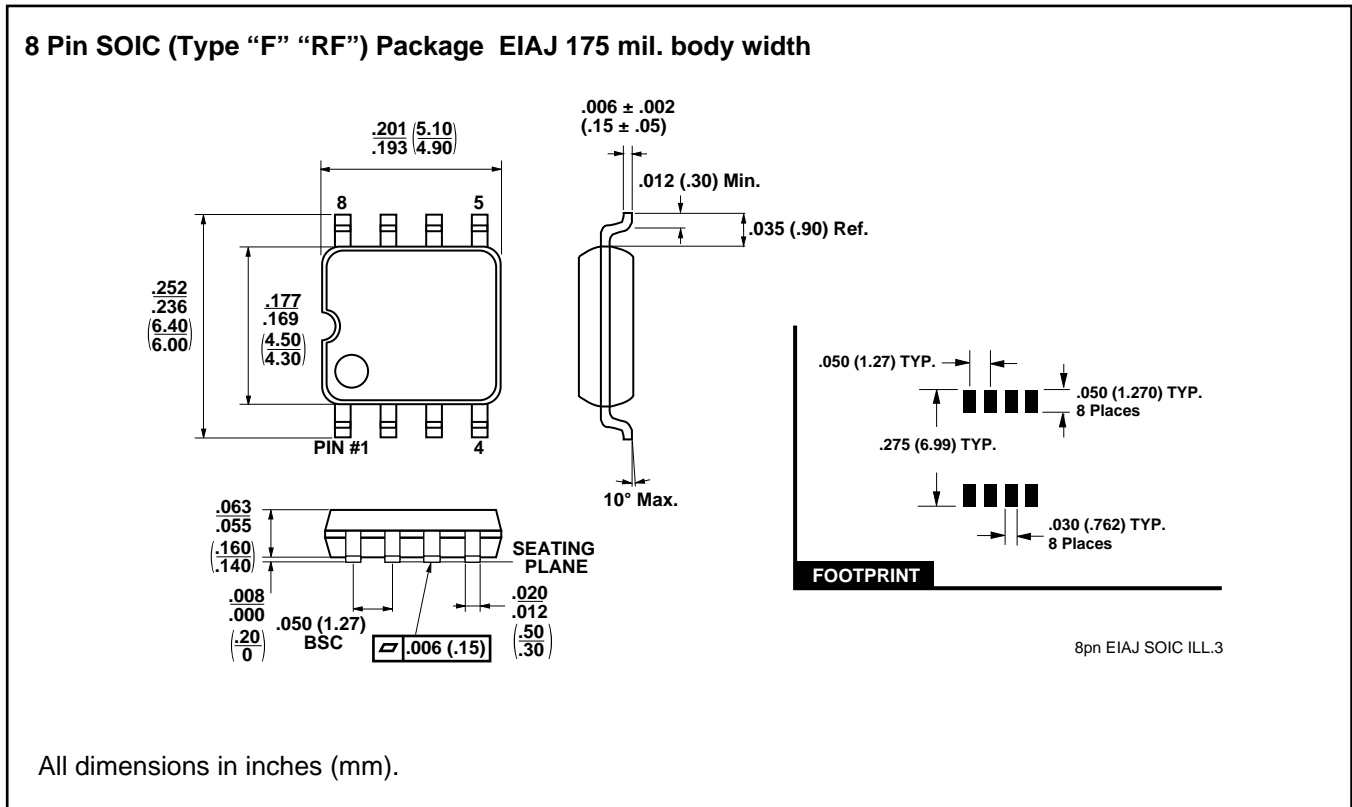
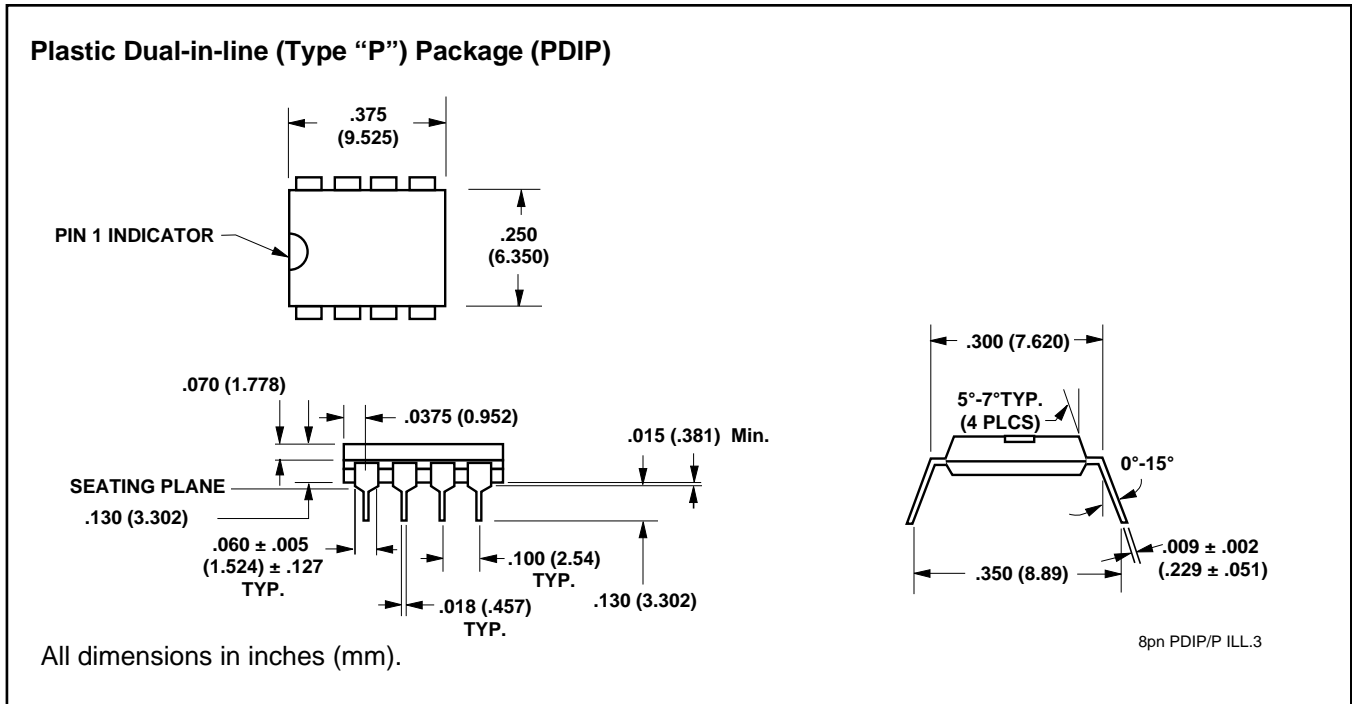


12 volt transmitter

Note: Any simpler transmitter is a subset of the circuit shown.

- Note:**
1. PWM may not be forced to more than 0.4 V from outside, except for communications during programming.
  2. S<sub>2</sub> is used as a clock during programming.

**PACKAGE DIAGRAMS**

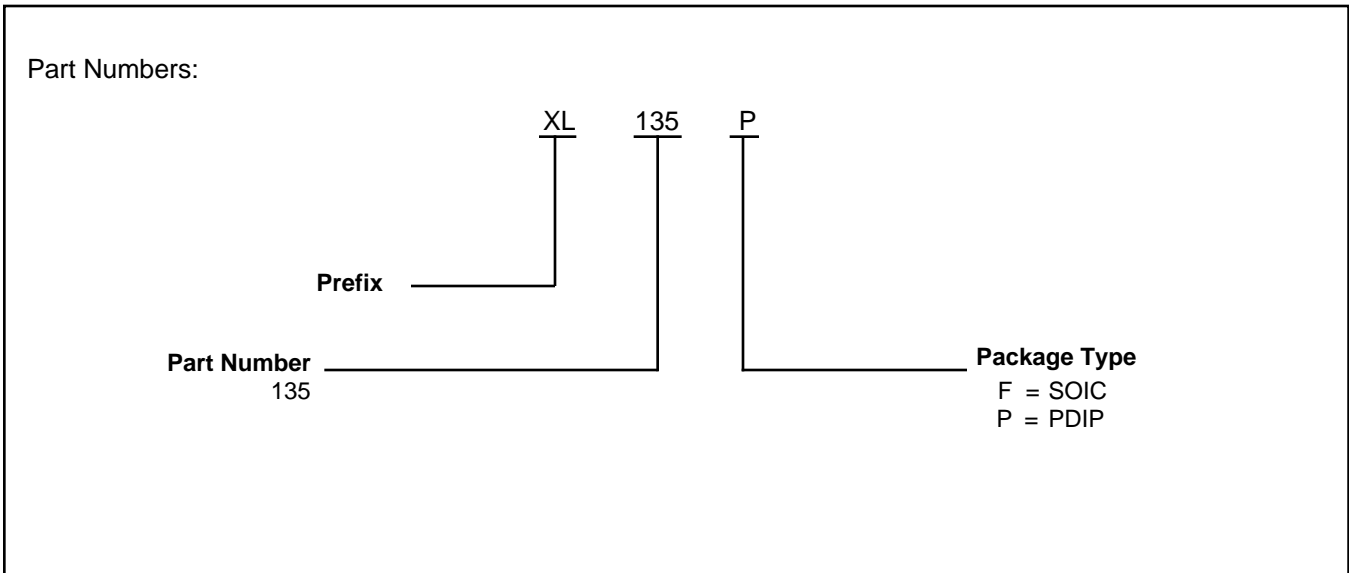


**ORDERING INFORMATION**

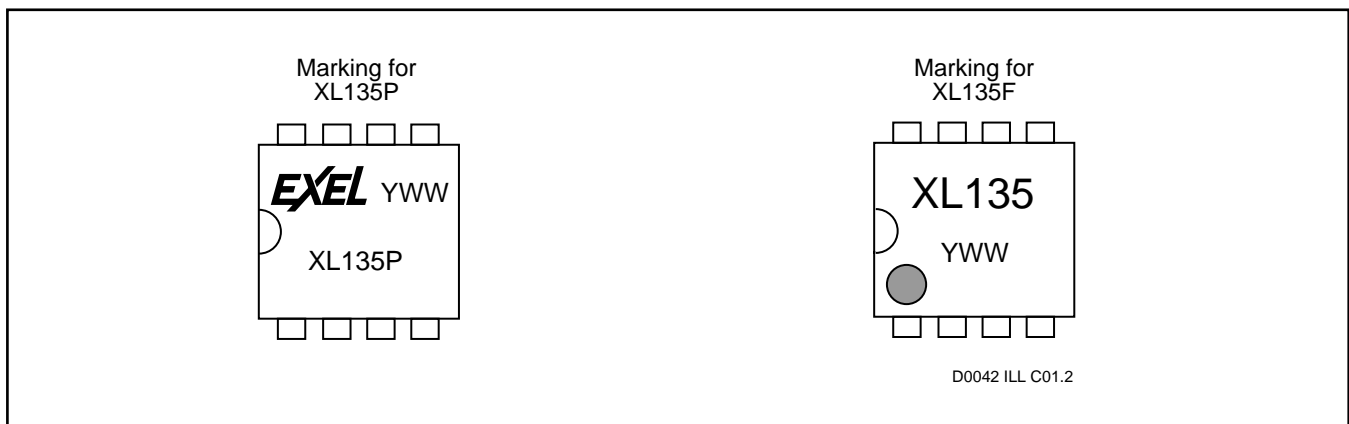
Standard Configurations

Prefix Type	Part Type	Package Type
XL	135	P, F

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**MARKING INFORMATION**

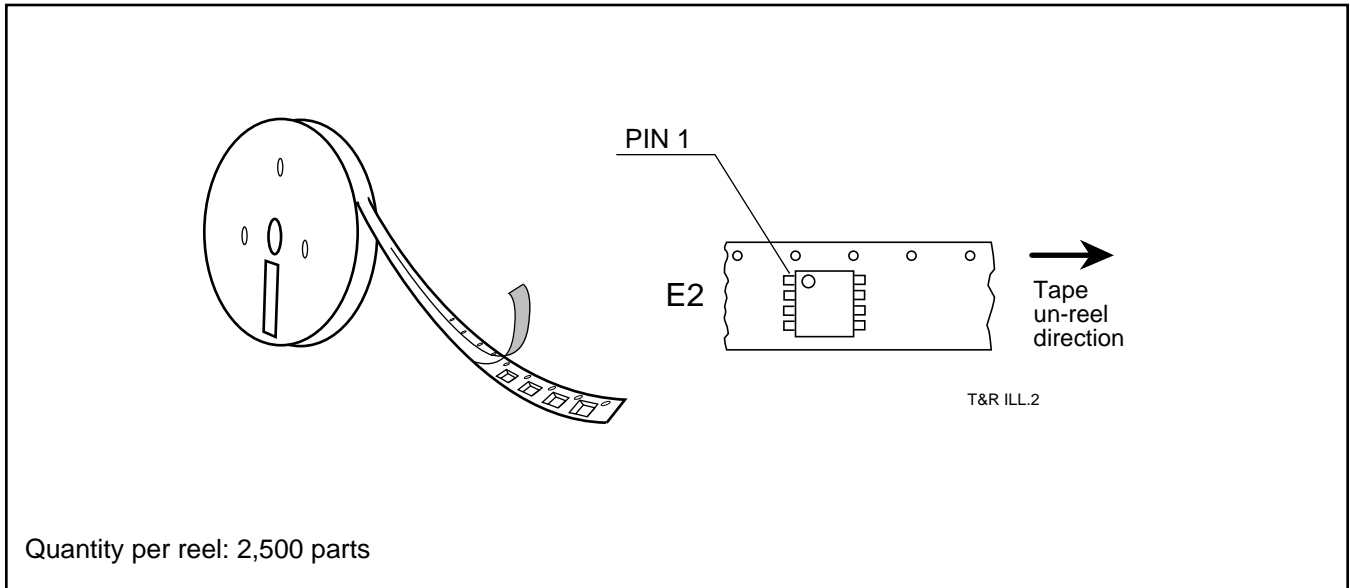




**TAPE AND REEL (EMBOSSED) INFORMATION**

Surface mount devices, which are normally shipped in antistatic plastic tubes, are also available mounted on embossed tape for customers using automatic placement

systems. The following diagram provides general information regarding the direction of the IC's. Tape "E2" shall be designated with PIN 1 at the trail direction.



NOTES:

**NOTES:**

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